## 10-BIT DIGITAL-TO-ANALOG CONVERTERS

## FEATURES

- 10-Bit CMOS Voltage Output DAC in an 8-Terminal Package
- 5V Single Supply Operation
- 3-Wire Serial Interface
- High-Impedance Reference Inputs
- Voltage Output Range: 2 Times the Reference Input Voltage
- Internal Power-On Reset
- Low Power Consumption: 1.75mW Max
- Update Rate of 1.21 MHz
- Settling Time to 0.5LSB: 12.5 $\mu$ s Typ
- Monotonic Over Temperature
- Pin-Compatible With the Maxim MAX515


## APPLICATIONS

- Battery-Powered Test Instruments
- Digital Offset and Gain Adjustment
- Battery Operated/Remote Industrial Controls
- Machine and Motion Control Devices
- Cellular Telephones


## DESCRIPTION

The TLC5615 is a 10-bit voltage output digital-to-analog converter (DAC) with a buffered reference input (high impedance). The DAC has an output voltage range that is two times the reference voltage, and the DAC is monotonic. The device is simple to use, running from a single supply of 5 V . A power-on-reset function is incorporated to ensure repeatable start-up conditions.

Digital control of the TLC5615 is over a three-wire serial bus that is CMOS compatible and easily interfaced to industry standard microprocessor and microcontroller devices. The device receives a 16-bit data word to produce the analog output. The digital inputs feature Schmitt triggers for high noise immunity. Digital communication protocols include the SPI ${ }^{T M}$, QSPI ${ }^{T M}$, and Microwire ${ }^{\text {TM }}$ standards.

The 8-terminal small-outline D package allows digital control of analog functions in space-critical applications. The TLC5615C is characterized for operation from $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$. The TLC5615I is characterized for operation from $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$.


This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

## FUNCTIONAL BLOCK DIAGRAM



Terminal Functions

| NAME |  | NORMINAL | I/O |
| :--- | :---: | :---: | :--- |
| DESCRIPTION |  |  |  |
| DIN | 1 | I | Serial data input |
| SCLK | 2 | I | Serial clock input |
| CS | 3 | I | Chip select, active low |
| DOUT | 4 | O | Serial data output for daisy chaining |
| AGND | 5 |  | Analog ground |
| REFIN | 6 | I | Reference input |
| OUT | 7 | O | DAC analog voltage output |
| V $_{\text {DD }}$ | 8 |  | Positive power supply |

## PACKAGE/ORDERING INFORMATION

For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

## ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range (unless otherwise noted) ${ }^{(1)}$

|  |  | UNIT |
| :---: | :---: | :---: |
| Supply voltage ( $\mathrm{V}_{\mathrm{DD}}$ to AGND) |  | 7 V |
| Digital input voltage range to AGND |  | -0.3 V to $\mathrm{V}_{\mathrm{DD}}+0.3 \mathrm{~V}$ |
| Reference input voltage range to AGND |  | -0.3 V to $\mathrm{V}_{\mathrm{DD}}+0.3 \mathrm{~V}$ |
| Output voltage at OUT from external sour |  | $\mathrm{V}_{\mathrm{DD}}+0.3 \mathrm{~V}$ |
| Continuous current at any terminal |  | $\pm 20 \mathrm{~mA}$ |
| Operating free-air temperature range, $\mathrm{T}_{\mathrm{A}}$ | TLC5615C | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ |
|  | TLC5615I | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| Storage temperature range, $\mathrm{T}_{\text {stg }}$ |  | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Lead temperature $1,6 \mathrm{~mm}$ (1/16 inch) from case for 10 seconds |  | $+260^{\circ} \mathrm{C}$ |

(1) Stresses beyond those listed under Absolute Maximum RatingS may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## RECOMMENDED OPERATING CONDITIONS

|  |  | MIN | NOM | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Supply voltage, $\mathrm{V}_{\mathrm{DD}}$ |  | 4.5 | 5 | 5.5 | V |
| High-level digital input voltage, $\mathrm{V}_{\mathrm{IH}}$ |  | 2.4 |  |  | V |
| Low-level digital input voltage, $\mathrm{V}_{\mathrm{IL}}$ |  |  |  | 0.8 | V |
| Reference voltage, $\mathrm{V}_{\text {ref }}$ to REFIN terminal |  | 2 | 2.048 | $\mathrm{V}_{\mathrm{DD}}-2$ | V |
| Load resistance, $\mathrm{R}_{\mathrm{L}}$ |  | 2 |  |  | k $\Omega$ |
|  | TLC5615C | 0 |  | 70 | ${ }^{\circ} \mathrm{C}$ |
| Operating free-air temperaure, $T_{\text {A }}$ | TLC5615I | 40 |  | 85 | ${ }^{\circ} \mathrm{C}$ |

## ELECTRICAL CHARACTERISTICS

over recommended operating free-air temperature range, $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V} \pm 5 \%, \mathrm{~V}_{\text {ref }}=2.048 \mathrm{~V}$ (unless otherwise noted)

| STATIC DAC SPECIFICATIONS |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| PARAMETER |  |  | TEST CONDITIONS |  | MIN | TYP | MAX | UNIT |
| Resolution |  |  |  |  | 10 |  |  | bits |
| Integral nonlinearity, end point adjusted (INL) |  |  | $\mathrm{V}_{\text {ref }}=2.048 \mathrm{~V}$, | See ${ }^{(1)}$ |  |  | $\pm 1$ | LSB |
| Differential nonlinearity (DNL) |  |  | $\mathrm{V}_{\text {ref }}=2.048 \mathrm{~V}$, | See ${ }^{(2)}$ |  | $\pm 0.1$ | $\pm 0.5$ | LSB |
| $\mathrm{E}_{\text {zS }}$ | Zero-scale error (offset error at zero scale) |  | $\mathrm{V}_{\text {ref }}=2.048 \mathrm{~V}$, | See ${ }^{(3)}$ |  |  | $\pm 3$ | LSB |
|  | Zero-scale-error temperature coefficient |  | $\mathrm{V}_{\text {ref }}=2.048 \mathrm{~V}$, | See ${ }^{(4)}$ |  | 3 |  | ppm $/{ }^{\circ} \mathrm{C}$ |
| $\mathrm{E}_{\mathrm{G}}$ | Gain error |  | $\mathrm{V}_{\text {ref }}=2.048 \mathrm{~V}$, | See ${ }^{(5)}$ |  |  | $\pm 3$ | LSB |
| Gain-error temperature coefficient |  |  | $\mathrm{V}_{\text {ref }}=2.048 \mathrm{~V}$, | See ${ }^{(6)}$ |  | 1 |  | $\mathrm{ppm} /{ }^{\circ} \mathrm{C}$ |
| PSRR | Power-supply rejection ratio | Zero scale | See ${ }^{(7)(8)}$ |  | 80 |  |  | dB |
|  |  | Gain |  |  | 80 |  |  |  |
| Analog full scale output |  |  | $\mathrm{R}_{\mathrm{L}}=100 \mathrm{k} \Omega$ |  | $2 \mathrm{~V}_{\text {ref }}(1023 / 1024)$ |  |  | V |

(1) The relative accuracy or integral nonlinearity (INL), sometimes referred to as linearity error, is the maximum deviation of the output from the line between zero and full scale excluding the effects of zero code and full-scale errors (see text). Tested from code 3 to code 1024.
(2) The differential nonlinearity (DNL), sometimes referred to as differential error, is the difference between the measured and ideal 1LSB amplitude change of any two adjacent codes. Monotonic means the output voltage changes in the same direction (or remains constant) as a change in the digital input code. Tested from code 3 to code 1024.
(3) Zero-scale error is the deviation from zero-voltage output when the digital input code is zero (see text).
(4) Zero-scale-error temperature coefficient is given by: $\mathrm{E}_{Z S} T C=\left[\mathrm{E}_{Z S}\left(T_{\max }\right)-\mathrm{E}_{Z S}\left(T_{\min }\right)\right] / V_{\text {ref }} \times 10^{6} /\left(T_{\max }-T_{\text {min }}\right)$.
(5) Gain error is the deviation from the ideal output ( $\mathrm{V}_{\text {ref }}-1 \mathrm{LSB}$ ) with an output load of $10 \mathrm{k} \Omega$ excluding the effects of the zero-scale error.
(6) Gain temperature coefficient is given by: $\mathrm{E}_{\mathrm{G}} \mathrm{TC}=\left[\mathrm{E}_{\mathrm{G}}\left(\mathrm{T}_{\max }\right)-\mathrm{E}_{\mathrm{G}}\left(\mathrm{T}_{\min }\right)\right] / V_{\text {ref }} \times 10^{6} /\left(\mathrm{T}_{\max }-\mathrm{T}_{\min }\right)$.
(7) Zero-scale-error rejection ratio (EZS-RR) is measured by varying the $V_{D D}$ from 4.5 V to 5.5 V dc and measuring the proportion of this signal imposed on the zero-code output voltage.
(8) Gain-error rejection ratio (EG-RR) is measured by varying the $V_{D D}$ from 4.5 V to 5.5 V dc and measuring the proportion of this signal imposed on the full-scale output voltage after subtracting the zero-scale change.

VOLTAGE OUTPUT (OUT)

| PARAMETER |  | TEST CONDITIONS | MIN | TYP MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{0}$ | Voltage output range | $\mathrm{R}_{\mathrm{L}}=10 \mathrm{k} \Omega$ | 0 | $\mathrm{V}_{\text {DD }}-0.4$ | V |
|  | Output load regulation accuracy | $\mathrm{V}_{\mathrm{O} \text { (OUT) }}=2 \mathrm{~V}, \quad \mathrm{R}_{\mathrm{L}}=2 \mathrm{k} \Omega$ |  | 0.5 | LSB |
| losc | Output short circuit current | OUT to $\mathrm{V}_{\mathrm{DD}}$ or AGND |  | 20 | mA |
| $\mathrm{V}_{\text {OL(low) }}$ | Output voltage, low-level | $\mathrm{I}_{\text {(OUT) }} \leq 5 \mathrm{~mA}$ |  | 0.25 | V |
| $\mathrm{V}_{\mathrm{OH} \text { (high) }}$ | Output voltage, high-level | $\mathrm{l}_{\mathrm{O}(\mathrm{OUT})} \leq-5 \mathrm{~mA}$ | 4.75 |  | V |

REFERENCE INPUT (REFIN)

| $\mathrm{V}_{1}$ | Input voltage |  | 0 | $\mathrm{~V}_{\mathrm{DD}}-2$ |
| :--- | :--- | ---: | :---: | :---: |
| $\mathrm{r}_{\mathrm{i}}$ | Input resistance |  | 10 | V |
| $\mathrm{C}_{\mathrm{i}}$ | Input capacitance |  | 5 | $\mathrm{M} \Omega$ |

DIGITAL INPUTS (DIN, SCLK, CS)

| $\mathrm{V}_{\mathrm{IH}}$ | High-level digital input voltage |  | 2.4 | V |
| :--- | :--- | :--- | :--- | :---: |
| $\mathrm{~V}_{\mathrm{IL}}$ | Low-level digital input voltage |  | 0.8 | V |
| $\mathrm{I}_{\mathrm{H}}$ | High-level digital input current | $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{DD}}$ |  | $\pm 1$ |
| $\mathrm{I}_{\mathrm{IL}}$ | Low-level digital input current | $\mathrm{V}_{\mathrm{I}}=0$ | $\mu \mathrm{~A}$ |  |
| $\mathrm{C}_{\mathrm{i}}$ | Input capacitance |  | 8 A |  |

DIGITAL OUTPUT (DOUT)

| $\mathrm{V}_{\mathrm{OH}}$ | Output voltage, high-level | $\mathrm{I}_{0}=-2 \mathrm{~mA}$ |  | $\mathrm{V}_{\mathrm{DD}}$-1 |  |  | V |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {OL }}$ | Output voltage, low-level | $\mathrm{I}_{\mathrm{O}}=2 \mathrm{~mA}$ |  |  |  | 0.4 | V |
| POWER SUPPLY |  |  |  |  |  |  |  |
| $\mathrm{V}_{\mathrm{DD}}$ | Supply voltage |  |  | 4.5 | 5 | 5.5 | V |
| $\mathrm{I}_{\mathrm{DD}}$ | Power supply current | $\mathrm{V}_{\mathrm{DD}}=5.5 \mathrm{~V}$, No load, All inputs $=0 \mathrm{~V}$ or $\mathrm{V}_{\mathrm{DD}}$ | $\mathrm{V}_{\text {ref }}=0$ |  | 150 | 250 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{DD}}=5.5 \mathrm{~V}$, No load, All inputs $=0 \mathrm{~V}$ or $\mathrm{V}_{\mathrm{DD}}$ | $\mathrm{V}_{\text {ref }}=2.048 \mathrm{~V}$ |  | 230 | 350 | $\mu \mathrm{A}$ |

ANALOG OUTPUT DYNAMIC PERFORMANCE
Signal-to-noise + distortion, S/(N+D) $\begin{aligned} & \mathrm{V}_{\text {ref }}=1 \mathrm{~V}_{\mathrm{PP}} \text { at } 1 \mathrm{kHz}+2.048 \mathrm{Vdc}, \\ & \mathrm{code}=1111111111(1)\end{aligned}$
60
dB
(1) The limiting frequency value at $1 \mathrm{~V}_{\mathrm{PP}}$ is determined by the output-amplifier slew rate.

DIGITAL INPUT TIMING REQUIREMENTS (See Figure 1)

|  | PARAMETER | MIN | NOM |
| :--- | :--- | ---: | :---: |
|  | MAX | UNIT |  |
| $\mathrm{t}_{\mathrm{su}(\mathrm{DS})}$ | Setup time, DIN before SCLK high | 45 | ns |
| $\mathrm{t}_{\mathrm{h}(\mathrm{DH})}$ | Hold time, DIN valid after SCLK high | 0 | ns |
| $\mathrm{t}_{\mathrm{su}(\mathrm{CSS})}$ | Setup time, $\overline{\mathrm{CS}}$ low to SCLK high | 1 | ns |
| $\mathrm{t}_{\mathrm{su}(\mathrm{CS} 1)}$ | Setup time, $\overline{\text { CS }}$ high to SCLK high | 50 | ns |
| $\mathrm{t}_{\mathrm{h}(\mathrm{CSH})}$ | Hold time, SCLK low to $\overline{\text { CS low }}$ | 1 | ns |
| $\mathrm{t}_{\mathrm{h}(\mathrm{CSH} 1)}$ | Hold time, SCLK low to CS high | 0 | ns |
| $\mathrm{t}_{\mathrm{w}(\mathrm{CS})}$ | Pulse duration, minimum chip select pulse width high | 20 | ns |
| $\mathrm{t}_{\mathrm{w}(\mathrm{CL})}$ | Pulse duration, SCLK low | 25 | ns |
| $\mathrm{t}_{\mathrm{w}(\mathrm{CH})}$ | Pulse duration, SCLK high | 25 | ns |

## OUTPUT SWITCHING CHARACTERISTICS

| PARAMETER | TEST CONDITIONS | MIN NOM | MAX | UNIT |
| :---: | :--- | :---: | :---: | :---: |
| $\mathrm{t}_{\text {pd(DOUT) }}$ | Propagation delay time, DOUT | $\mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}$ |  | 50 |

## OPERATING CHARACTERISTICS

over recommended operating free-air temperature range, $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V} \pm 5 \%, \mathrm{~V}_{\text {ref }}=2.048 \mathrm{~V}$ (unless otherwise noted)

| PARAMETER | TEST CONDITIONS | MIN TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: |
| ANALOG OUTPUT DYNAMIC PERFORMANCE |  |  |  |  |
| SR Output slew rate | $\begin{array}{ll} \hline \mathrm{C}_{\mathrm{L}}=100 \mathrm{pF}, & \mathrm{R}_{\mathrm{L}}=10 \mathrm{k} \Omega, \\ \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}, \end{array}$ | 0.30 .5 |  | V/us |
| $\mathrm{t}_{\text {s }} \quad$ Output settling time | $\begin{array}{ll}\text { To 0.5LSB, } \\ \mathrm{R}_{\mathrm{L}}=10 \mathrm{k} \Omega, & \mathrm{C}_{\mathrm{L}}=100 \mathrm{pF},{ }^{\text {(1) }}\end{array}$ | 12.5 |  | $\mu \mathrm{S}$ |
| Glitch energy | DIN = All 0s to all 1s | 5 |  | nV -s |
| REFERENCE INPUT (REFIN) |  |  |  |  |
| Reference feedthrough | REFIN $=1 \mathrm{~V}_{\text {PP }}$ at $1 \mathrm{kHz}+2.048 \mathrm{Vdc}{ }^{(2)}$ | -80 |  | dB |
| Reference input bandwidth ( $\mathrm{f}-3 \mathrm{~dB}$ ) | REFIN $=0.2 \mathrm{~V}_{\text {PP }}+2.048 \mathrm{Vdc}$ | 30 |  | kHz |

(1) Settling time is the time for the output signal to remain within $\pm 0.5 \mathrm{LSB}$ of the final measured value for a digital input code change of 000 hex to $3 F F$ hex or $3 F F$ hex to 000 hex.
(2) Reference feedthrough is measured at the DAC output with an input code $=000$ hex and a $\mathrm{V}_{\text {ref }}$ input $=2.048 \mathrm{Vdc}+1 \mathrm{~V}_{\mathrm{pp}}$ at 1 kHz .

## PARAMETER MEASUREMENT INFORMATION


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Figure 1. Timing Diagram

TYPICAL CHARACTERISTICS


Figure 2.
SUPPLY CURRENT
TEMPERATURE


OA - O2.
91utcisqFine - -

Figure 4.


Figure 3.
$\mathrm{V}_{\text {REFIN }}$ TO $\mathrm{V}_{\text {(OUT) }}$ RELATIVE GAIN
INPUT FREQUENCY


Figure 5.

TYPICAL CHARACTERISTICS (continued)


Figure 6.


Figure 7. Differential Nonlinearity With Input Code


Figure 8. Integral Nonlinearity With Input Code

## APPLICATION INFORMATION

## GENERAL FUNCTION

The TLC5615 uses a resistor string network buffered with an op amp in a fixed gain of 2 to convert 10－bit digital data to analog voltage levels（see functional block diagram and Figure 9）．The output of the TLC5615 is the same polarity as the reference input（see Table 1）．
An internal circuit resets the DAC register to all zeros on power up．


Figure 9．TLC5615 Typical Operating Circuit
Table 1．Binary Code Table（ 0 V to $2 \mathrm{~V}_{\text {Refin }}$ Output），Gain $=2$

| INPUT ${ }^{(1)}$ |  |  | OUTPUT |  |
| :---: | :---: | :---: | :---: | :---: |
| 1111 | 1111 | 11（00） |  | espr asor－＿ |
|  | ： |  |  | ： |
| 1000 | 0000 | 01（00） |  | $\begin{aligned} & \text { gra } \\ & \text { Asor } \end{aligned}$ |
| 1000 | 0000 | 00（00） | 㴆 | ス｜コヨ゙ャ |
| 0111 | 1111 | 11（00） |  | $\begin{aligned} & \text { ryc } \\ & \text { Asor } \end{aligned}$ |
|  | ： |  |  | ： |
| 0000 | 0000 | 01（00） |  | asbr |
| 0000 | 0000 | 00（00） |  | 0 V |

（1）A 10－bit data word with two bits below the LSB bit（sub－LSB）with 0 values must be written since the DAC input latch is 12 bits wide．

## BUFFER AMPLIFIER

The output buffer has a rail-to-rail output with short circuit protection and can drive a $2 \mathrm{k} \Omega$ load with a 100 pF load capacitance. Settling time is $12.5 \mu \mathrm{~s}$ typical to within 0.5 LSB of final value.

## EXTERNAL REFERENCE

The reference voltage input is buffered, which makes the DAC input resistance not code dependent. Therefore, the REFIN input resistance is $10 \mathrm{M} \Omega$ and the REFIN input capacitance is typically 5 pF independent of input code. The reference voltage determines the DAC full-scale output.

## LOGIC INTERFACE

The logic inputs function with either TTL or CMOS logic levels. However, using rail-to-rail CMOS logic achieves the lowest power dissipation. The power requirement increases by approximately 2 times when using TTL logic levels.

## SERIAL CLOCK AND UPDATE RATE

Figure 1 shows the TLC5615 timing. The maximum serial clock rate is:

or approximately 14 MHz . The digital update rate is limited by the chip-select period, which is:

$$
1 \quad=\partial r \times) \stackrel{\downarrow}{\dagger}+1 P(\underset{W D P}{\dagger}(+\underset{\text { WQP }}{\dagger}
$$

and is equal to 820 ns which is a 1.21 MHz update rate. However, the DAC settling time to 10 bits of $12.5 \mu \mathrm{~s}$ limits the update rate to 80 kHz for full-scale input step transitions.

## SERIAL INTERFACE

When chip select ( $\overline{\mathrm{CS}}$ ) is low, the input data is read into a 16 -bit shift register with the input data clocked in most significant bit first. The rising edge of the SLCK input shifts the data into the input register.
The rising edge of $\overline{C S}$ then transfers the data to the DAC register. When $\overline{C S}$ is high, input data cannot be clocked into the input register. All $\overline{\text { CS }}$ transitions should occur when the SCLK input is low.
If the daisy chain (cascading) function (see daisy-chaining devices section) is not used, a 12-bit input data sequence with the MSB first can be used as shown in Figure 10:


Figure 10. 12-Bit Input Data Sequence
or 16 bits of data can be transferred as shown in Figure 11 with the 4 upper dummy bits first.


Figure 11. 16-Bit Input Data Sequence

The data from DOUT requires 16 falling edges of the input clock and, therefore, requires an extra clock width. When daisy chaining multiple TLC5615 devices, the data requires 4 upper dummy bits because the data transfer requires 16 input-clock cycles plus one additional input-clock falling edge to clock out the data at the DOUT terminal (see Figure 1).

The two extra (sub-LSB) bits are always required to provide hardware and software compatibility with 12-bit data converter transfers.

The TLC5615 three-wire interface is compatible with the SPI, QSPI, and Microwire serial standards. The hardware connections are shown in Figure 12 and Figure 13.

The SPI and Microwire interfaces transfer data in 8-bit bytes; therefore, two write cycles are required to input data to the DAC. The QSPI interface, which has a variable input data length from 8 to 16 bits, can load the DAC input register in one write cycle.


NOTE A: The DOUT-SI connection is not required for writing to the TLC5615 but may be used for verifying data transfer if desired.

Figure 12. Microwire Connection


NOTE A: The DOUT-MISO connection is not required for writing to the TLC5615 but may be used for verifying data transfer.

Figure 13. SPI/QSPI Connection

## DAISY-CHAINING DEVICES

DACs can be daisy-chained by connecting the DOUT terminal of one device to the DIN of the next device in the chain, providing that the setup time, $\mathrm{t}_{\text {su(CSS) }}(\overline{\mathrm{CS}}$ low to SCLK high), is greater than the sum of the setup time, $\mathrm{t}_{\text {su(DS) }}$, plus the propagation delay time, $\mathrm{t}_{\mathrm{pd}(\mathrm{DOUT})}$, for proper timing (see digital input timing requirements section). The data at DIN appears at DOUT, delayed by 16 clock cycles plus one clock width. DOUT is a totem-poled output for low power. DOUT changes on the SCLK falling edge when $\overline{\mathrm{CS}}$ is low. When $\overline{\mathrm{CS}}$ is high, DOUT remains at the value of the last data bit and does not go into a high-impedance state.

## LINEARITY, OFFSET, AND GAIN ERROR USING SINGLE-ENDED SUPPLIES

When an amplifier is operated from a single supply, the voltage offset can still be either positive or negative. With a positive offset, the output voltage changes on the first code change. With a negative offset the output voltage may not change with the first code depending on the magnitude of the offset voltage.

The output amplifier attempts to drive the output to a negative voltage. However, because the most negative supply rail is ground, the output cannot drive below ground and clamps the output at 0 V .
The output voltage then remains at zero until the input code value produces a sufficient positive output voltage to overcome the negative offset voltage, resulting in the transfer function shown in Figure 14.


Figure 14. Effect of Negative Offset (Single Supply)
This offset error, not the linearity error, produces this breakpoint. The transfer function would have followed the dotted line if the output buffer could drive below the ground rail.

For a DAC, linearity is measured between zero-input code (all inputs ' 0 ') and full-scale code (all inputs ' 1 ') after offset and full scale are adjusted out or accounted for in some way. However, single supply operation does not allow for adjustment when the offset is negative due to the breakpoint in the transfer function. So the linearity is measured between full-scale code and the lowest code that produces a positive output voltage. For the TLC5615, the zero-scale (offset) error is $\pm 3 L S B$ maximum. The code is calculated from the maximum specification for the negative offset.

## POWER-SUPPLY BYPASSING AND GROUND MANAGEMENT

Printed circuit boards that use separate analog and digital ground planes offer the best system performance. Wire-wrap boards do not perform well and should not be used. The two ground planes should be connected together at the low-impedance power-supply source. The best ground connection may be achieved by connecting the DAC AGND terminal to the system analog ground plane making sure that analog ground currents are well managed and there are negligible voltage drops across the ground plane.

A $0.1 \mu \mathrm{~F}$ ceramic-capacitor bypass should be connected between $\mathrm{V}_{\mathrm{DD}}$ and AGND and mounted with short leads as close as possible to the device. Use of ferrite beads may further isolate the system analog supply from the digital power supply.
Figure 15 shows the ground plane layout and bypassing technique.


Figure 15. Power-Supply Bypassing

## SAVING POWER

Setting the DAC register to all 0s minimizes power consumption by the reference resistor array and the output load when the system is not using the DAC.

## AC CONSIDERATIONS

## Digital Feedthrough

Even with $\overline{\mathrm{CS}}$ high, high-speed serial data at any of the digital input or output terminals may couple through the DAC package internal stray capacitance and appear at the DAC analog output as digital feedthrough. Digital feedthrough is tested by holding CS high and transmitting 0101010101 from DIN to DOUT.

## Analog Feedthrough

Higher frequency analog input signals may couple to the output through internal stray capacitance. Analog feedthrough is tested by holding $\overline{C S}$ high, setting the DAC code to all 0 s, sweeping the frequency applied to REFIN, and monitoring the DAC output.

## Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

## Changes from D Revision (August 2003) to E Revision

Page

- Added ESD statement
.................................................................................................................................................. 2
- Changed —moved package option table from front page............................................................................................... 2


## PACKAGING INFORMATION

| Orderable Device | Status ${ }^{(1)}$ | Package Type | Package Drawing |  | Package Qty | $\text { e Eco Plan }{ }^{(2)}$ | Lead/Ball Finish | MSL Peak Temp ${ }^{(3)}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TLC5615CD | ACTIVE | SOIC | D | 8 | 75 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| TLC5615CDG4 | ACTIVE | SOIC | D | 8 | 75 | $\begin{gathered} \text { Green (RoHS \& } \\ \text { no Sb/Br) } \end{gathered}$ | CU NIPDAU | Level-1-260C-UNLIM |
| TLC5615CDGK | ACTIVE | MSOP | DGK | 8 | 80 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| TLC5615CDGKG4 | ACTIVE | MSOP | DGK | 8 | 80 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| TLC5615CDGKR | ACTIVE | MSOP | DGK | 8 | 2500 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| TLC5615CDGKRG4 | ACTIVE | MSOP | DGK | 8 | 2500 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| TLC5615CDR | ACTIVE | SOIC | D | 8 | 2500 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| TLC5615CDRG4 | ACTIVE | SOIC | D | 8 | 2500 | $\begin{gathered} \text { Green (RoHS \& } \\ \text { no Sb/Br) } \\ \hline \end{gathered}$ | CU NIPDAU | Level-1-260C-UNLIM |
| TLC5615CP | ACTIVE | PDIP | P | 8 | 50 | Pb-Free (RoHS) | CU NIPDAU | N/A for Pkg Type |
| TLC5615CPE4 | ACTIVE | PDIP | P | 8 | 50 | Pb-Free (RoHS) | CU NIPDAU | N/ A for Pkg Type |
| TLC5615ID | ACTIVE | SOIC | D | 8 | 75 | $\begin{gathered} \hline \text { Green (RoHS \& } \\ \text { no Sb/Br) } \\ \hline \end{gathered}$ | CU NIPDAU | Level-1-260C-UNLIM |
| TLC5615IDG4 | ACTIVE | SOIC | D | 8 | 75 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| TLC5615IDGK | ACTIVE | MSOP | DGK | 8 | 80 | Green (RoHS \& no $\mathrm{Sb} / \mathrm{Br}$ ) | CU NIPDAU | Level-1-260C-UNLIM |
| TLC5615IDGKG4 | ACTIVE | MSOP | DGK | 8 | 80 | $\begin{gathered} \text { Green (RoHS \& } \\ \text { no Sb/Br) } \\ \hline \end{gathered}$ | CU NIPDAU | Level-1-260C-UNLIM |
| TLC5615IDR | ACTIVE | SOIC | D | 8 | 2500 | $\begin{gathered} \text { Green (RoHS \& } \\ \text { no Sb/Br) } \\ \hline \end{gathered}$ | CU NIPDAU | Level-1-260C-UNLIM |
| TLC5615IDRG4 | ACTIVE | SOIC | D | 8 | 2500 | $\begin{gathered} \text { Green (RoHS \& } \\ \text { no Sb/Br) } \\ \hline \end{gathered}$ | CU NIPDAU | Level-1-260C-UNLIM |
| TLC5615IP | ACTIVE | PDIP | P | 8 | 50 | Pb -Free (RoHS) | CU NIPDAU | N/ A for Pkg Type |
| TLC5615IPE4 | ACTIVE | PDIP | P | 8 | 50 | Pb-Free (RoHS) | CU NIPDAU | N/A for Pkg Type |

${ }^{(1)}$ The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but Tl does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.
${ }^{(2)}$ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS \& no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.
TBD: The Pb-Free/Green conversion plan has not been defined.
Pb -Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed $0.1 \%$ by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb -Free products are suitable for use in specified lead-free processes.
Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and
package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb -Free (RoHS compatible) as defined above.
Green ( RoHS \& no $\mathbf{S b} / \mathrm{Br}$ ): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine ( Br ) and Antimony ( Sb ) based flame retardants ( Br or Sb do not exceed $0.1 \%$ by weight in homogeneous material)
${ }^{(3)}$ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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## TAPE AND REEL INFORMATION



QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

*All dimensions are nominal

| Device | Package <br> Type | Package <br> Drawing | Pins | SPQ | Reel <br> Diameter <br> $(\mathbf{m m})$ | Reel <br> Width <br> W1 $(\mathbf{m m})$ | A0 (mm) | B0 (mm) | K0 (mm) | P1 <br> $(\mathbf{m m})$ | W <br> $(\mathbf{m m})$ | Pin1 <br> Quadrant |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TLC5615CDGKR | MSOP | DGK | 8 | 2500 | 330.0 | 12.4 | 5.3 | 3.4 | 1.4 | 8.0 | 12.0 | Q1 |
| TLC5615CDR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |
| TLC5615CDR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |
| TLC5615IDR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |
| TLC5615IDR | SOIC | D | 8 | 2500 | 330.0 | 12.4 | 6.4 | 5.2 | 2.1 | 8.0 | 12.0 | Q1 |


*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TLC5615CDGKR | MSOP | DGK | 8 | 2500 | 346.0 | 346.0 | 29.0 |
| TLC5615CDR | SOIC | D | 8 | 2500 | 346.0 | 346.0 | 29.0 |
| TLC5615CDR | SOIC | D | 8 | 2500 | 340.5 | 338.1 | 20.6 |
| TLC5615IDR | SOIC | D | 8 | 2500 | 340.5 | 338.1 | 20.6 |
| TLC5615IDR | SOIC | D | 8 | 2500 | 346.0 | 346.0 | 29.0 |

$P(R-P D I P-T 8)$
PLASTIC DUAL-IN-LINE PACKAGE


NOTES: A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. Falls within JEDEC MS-001 variation BA.


NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.

C Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 per end.
D Body width does not include interlead flash. Interlead flash shall not exceed 0.50 per side.
E. Falls within JEDEC MO-187 variation AA, except interlead flash.

D (R-PDSO-G8)
PLASTIC SMALL-OUTLINE PACKAGE


4040047-3/J 09/09
NOTES: A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.

C Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed $.006(0,15)$ per end.
D Body width does not include interlead flash. Interlead flash shall not exceed $.017(0,43)$ per side.
E. Reference JEDEC MS-012 variation AA.

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