

Professional *Extended-10*™ Video Encoder with 54 MHz Oversampling

ADV7194*

FEATURES

10-Bit Extended CCIR-656 Input Data Port Six High-Quality 10-Bit Video DACs 10-Bit Internal Digital Video Processing Multistandard Video Input Multistandard Video Output

 $4\times$ Oversampling with Internal 54 MHz PLL

Programmable Video Control Includes:

Digital Noise Reduction

Gamma Correction

Black Burst

LUMA Delay

CHROMA Delay

Multiple Luma and Chroma Filters

Luma SSAF™ (Super Sub-Alias Filter)

Average Brightness Detection

Field Counter

CGMS (Copy Generation Management System)

WSS (Wide Screen Signaling)

Closed Captioning Support

Teletext Insertion Port (PAL-WST)

2-Wire Serial MPU Interface (I²C Compatible and Fast I²C)

Supply Voltage 5 V and 3.3 V Operation 80-Lead LQFP Package

APPLICATIONS

Professional DVD Playback Systems PC Video/Multimedia Playback Systems Progressive Scan Playback Systems Professional Studio Equipment

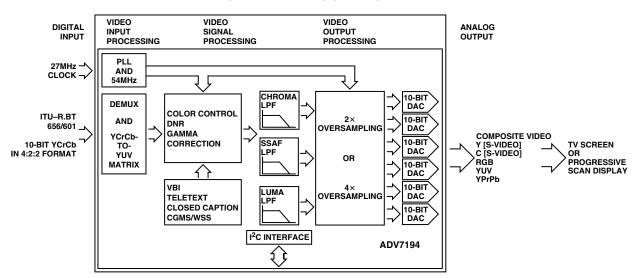
GENERAL DESCRIPTION

The ADV7194 is part of the new generation of video encoders from Analog Devices. The device builds on the performance of previous video encoders and provides new features like interfacing progressive scan devices, digital noise reduction, gamma correction, 4× oversampling and 54 MHz operation, average brightness detection, black burst signal generation, chroma delay, an additional Chroma Filter, etc.

The ADV7194 supports NTSC-M, NTSC-N (Japan), PAL N, PAL-B/D/G/H/I and PAL-60 standards. Input standards supported include ITU-R.BT656 4:2:2 YCrCb in 8-, 10-, 16- or 20-bit format and 3× 10-bit YCrCb progressive scan format. The ADV7194 can output composite video (CVBS), S-Video (Y/C), Component YUV or RGB and analog progressive scan in YPrPb format. The analog component output is also compatible with Betacam, MII and SMPTE/EBU N10 levels, SMPTE 170M NTSC and ITU-R.BT 470 PAL.

For more information about the ADV7194's features refer to Detailed Description of Features section.

SIMPLIFIED BLOCK DIAGRAM



^{*}This device is protected by U.S. Patent Numbers 4631603, 4577216, and 4819098 and other intellectual property rights.

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ITU-R and CCIR are used interchangeably in this document (ITU-R has replaced CCIR recommendations). I²C is a registered trademark of Philips Corporation.

RFV. A

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SPECIFICATIONS

5 V SPECIFICATIONS¹ ($V_{AA} = 5 \text{ V}, V_{REF} = 1.235 \text{ V}, R_{SET1,2} = 1200 \Omega$ unless otherwise noted. All specifications T_{MIN} to T_{MAX}^2 unless otherwise noted.)

Parameter	Min	Typ	Max	Unit	Test Conditions
STATIC PERFORMANCE Resolution (Each DAC) Accuracy (Each DAC)			10	Bits	
Integral Nonlinearity ³ Differential Nonlinearity ³			$\pm 1.0 \\ \pm 1.0$	LSB LSB	Guaranteed Monotonic
DIGITAL INPUTS Input High Voltage, V _{INH} Input Low Voltage, V _{INL} Input Current, I _{IN}	2	0	0.8 ±1	V V	V = 0.4 V or 2.4 V
Input Current, I _{IN} Input Capacitance, C _{IN} Input Leakage Current ⁴ Input Leakage Current ⁵		0 6 1 200	10	μΑ pF μΑ μΑ	$V_{IN} = 0.4 \text{ V or } 2.4 \text{ V}$
DIGITAL OUTPUTS Output High Voltage, V _{OH} Output Low Voltage, V _{OL} Three-State Leakage Current ⁶ Three-State Leakage Current ⁷	2.4	0.8 10 200 6	0.4	V V μΑ μΑ	$I_{SOURCE} = 400 \mu A$ $I_{SINK} = 3.2 \text{ mA}$
Three-State Output Capacitance ANALOG OUTPUTS		0	10	pF	
Output Current (Max) Output Current (Min)	4.125	4.33 2.16	4.625	mA mA	$R_L = 300 \Omega$ $R_L = 600 \Omega$, $R_{SET1,2} = 2400 \Omega$
DAC-to-DAC Matching ³ Output Compliance, V _{OC} Output Impedance, R _{OUT}	0	0.4	2.5 1.4	% V kΩ	
Output Capacitance, C _{OUT}		6		pF	$I_{OUT} = 0 \text{ mA}$
VOLTAGE REFERENCE ⁸ Reference Range, V _{REF}	1.112	1.235	1.359	V	
POWER REQUIREMENTS V _{AA} Normal Power Mode	4.75	5.0	5.25	V	
I_{DAC}^{9} I_{CCT} (2× Oversampling) ^{10, 11}		29 80	35 120	mA mA	
I_{CCT} (4× Oversampling) ^{10, 11} I_{PLL} Sleep Mode		120 6	170 10	mA mA	
I _{DAC} I _{CCT}		0.01 85		μ Α μ Α	

Specifications subject to change without notice.

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 $^{^1}$ All measurements are made in 4× Oversampling Mode unless otherwise specified. 2 Temperature range T_{MIN} to T_{MAX} : 0°C to 70°C.

³Guaranteed by characterization.

⁴For all inputs but PAL_NTSC and ALSB.

⁵For PAL_NTSC and ALSB inputs.

⁶For all outputs but VSO/TTX/CLAMP.

⁷For VSO/TTX/CLAMP outputs.

⁸Measurement made in 2× Oversampling Mode.

 $^{^9}I_{DAC}$ is the total current required to supply all DACs including the V_{REF} circuitry.

 $^{^{11}}I_{CCT}$ or the circuit current, is the continuous current required to drive the digital core without I_{PLL} .

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3.3 V SPECIFICATIONS ($V_{AA} = 3.0 \text{ V}, V_{REF} = 1.235 \text{ V}, R_{SET1,2} = 1200 \Omega$ unless otherwise noted. All specifications T_{MIN} to T_{MAX}^2 unless otherwise noted.)

Parameter	Min	Тур	Max	Unit	Test Conditions
STATIC PERFORMANCE Resolution (Each DAC) Accuracy (Each DAC)			10	Bits	
Integral Nonlinearity Differential Nonlinearity			$\pm 1.0 \\ \pm 1.0$	LSB LSB	Guaranteed Monotonic
DIGITAL INPUTS Input High Voltage, V _{INH} Input Low Voltage, V _{INL} Input Current, I _{IN} Input Capacitance, C _{IN} Input Leakage Current ³ Input Leakage Current ⁴		2 0.8 6 1 200	±1 10	V V μA pF μA μA	V _{IN} = 0.4 V or 2.4 V
DIGITAL OUTPUTS Output High Voltage, V _{OH} Output Low Voltage, V _{OL} Three-State Leakage Current ⁵ Three-State Leakage Current ⁶ Three-State Output Capacitance		2.4 0.4 10 200 6	10	V V μΑ μΑ pF	$I_{SOURCE} = 400 \mu A$ $I_{SINK} = 3.2 \text{ mA}$
ANALOG OUTPUTS Output Current (Max) Output Current (Min) DAC-to-DAC Matching Output Compliance, V _{OC} Output Impedance, R _{OUT} Output Capacitance, C _{OUT}	4.125	4.33 2.16 0.4 100 6	4.625 2.5 1.4	mA mA % V kΩ pF	$R_{L} = 300 \ \Omega$ $R_{L} = 600 \ \Omega$, $R_{SET1,2} = 2400 \ \Omega$ $I_{OUT} = 0 \ mA$
VOLTAGE REFERENCE Reference Range ⁷		1.235		v	-
POWER REQUIREMENTS V _{AA} Normal Power Mode	3.15	3.3	3.6	V	
$I_{ m DAC}^{8}$ $I_{ m CCT}$ (2× Oversampling) ^{9, 10} $I_{ m CCT}$ (4× Oversampling) ^{9, 10} $I_{ m PLL}$		29 42 68 6	54 86	mA mA mA mA	
Sleep Mode I_{DAC} I_{CCT}		0.01 85		μ Α μ Α	

NOTES

Specifications subject to change without notice.

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¹All measurements are made in 4× Oversampling Mode unless otherwise specified and are guaranteed by characterization. For 2× Oversampling Mode, the power requirements for the ADV7194 are typically 3.0 V.

²Temperature range T_{MIN} to T_{MAX} : 0°C to 70°C.

³For all inputs but PAL_NTSC and ALSB.

⁴For PAL_NTSC and ALSB inputs.

 $^{^5}$ For all outputs but $\overline{VSO}/TTX/CLAMP$.

 $^{^6}$ For $\overline{\text{VSO}}/\text{TTX}/\text{CLAMP}$ outputs.

 $^{^7}$ Measurement made in $2 \times$ Oversampling Mode.

 $^{^8}I_{DAC}$ is the total current required to supply all DACs including the V_{REF} circuitry.

⁹All six DACs on.

 $^{^{10}}I_{CCT}$ or the circuit current, is the continuous current required to drive the digital core without I_{PLL} .

5 V DYNAMIC SPECIFICATIONS¹

(V_{AA} = 5 V \pm 250 mV, V_{REF} = 1.235 V, R_{SET1,2} = 1200 Ω unless otherwise noted. All specifications T_{MIN} to T_{MAX}² unless otherwise noted.)

Parameter	Min	Typ	Max	Unit	Test Conditions
Hue Accuracy		0.5		Degrees	
Color Saturation Accuracy		0.7		%	
Chroma Nonlinear Gain		0.7	0.9	± %	Referenced to 40 IRE
Chroma Nonlinear Phase		0.5		±Degrees	
Chroma/Luma Intermod		0.1		± %	
Chroma/Luma Gain Ineq		1.7		± %	
Chroma/Luma Delay Ineq		2.2		ns	
Luminance Nonlinearity		0.6	0.7	± %	
Chroma AM Noise		82		dB	
Chroma PM Noise		72		dB	
Differential Gain ³		0.1(0.4)	0.3(0.5)	%	
Differential Phase ³		0.4(0.15)	0.5 (0.3)	Degrees	
SNR (Pedestal) ³		78.5 (78)		dB rms	RMS
		78 (78)		dB p-p	Peak Periodic
SNR (Ramp) ³		61.7 (61.7)		dB rms	RMS
		62 (63)		dB p-p	Peak Periodic

NOTES

Specifications subject to change without notice.

3.3 V DYNAMIC SPECIFICATIONS ($V_{AA} = 3.3 \text{ V} \pm 150 \text{ mV}$, $V_{REF} = 1.235 \text{ V}$, $R_{SET1,2} = 1200 \Omega$ unless otherwise noted. All specifications T_{MIN} to T_{MAX}^2 unless otherwise noted.)

Parameter	Min Typ Max	Unit	Test Conditions
Hue Accuracy	0.5	Degrees	
Color Saturation Accuracy	0.8	%	
Luminance Nonlinearity	0.6	± %	
Chroma AM Noise	83	dB	
Chroma PM Noise	71	dB	
Chroma Nonlinear Gain	0.7	± %	Referenced to 40 IRE
Chroma Nonlinear Phase	0.5	±Degrees	
Chroma/Luma Intermod	0.1	±%	
Differential Gain ³	0.2 (0.5)	%	
Differential Phase ³	0.5 (0.2)	Degrees	
SNR (Pedestal) ³	78.5 (78)	dB rms	RMS
, ,	78 (78)	dB p-p	Peak Periodic
SNR (Ramp) ³	62.3 (62)	dB rms	RMS
• •	61 (62.5)	dB p-p	Peak Periodic

NOTES

Specifications subject to change without notice.

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¹All measurements are made in 4× Oversampling Mode unless otherwise specified.

 $^{^2} Temperature \ range \ T_{MIN}$ to $T_{MAX}\!\!:0^\circ C$ to $70^\circ C.$

³Values in parentheses apply to 2× Oversampling Mode.

¹All measurements are made in 4× Oversampling Mode unless otherwise specified.

 $^{^2} Temperature \ range \ T_{MIN}$ to T_{MAX} : 0°C to 70°C.

 $^{^3}$ Values in brackets apply to $2\times$ Oversampling Mode.

5 V TIMING CHARACTERISTICS $(V_{AA}=5~V~\pm~250~mV, V_{REF}=1.235~V, R_{SET1,2}=1200~\Omega)$ unless otherwise noted. All specifications T_{MIN} to T_{MAX}^{-1} unless otherwise noted.)

Parameter	Min	Тур	Max	Unit	Test Conditions
MPU PORT ²					
SCLOCK Frequency	0		400	kHz	
SCLOCK High Pulsewidth, t ₁	0.6			μs	
SCLOCK Low Pulsewidth, t ₂	1.3			us us	
Hold Time (Start Condition), t ₃	0.6			μs	After This Period the First Clock Is Generated
Setup Time (Start Condition), t ₄	0.6			μs	Relevant for Repeated Start Condition
Data Setup Time, t ₅	100			ns	_
SDATA, SCLOCK Rise Time, t ₆			300	ns	
SDATA, SCLOCK Fall Time, t ₇			300	ns	
Setup Time (Stop Condition), t ₈	0.6			μs	
ANALOG OUTPUTS ²					
Analog Output Delay		8		ns	
DAC Analog Output Skew		0.1		ns	
CLOCK CONTROL AND PIXEL PORT ³					
$ _{ m CLOCK}$		27		MHz	
Clock High Time, t ₉	8			ns	
Clock Low Time, t ₁₀	8			ns	
Data Setup Time, t ₁₁	6			ns	
Data Hold Time, t ₁₂	5			ns	
Control Setup Time, t ₁₁	6			ns	
Control Hold Time, t ₁₂	4			ns	
Digital Output Access Time, t ₁₃		13	24	ns	
Digital Output Hold Time, t ₁₄		12		ns	
Pipeline Delay, t ₁₅ (2× Oversampling)		57		Clock Cycles	
Pipeline Delay, t ₁₅ (4× Oversampling)		67		Clock Cycles	
TELETEXT PORT ⁴					
Digital Output Access Time, t ₁₆		11		ns	
Data Setup Time, t ₁₇		3		ns	
Data Hold Time, t ₁₈		6		ns	
RESET CONTROL					
Reset Low Time		3	20	ns	
$\overline{\mathrm{PLL}^2}$					
PLL Output Frequency		54		MHz	

¹Temperature range T_{MIN} to T_{MAX} : 0°C to 70°C. ²Guaranteed by characterization.

Data: TTX.

Specifications subject to change without notice.

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³Pixel Port consists of the following:

Data: P0–P9, Y0/P10–Y9/P19, Control: HSYNC, VSYNC, BLANK

Clock: CLKIN Input.

⁴Teletext Port consists of: Digital Output: TTXRQ,

3.3 V TIMING CHARACTERISTICS $(V_{AA}=3.3~V~\pm~150~mV,~V_{REF}=1.235~V,~R_{SET1,2}=1200~\Omega$ unless otherwise noted. All specifications T_{MIN} to T_{MAX}^{-1} unless otherwise noted.)²

Parameter	Min	Тур	Max	Unit	Test Conditions
MPU PORT					
SCLOCK Frequency	0		400	kHz	
SCLOCK High Pulsewidth, t ₁	0.6			μs	
SCLOCK Low Pulsewidth, t ₂	1.3			μs	
Hold Time (Start Condition), t ₃	0.6			μs	After This Period the First Clock Is Generated
Setup Time (Start Condition), t ₄	0.6			μs	Relevant for Repeated Start Condition
Data Setup Time, t ₅	100			ns	
SDATA, SCLOCK Rise Time, t ₆			300	ns	
SDATA, SCLOCK Fall Time, t ₇			300	ns	
Setup Time (Stop Condition), t ₈	0.6	2		μs	
ANALOG OUTPUTS					
Analog Output Delay		8		ns	
DAC Analog Output Skew		0.1		ns	
CLOCK CONTROL AND PIXEL					
$PORT^3$					
$ m f_{CLOCK}$		27		MHz	
Clock High Time, t ₉	8			ns	
Clock Low Time, t ₁₀	8			ns	
Data Setup Time, t ₁₁	6			ns	
Data Hold Time, t ₁₂	4			ns	
Control Setup Time, t ₁₁	2.5			ns	
Control Hold Time, t ₁₂	3			ns	
Digital Output Access Time, t ₁₃		13		ns	
Digital Output Hold Time, t ₁₄		12		ns	
Pipeline Delay, t ₁₅ , 2× Oversampling		37		Clock Cycles	
TELETEXT PORT ⁴					
Digital Output Access Time, t ₁₆		11		ns	
Data Setup Time, t ₁₇		3		ns	
Data Hold Time, t ₁₈		6		ns	
RESET CONTROL					
RESET Low Time		3	20	ns	
PLL					
PLL Output Frequency		54		MHz	

NOTES

 $^{1}Temperature$ range T_{MIN} to T_{MAX} : 0°C to 70°C.

Specifications subject to change without notice.

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²Guaranteed by characterization.

³Pixel Port consists of the following:

Data: P0-P9, Y0/P10-Y9/P19,

Control: HSYNC, VSYNC, BLANK

Clock: CLKIN Input. ⁴Teletext Port consists of:

Digital Output: TTXRQ,

Data: TTX.

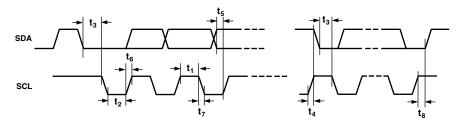


Figure 1. MPU Port Timing Diagram

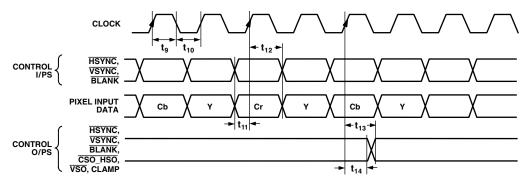


Figure 2. Pixel and Control Data Timing Diagram

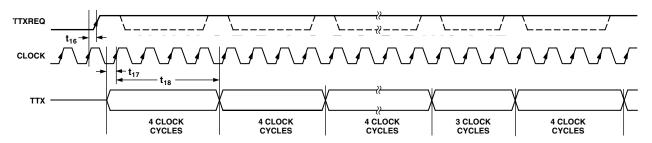


Figure 3. Teletext Timing Diagram

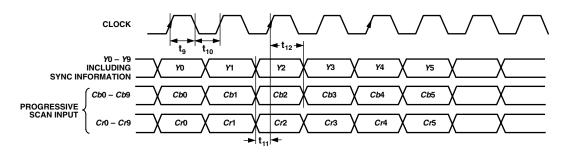


Figure 4. Progressive Scan Input Timing

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ABSOLUTE MAXIMUM RATINGS1

V _{AA} to GND 7 V
Voltage on Any Digital Input Pin GND – 0.5 V to $V_{AA} + 0.5 \text{ V}$
Storage Temperature (T_S)65°C to +150°C
Junction Temperature (T _J) 150°C
Body Temperature (Soldering, 10 secs)
Analog Outputs to GND^2 $GND - 0.5$ to V_{AA}

NOTES

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those listed in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

²Analog Output Short Circuit to any Power Supply or Common can be of an indefinite duration.

PACKAGE THERMAL PERFORMANCE

The 80-lead package is used for this device. The junction-to-ambient (θ_{JA}) thermal resistance in still air on a four-layer PCB is $24.7^{\circ}C$.

To reduce power consumption when using this part the user can run the part on a 3.3 V supply, turn off any unused DACs.

The user must at all times stay below the maximum junction temperature of 110°C. The following equation shows how to calculate this junction temperature:

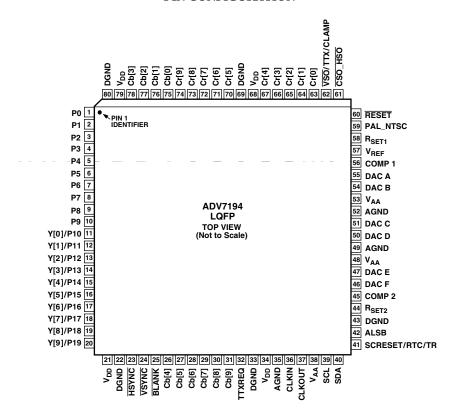
Junction Temperature = $(V_{AA} \times (I_{DAC} + I_{CCT})) \times \theta_{JA} + 70^{\circ}C (T_{AMB})$

 $I_{DAC} = 10 \text{ mA} + \text{(sum of the average currents consumed by }$ each powered-on DAC)

Average current consumed by each powered-on DAC =

 $(V_{REF} \times K)/R_{SET}$ $V_{REF} = 1.235 V$ K = 4.2146

PIN CONFIGURATION



ORDERING GUIDE

Model	Temperature Range	Package Description	Package Option
ADV7194KST	0°C to 70°C	80-Lead Quad Flatpack	ST-80

CAUTION_

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the ADV7194 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high-energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



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PIN FUNCTION DESCRIPTIONS

Pin No.	Mnemonic	Input/ Output	Function	
1–10	P0-P9	I	10-Bit or 8-Bit 4:2:2 Multiplexed YCrCb Pixel Port. The LSB of the input data is set up on Pin P0 (Pin Number 1) in 10-bit input mode.	
11-20	Y0/P10-Y9/P19	I	20-Bit or 16-Bit Multiplexed YCrCb Pixel Port or 1×10-bit progressive scan input for Y data.	
21, 34, 68, 79	V_{DD}	P	Digital Power Supply (3.3 V to 5 V).	
22, 33, 43, 69, 80	DGND	G	Digital Ground.	
23	HSYNC	I/O	HSYNC (Modes 1, 2, and 3) Control Signal. This pin may be configured to be an output (Master Mode) or an input (Slave Mode) and accept Sync Signals.	
24	VSYNC	I/O	VSYNC Control Signal. This pin may be configured as an output (Master Mode) or as an input (Slave Mode) and accept VSYNC as a Control Signal.	
25	BLANK	I/O	Video Blanking Control Signal. This signal is optional. For further information see Vertical Blanking and Data Insertion Blanking Input section.	
26-31, 75-78	Cb0-Cb9	I	1 × 10-Bit Progressive Scan Input Port for Cb Data.	
32	TTXREQ	О	Teletext Data Request Output Signal, used to control teletext data transfer.	
35, 49, 52	AGND	G	Analog Ground.	
36	CLKIN	I	TTL Clock Input. Requires a stable 27 MHz reference clock for standard operation. Alternatively, a 24.5454 MHz (NTSC) or 29.5 MHz (PAL) can be used for square pixel operation.	
37	CLKOUT	О	Clock Output Pin.	
38, 48, 53	V _{AA}	P	Analog Power Supply (3.3 V to 5 V).	
39	SCL	I	MPU Port Serial Interface Clock Input.	
40	SDA	I/O	MPU Port Serial Data Input/Output.	
41	SCRESET/RTC/TR	I	Multifunctional Input: Real-Time Control (RTC) input, Timing Reset input, Subcarrier Reset input.	
42	ALSB	I	TTL Address Input. This signal sets up the LSB of the MPU address.	
44	R _{SET2}	I	A 1200 Ω resistor connected from this pin to AGND is used to control full-scale amplitudes of the Video Signals from the DAC D, E, F.	
45	COMP 2	О	Compensation Pin for DACs D, E, and F. Connect a 0.1 μF Capacitor from COMP 2 to V_{AA} .	
46	DAC F	О	S-Video C/Pr/V/RED Analog Output. This DAC is capable of providing 4.33 mA output.	
47	DAC E	О	S-Video Y/Pb/U/BLUE Analog Output. This DAC is capable of providing 4.33 mA output.	
50	DAC D	О	Composite/Y/Y/GREEN Analog Output. This DAC is capable of providing 4.33 mA output.	
51	DAC C	О	S-Video C/Pr/V/RED Analog Output. This DAC is capable of providing 4.33 mA output.	
54	DAC B	О	S-Video Y/Pb/U/BLUE Analog Output. This DAC is capable of providing 4.33 mA output.	
55	DAC A	О	Composite/Y/Y/GREEN Analog Output. This DAC is capable of providing 4.33 mA output.	
56	COMP 1	О	Compensation Pin for DACs A, B, and C. Connect a 0.1 μF Capacitor from COMP 1 to V_{AA} .	
57	V_{REF}	I/O	Voltage Reference Input for DACs or Voltage Reference Output (1.235 V). An external V_{REF} can not be used in $4\times$ oversampling mode.	
58	R _{SET1}	I	A 1200 Ω resistor connected from this pin to AGND is used to control full-scale amplitudes of the Video Signals from the DAC A, B, C.	
59	PAL_NTSC	I	Input signal to select PAL or NTSC mode of operation, pin set to Logic 1 selects PAI	
60	RESET	I	The input resets the on-chip timing generator and sets the ADV7194 into default mode See Appendix 8 for Default Register settings.	
61	CSO_HSO	О	Dual function CSO or HSO output Sync Signal at TTL level.	
62	VSO/TTX/CLAMP	I/O	Multifunctional Pin. VSO Output Sync Signal at TTL level. Teletext Data Input pin. CLAMP TTL Output Signals can be used to drive external circuitry to enable clamping of all Video Signals.	
63–67, 70–74	Cr0-Cr9	I	1 × 10-Bit Progressive Scan Input Port for Cr Data.	

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DETAILED DESCRIPTION OF FEATURES

Clocking

Single 27 MHz Clock Required to Run the Device

4× Oversampling with Internal 54 MHz PLL

Square Pixel Operation

Advanced Power Management

Programmable Video Control Features

Digital Noise Reduction

Black Burst Signal Generation

Pedestal Level

Hue, Brightness, Contrast and Saturation

Clamping Output signal

VBI (Vertical Blanking Interval)

Subcarrier Frequency and Phase

LUMA Delay

CHROMA Delay

Gamma Correction

Luma and Chroma Filters

Luma SSAF (Super Subalias Filter)

Average Brightness Detection

Field Counter

Interlaced/Noninterlaced Operation

Complete On-Chip Video Timing Generator

Programmable Multimode Master/Slave Operation

CGMS (Copy Generation Management System)

WSS (Wide Screen Signaling)

Closed Captioning Support

Teletext Insertion Port (PAL-WST)

2-Wire Serial MPU Interface

(I²C Compatible and Fast I²C)

I²C Registers Synchronized to VSYNC

GENERAL DESCRIPTION

The ADV7194 is an integrated Digital Video Encoder that converts digital CCIR-601/656 4:2:2 10-bit (or 20-bit or 8-/16-bit) component video data into a standard analog baseband television signal compatible with worldwide standards. Additionally there is the possibility to input video data in 3× 10-bit YCrCb progressive scan format to facilitate interfacing devices such as progressive scan systems.

There are six DACs available on the ADV7194, each of which is capable of providing 4.33 mA of current. In addition to the composite output signal there is the facility to output S-Video (Y/C Video), RGB Video, and YUV Video. All YUV formats (SMPTE/EBU N10, MII, or Betacam) are supported.

The on-board SSAF (Super Subalias Filter) with extended luminance frequency response and sharp stopband attenuation enables studio quality video playback on modern TVs, giving optimal horizontal line resolution. An additional sharpness control feature allows high-frequency enhancement on the luminance signal.

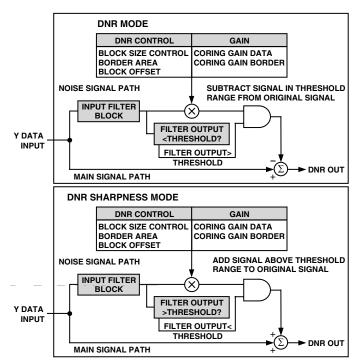


Figure 6. Block Diagram for DNR Mode and DNR Sharpness Mode

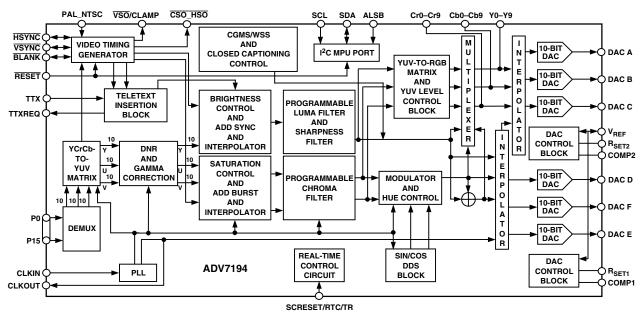


Figure 5. Detailed Functional Block Diagram

Digital noise reduction allows improved picture quality in removing low-amplitude, high-frequency noise. Figure 6 shows the DNR functionality in the two modes available.

Programmable gamma correction is also available. The figure below shows the response of different gamma values to a ramp input signal.

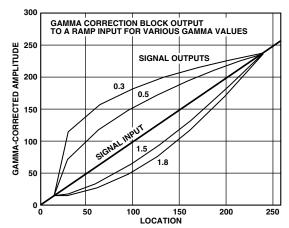


Figure 7. Signal Input (Ramp) and Selectable Gamma Output Curves

The device is driven by a 27 MHz clock. Data can be output at 27 MHz or 54 MHz (on-board PLL) when 4× oversampling is enabled. Also, the filter requirements in 4× oversampling and 2× oversampling differ, as can be seen in the figure below.

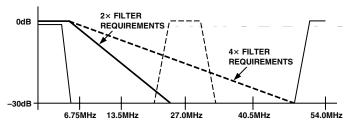


Figure 8. Output Filter Requirements in $2\times$ and $4\times$ Oversampling Mode

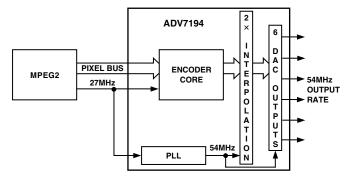


Figure 9. PLL and 4x Oversampling Block Diagram

The ADV7194 also supports both PAL and NTSC square pixel operation. In this case, the encoder requires a 24.5454 MHz clock for NTSC or 29.5 MHz clock for PAL square pixel mode operation. All internal timing is generated on-chip.

An advanced power management circuit enables optimal control of power consumption in both normal operating modes or sleep modes.

The output video frames are synchronized with the incoming data timing reference codes. Optionally the encoder accepts (and can generate) HSYNC, VSYNC and FIELD timing signals. These timing signals can be adjusted to change pulsewidth and position while the part is in master mode.

 $\overline{\text{HSO/CSO}}$ and $\overline{\text{VSO}}$ TTL outputs are also available and are timed to the analog output video.

A separate teletext port enables the user to directly input teletext data during the vertical blanking interval.

The ADV7194 also incorporates WSS and CGMS-A data control generation.

The ADV7194 modes are set up over a 2-wire serial bidirectional port (I²C-compatible) with two slave addresses and the device is register-compatible with the ADV7172/ADV7173.

The ADV7194 is packaged in an 80-lead LQFP package.

DATA PATH DESCRIPTION

For PAL B, D, G, H, I, N, and NTSC M, N modes, YCrCb 4:2:2 Data is input via the CCIR-656/601-compatible Pixel Port at a 27 MHz Data Rate. The Pixel Data is demultiplexed to form three data paths. Y typically has a range of 16 to 235, Cr and Cb typically have a range of 128+/–112; however, it is possible to input data from 1 to 254 on both Y, Cb, and Cr. The ADV7194 supports PAL (B, D, G, H, I, N) and NTSC M, N (with and without Pedestal) and PAL60 standards.

Digital Noise Reduction can be applied to the Y signal. Programmable gamma correction can also be applied to the Y signal if required.

The Y data can be manipulated for contrast control and a setup level can be added for brightness control. The Cr, Cb data can be scaled to achieve color saturation control. All settings become effective at the start of the next field when double buffering is enabled.

The appropriate sync, blank and burst levels are added to the YCrCb data. Closed-Captioning and Teletext levels are also added to Y and the resultant data is interpolated to 54 MHz (4× Oversampling Mode). The interpolated data is filtered and scaled by three digital FIR filters.

The U and V signals are modulated by the appropriate Subcarrier Sine/Cosine waveforms and a phase offset may be added onto the color subcarrier during active video to allow hue adjustment. The resulting U and V signals are added together to make up the Chrominance Signal. The Luma (Y) signal can be delayed by up to six clock cycles (at 27 MHz) and the Chroma signal can be delayed by up to eight clock cycles (at 27 MHz).

The Luma and Chroma signals are added together to make up the Composite Video Signal. All timing signals are controlled.

The YCrCb data is also used to generate RGB data with appropriate sync and blank levels. The YUV levels are scaled to output the suitable SMPTE/EBU N10, MII, or Betacam levels.

Each DAC can be individually powered off if not required. A complete description of DAC output configurations is given in the Mode Register 2 section.

Video output levels are illustrated in Appendix 9.

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When used to interface progressive scan systems, the ADV7194 allows input to YCrCb signals in Progressive Scan format (3×10 bit) before these signals are routed to the interpolation filters and the DACs.

INTERNAL FILTER RESPONSE

The Y Filter supports several different frequency responses including two low-pass responses, two notch responses, an Extended (SSAF) response with or without gain boost/attenuation, a CIF response and a QCIF response. The UV Filter supports several different frequency responses including five low-pass responses, a CIF response and a QCIF response, as can be seen in the following figures.

In Extended Mode there is the option of 12 responses in the range from –4 dB to +4 dB. The desired response can be chosen by the user by programming the correct value via the I²C. The variation of frequency responses can be seen in the tables on the following pages.

For a more detailed filter specification, refer to Analog Devices' application note AN-562.

Table I. Luminance Internal Filter Specifications (4× Oversampling)

Filter Type	Filter Selection			Passband Ripple ¹ (dB)	3 dB Bandwidth ² (MHz)
	MR04	MR03	MR02		
Low-Pass (NTSC)	0	0	0	0.16	4.24
Low-Pass (PAL)	0	0	1	0.1	4.81
Notch (NTSC)	0	1	0	0.09	2.3/4.9/6.6
Notch (PAL)	0	1	1	0.1	3.1/5.6/6.4
Extended (SSAF)	1	0	0	0.04	6.45
CIF	1	0	1	0.127	3.02
QCIF	1	1	0	Monotonic	1.5

NOTES

Table II. Chrominance Internal Filter Specifications (4× Oversampling)

Filter Type	Filte	er Select	ion	Passband Ripple ¹ (dB)	3 dB Bandwidth ² (MHz)
	MR07	MR06	MR05		
1.3 MHz Low-Pass	0	0	0	0.09	1.395
0.65 MHz Low-Pass	0	0	1	Monotonic	0.65
1.0 MHz Low-Pass	0	1	0	Monotonic	1.0
2.0 MHz Low-Pass	0	1	1	0.048	2.2
3.0 MHz Low-Pass	1	1	1	Monotonic	3.2
CIF	1	0	1	Monotonic	0.65
QCIF	1	1	0	Monotonic	0.5

NOTES

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¹Passband Ripple is defined to be fluctuations from the 0 dB response in the passband, measured in (dB). The passband is defined to have 0-fc frequency limits for a low-pass filter, 0-f1 and f2-infinity for a notch filter, where fc, f1, f2 are the =3 dB points.

²3 dB bandwidth refers to the -3 dB cutoff frequency.

¹Passband Ripple is defined to be fluctuations from the 0 dB response in the passband, measured in (dB). The passband is defined to have 0-fc frequency limits for a low-pass filter, 0-f1 and f2-infinity for a notch filter, where fc, f1, f2 are the −3 dB points.

²3 dB bandwidth refers to the –3 dB cutoff frequency.

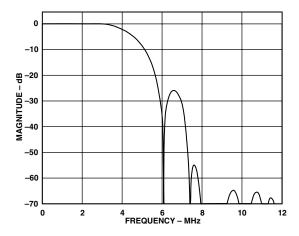


Figure 10. NTSC Low-Pass Luma Filter

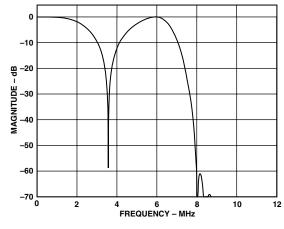


Figure 13. NTSC Notch Luma Filter

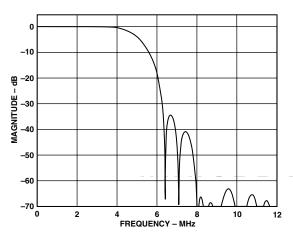


Figure 11. PAL Low-Pass Luma Filter

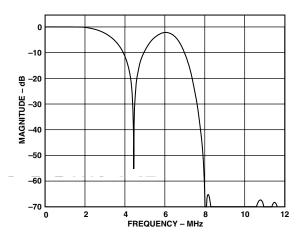


Figure 14. PAL Notch Luma Filter

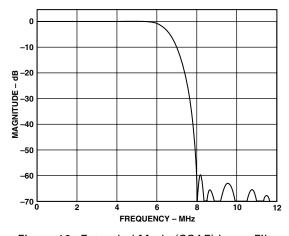


Figure 12. Extended Mode (SSAF) Luma Filter

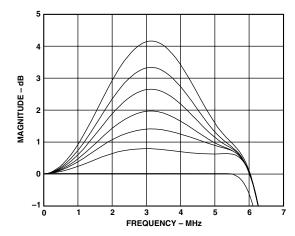


Figure 15. Extended SSAF and Programmable Gain, Showing Range 0 dB/4 dB

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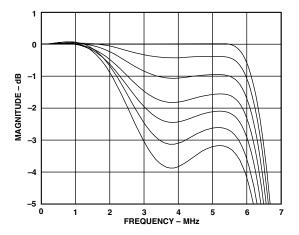


Figure 16. Extended SSAF and Programmable Attenuation, Showing Range 0 dB/–4 dB

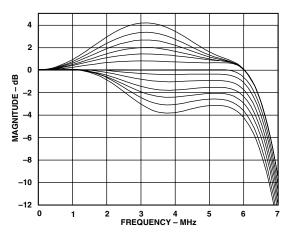


Figure 19. Extended SSAF and Programmable Gain/ Attenuation, Showing Range +4 dB/–12 dB

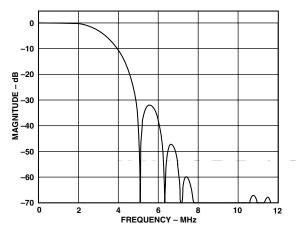


Figure 17. Luma CIF Filter

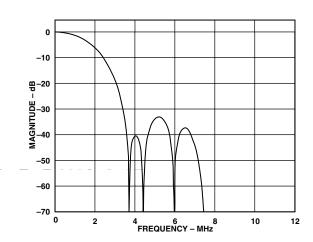


Figure 20. Luma QCIF Filter

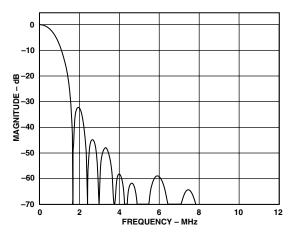


Figure 18. Chroma 0.65 MHz Low-Pass Filter

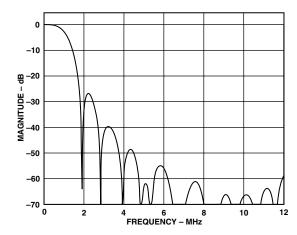


Figure 21. Chroma 1 MHz Low-Pass Filter

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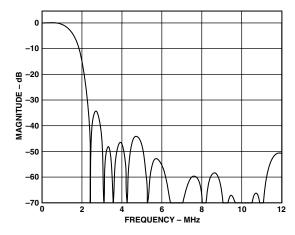
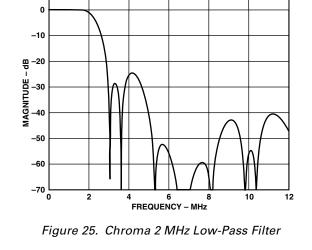


Figure 22. Chroma 1.3 MHz Low-Pass Filter



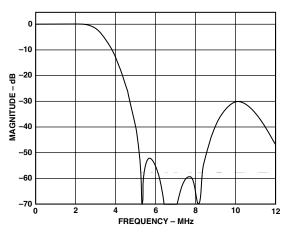


Figure 23. Chroma 3 MHz Low-Pass Filter

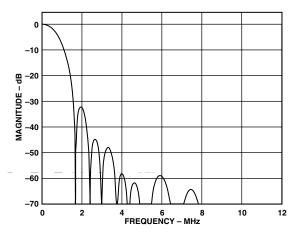


Figure 26. Chroma CIF Filter

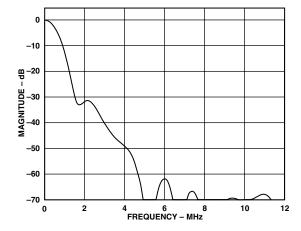


Figure 24. Chroma QCIF Filter

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FEATURES—FUNCTIONAL DESCRIPTION BLACK BURST OUTPUT

It is possible to output a black burst signal from two DACs. This signal output is very useful for professional video equipment since it enables two video sources to be locked together. (Mode Register 9.)

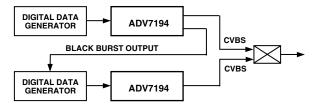


Figure 27. Possible Application for the Black Burst Output Signal

BRIGHTNESS DETECT

This feature is used to monitor the average brightness of the incoming Y video signal on a field by field basis. The information is read from the I²C and based on this information the color saturation, contrast and brightness controls can be adjusted (for example to compensate for very dark pictures). (Brightness Detect Register.)

CHROMA/LUMA DELAY

The luminance data can be delayed by maximum of six clock cycles. Additionally the Chroma can be delayed by a maximum of eight clock cycles (one clock cycle at 27 MHz). (Timing Register 0 and Mode Register 9.)

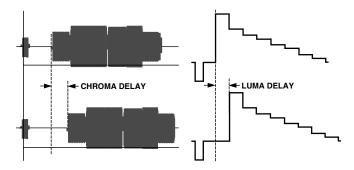


Figure 28. Chroma Delay

Figure 29. Luma Delay

CLAMP OUTPUT

The ADV7194 has a programmable clamp TTL output signal. This clamp signal is programmable to the front and back porch. The clamp signal can be varied by one to three clock cycles in a positive and negative direction from the default position. (Mode Register 5, Mode Register 7.)

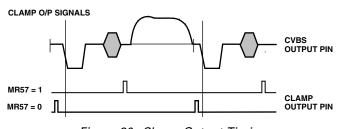


Figure 30. Clamp Output Timing

CSO, HSO, AND VSO OUTPUTS

The ADV7194 supports three output timing signals, \overline{CSO} (composite sync signal), \overline{HSO} (Horizontal Sync Signal) and \overline{VSO} (Vertical Sync Signal). These output TTL signals are aligned with the analog video outputs. See Figure 31 for an example of these waveforms. (Mode Register 7.)

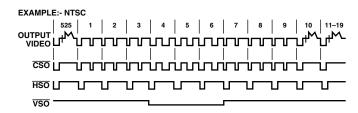


Figure 31. CSO, HSO, VSO Timing Diagram

COLOR BAR GENERATION

The ADV7194 can be configured to generate 100/7.5/75/7.5 color bars for NTSC or 100/0/75/0 color bars for PAL. (Mode Register 4.)

COLOR BURST SIGNAL CONTROL

The burst information can be switched on and off the composite and chroma video output. (Mode Register 4.)

COLOR CONTROLS

The ADV7194 allows the user to control the brightness, contrast, hue and saturation of the color. The control registers may be double-buffered, meaning that any modification to the registers will be done outside the active video region and, therefore, changes made will not be visible during active video.

Contrast Control

Contrast adjustment is achieved by scaling the Y input data by a factor programmed by the user. This factor allows the data to be scaled between 0% and 150%. (Contrast Control Register.)

Brightness Control

The brightness is controlled by adding a programmable setup level onto the scaled Y data. This brightness level may be added onto the Y data. For NTSC with pedestal, the setup can vary from 0 IRE to 22.5 IRE. For NTSC without pedestal and PAL, the setup can vary from –7.5 IRE to +15 IRE. (Brightness Control Register.)

Color Saturation

Color adjustment is achieved by scaling the Cr and Cb input data by a factor programmed by the user. This factor allows the data to be scaled between 0% and 200%. (U Scale Register and V Scale Register.)

Hue Adjust Control

The hue adjustment is achieved on the composite and chroma outputs by adding a phase offset onto the color subcarrier in the active video but leaving the color burst unmodified, i.e., only the phase between the video and the colorburst is modified and hence the hue is shifted. The ADV7194 provides a range of $\pm 22^{\circ}$ in increments of 0.17578125° . (Hue Adjust Register.)

CHROMINANCE CONTROL

The color information can be switched on and off the composite, chroma and color component video outputs. (Mode Register 4.)

UNDERSHOOT LIMITER

A limiter is placed after the digital filters. This prevents any synchronization problems for TVs. The level of undershoot is programmable between -1.5 IRE, -6 IRE, -11 IRE when operating in 4× Oversampling Mode. In 2× Oversampling Mode the limits are -7.5 IRE and 0 IRE. (Mode Register 9 and Timing Register 0.)

DIGITAL NOISE REDUCTION

DNR is applied to the Y data only. A filter block selects the high frequency, low-amplitude components of the incoming signal (DNR Input Select). The absolute value of the filter output is compared to a programmable threshold value (DNR Threshold Control). There are two DNR modes available: DNR Mode and DNR Sharpness Mode.

In DNR Mode, if the absolute value of the filter output is smaller than the threshold, it is assumed to be noise. A programmable amount (Coring Gain Control) of this noise signal will be subtracted from the original signal.

In DNR Sharpness Mode, if the absolute value of the filter output is less than the programmed threshold, it is assumed to be noise, as before. Otherwise, if the level exceeds the threshold, now being identified as a valid signal, a fraction of the signal (Coring Gain Control) will be added to the original signal in order to boost high frequency components and to sharpen the video image.

In MPEG systems it is common to process the video information in blocks of 8×8 pixels for MPEG2 systems, or 16×16 pixels for MPEG1 systems (Block Size Control). DNR can be applied to the resulting block transition areas that are known to contain noise. Generally the block transition area contains two pixels. It is possible to define this area to contain four pixels (Border Area Control).

It is also possible to compensate for variable block positioning or differences in YCrCb pixel timing with the use of the Block Offset Control. (Mode Register 8, DNR Registers 0–2.)

DOUBLE BUFFERING

Double buffering can be enabled or disabled on the following registers: Closed Captioning Registers, Brightness Control Register, V-Scale Register, U-Scale Register, Contrast Control Register, Hue Adjust Register, and the Gamma Curve Select bit. These registers are updated once per field on the falling edge of the VSYNC signal. Double Buffering improves the overall performance of the ADV7194, since modifications to register settings will not be made during active video, but take effect on the start of the active video. (Mode Register 8.)

GAMMA CORRECTION CONTROL

Gamma correction may be performed on the luma data. The user has the choice to use either of two different gamma curves, A or B. At any one time one of these curves is operational if gamma correction is enabled. Gamma correction allows the mapping of the luma data to a user-defined function. (Mode Register 8, Gamma Correction Registers 0–13.)

NTSC PEDESTAL CONTROL

In NTSC mode it is possible to have the pedestal signal generated on the output video signal. (Mode Register 2.)

POWER-ON RESET

After power-up, it is necessary to execute a \overline{RESET} operation. A reset occurs on the falling edge of a high-to-low transition on the \overline{RESET} pin. This initializes the pixel port such that the data on the pixel inputs pins is ignored. See Appendix 8 for the register settings after \overline{RESET} is applied.

PROGRESSIVE SCAN INPUT

It is possible to input data to the ADV7194 in progressive scan format. For this purpose the input pins Y0/P10–Y9/P19, Cr0–Cr9, Cb0–Cb9 accept 10-bit Y data, 10-bit Cb data and 10-bit Cr data. The data is clocked into the part at 27 MHz. The data is then filtered and sinc corrected in an 2× Interpolation filter and then output to three video DACs at 54 MHz (to interface to a progressive scan monitor).

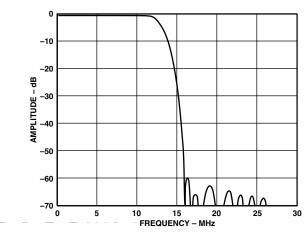


Figure 32. Plot of the Interpolation Filter for the Y Data

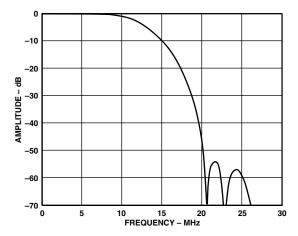


Figure 33. Plot of the Interpolation Filter for the CrCb Data

It is assumed that there is no color space conversion or any other such operation to be performed on the incoming data. Thus if these DAC outputs are to drive a TV, all relevant timing and synchronization data should be contained in the incoming digital Y data. An FPGA can be used to achieve this.

The block diagram below shows a possible configuration for progressive scan mode using the ADV7194.

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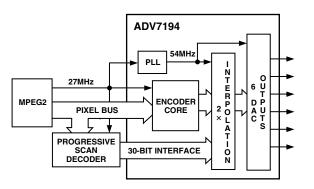


Figure 34. Block Diagram Using the ADV7194 in Progressive Scan Mode

The progressive scan decoder deinterlaces the data from the MPEG2 decoder. This now means that there are 525 video lines per field in NTSC mode and 625 video lines per field in PAL mode. The duration of the video line is now 32 μ s.

It is important to note that the data from the MPEG2 decoder is in 4:2:2 format. The data output from the progressive scan decoder is in 4:4:4 format. Thus it is assumed that some form of interpolation on the color component data is performed in the progressive scan decoder IC. (Mode Register 8.)

REAL-TIME CONTROL, SUBCARRIER RESET AND TIMING RESET

Together with the SCRESET/RTC/TR pin and of Mode Register 4 (Genlock Control), the ADV7194 can be used in (a) Timing Reset Mode, (b) Subcarrier Phase Reset Mode or (c) RTC Mode.

- (a) A TIMING RESET is achieved in holding this pin high. In this state the horizontal and vertical counters will remain reset. On releasing this pin (set to low), the internal counters will commence counting again. The minimum time the pin has to be held high is 37 ns (1 clock cycle at 27 MHz), otherwise the reset signal might not be recognized.
- (b) The SUBCARRIER PHASE will reset to that of Field 0 at the start of the following field when a low to high transition occurs on this input pin.
- (c) In RTC MODE, the ADV7194 can be used to lock to an external video source.

The real-time control mode allows the ADV7194 to automatically alter the subcarrier frequency to compensate for line length variations. When the part is connected to a device that outputs a digital datastream in the RTC format (such as an ADV7185 video decoder, see Figure 37), the part will automatically change to the compensated subcarrier frequency on a line-by-line basis. This digital datastream is 67 bits wide and the subcarrier is contained in Bits 0 to 21. Each bit is two clock cycles long. 00Hex should be written into all four Subcarrier Frequency registers when using this mode. It is recommended to use the ADV7185 in this mode (Mode Register 4.)

SCH PHASE MODE

The SCH phase is configured in default mode to reset every four (NTSC) or eight (PAL) fields to avoid an accumulation of SCH phase error over time. In an ideal system, zero SCH phase error would be maintained forever, but, in reality, this is impossible to achieve due to clock frequency variations. This effect is reduced by the use of a 32-bit DDS, which generates this SCH.

Resetting the SCH phase every four or eight fields avoids the accumulation of SCH phase error, and results in very minor SCH phase jumps at the start of the four or eight field sequence.

Resetting the SCH phase should not be done if the video source does not have stable timing or the ADV7194 is configured in RTC mode. Under these conditions (unstable video) the Subcarrier Phase Reset should be enabled but no reset applied. In this configuration the SCH Phase will never be reset; this means that the output video will now track the unstable input video. The Subcarrier Phase Reset when applied will reset the SCH phase to Field 0 at the start of the next field (e.g., Subcarrier Phase Reset applied in Field 5 (PAL) on the start of the next field SCH phase will be reset to Field 0). (Mode Register 4.)

SLEEP MODE

If, after RESET, the SCRESET/RTC/TR and NTSC_PAL pins are both set high, the ADV7194 will power-up in Sleep Mode to facilitate low-power consumption before all registers have been initialized.

If Power-up in Sleep Mode is disabled, Sleep Mode control passes to the Sleep Mode control in Mode Register 2 (i.e., control via I²C). (Mode Register 2 and Mode Register 6.)

SQUARE PIXEL MODE

The ADV7194 can be used to operate in square pixel mode. For NTSC operation an input clock of 24.5454 MHz is required. Alternatively, for PAL operation, an input clock of 29.5 MHz is required. The internal timing logic adjusts accordingly for square pixel mode operation. Square pixel mode is not available in 4× Oversampling mode. (Mode Register 2.)

VERTICAL BLANKING DATA INSERTION AND $\overline{\text{BLANK}}$ INPUT

It is possible to allow encoding of incoming YCbCr data on those lines of VBI that do not have line sync or pre-/post-equalization pulses. This mode of operation is called *Partial Blanking*. It allows the insertion of any VBI data (Opened VBI) into the encoded output waveform, this data is present in digitized incoming YCbCr data stream (e.g., WSS data, CGMS, VPS etc.). Alternatively the entire VBI may be blanked (no VBI data inserted) on these lines. VBI is available in all timing modes.

It is possible to allow control over the \overline{BLANK} signal using Timing Register 0. When the \overline{BLANK} input is enabled (TR03 = 0 and input pin tied low), the \overline{BLANK} input can be used to input externally generated blank signals in Slave Mode 1, 2, or 3. When the \overline{BLANK} input is disabled (TR03 = 1 and input pin tied low or tied high) the \overline{BLANK} input is not used and the ADV7194 automatically blanks all normally blank lines as per CCIR-624. (Timing Register 0.)

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YUV LEVELS

This functionality allows the ADV7194 to output SMPTE levels or Betacam levels on the Y output when configured in PAL or NTSC mode.

	Sync	Video	
Betacam	286 mV	714 mV	
SMPTE	300 mV	700 mV	
MII	300 mV	700 mV	

As the data path is branched at the output of the filters the luma signal relating to the CVBS or S-Video Y/C output is unaltered. It is only the Y output of the YCrCb outputs that is scaled. This control allows color component levels to have a peak-peak amplitude of 700 mV, 1000 mV or the default values of 934 mV in NTSC and 700 mV in PAL. (Mode Register 5.)

20-/16-BIT INTERFACE

It is possible to input data in 20-bit or 16-bit format. In this case, the interface only operates if the data is accompanied by separate HSYNC/VSYNC/BLANK signals. Twenty-bit or 16-bit mode is not available in Slave Mode 0 since EAV/SAV timing codes are used. (Mode Register 8.)

4× OVERSAMPLING AND INTERNAL PLL

It is possible to operate all six DACs at 27 MHz (2× Oversampling) or 54 MHz (4× Oversampling).

The ADV7194 is supplied with a 27 MHz clock synced with the incoming data. Two options are available: to run the device throughout at 27 MHz or to enable the PLL. In the latter case, even if the incoming data runs at 27 MHz, 4× Oversampling and the internal PLL will output the data at 54 MHz.

NOTE

In 4× Oversampling Mode the requirements for the optional output filters are different than from those in 2× Oversampling. (Mode Register 1, Mode Register 6.)

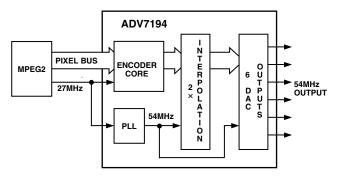


Figure 35a. PLL and 4x Oversampling Block Diagram

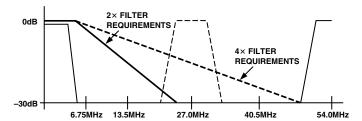


Figure 35b. Output Filter Requirements in 4x Oversampling Mode

VIDEO TIMING DESCRIPTION

The ADV7194 is intended to interface to off-the-shelf MPEG1 and MPEG2 Decoders. As a consequence, the ADV7194 accepts 4:2:2 YCrCb Pixel Data via a CCIR-656 Pixel Port and has several Video Timing Modes of operation that allow it to be configured as either System Master Video Timing Generator or a Slave to the System Video Timing Generator. The ADV7194 generates all of the required horizontal and vertical timing periods and levels for the analog video outputs.

The ADV7194 calculates the width and placement of analog sync pulses, blanking levels, and color burst envelopes. Color bursts are disabled on appropriate lines and serration and equalization pulses are inserted where required.

In addition, the ADV7194 supports a PAL or NTSC square pixel operation. The part requires an input pixel clock of 24.5454 MHz for NTSC square pixel operation and an input pixel clock of 29.5 MHz for PAL square pixel operation. The internal horizontal line counters place the various video waveform sections in the correct location for the new clock frequencies.

The ADV7194 has four distinct Master and four distinct Slave timing configurations. Timing Control is established with the bidirectional HSYNC, BLANK and VSYNC pins. Timing Register 1 can also be used to vary the timing pulsewidths and where they occur in relation to each other. (Mode Register 2, Timing Register 0, 1.)

RESET SEQUENCE

When RESET becomes active the ADV7194 reverts to the default output configuration (see Appendix for register settings). The ADV7194 internal timing is under the control of the logic level on the NTSC_PAL pin.

When RESET is released Y, Cr, Cb values corresponding to a black screen are input to the ADV7194. Output timing signals are still suppressed at this stage. DACs A, B, C are switched off and DACs D, E, F are switched on.

When the user requires valid data, Pixel Data Valid Control is enabled (MR26 = 1) to allow the valid pixel data to pass through the encoder. Digital output timing signals become active and the encoder timing is now under the control of the Timing Registers. If at this stage, the user wishes to select a different video standard to that on the NTSC_PAL pin, Standard I²C Control should be enabled (MR25 = 1) and the video standard required is selected by programming Mode Register 0 (Output Video Standard Selection). Figure 36 illustrates the RESET sequence timing.

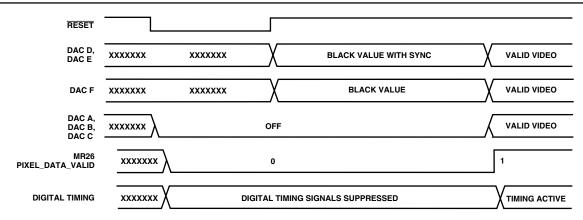


Figure 36. RESET Sequence Timing Diagram

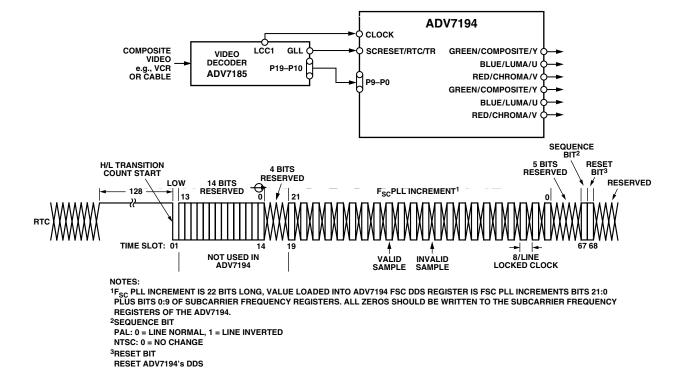


Figure 37. RTC Timing and Connections

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Mode 0 (CCIR-656): Slave Option

(Timing Register 0 TR0 = X X X X X 0 0 0)

The ADV7194 is controlled by the SAV (Start Active Video) and EAV (End Active Video) Time Codes in the Pixel Data. All timing information is transmitted using a 4-byte synchronization pattern. A synchronization pattern is sent immediately before and after each line during active picture and retrace. Mode 0 is illustrated in Figure 38. The HSYNC, VSYNC and BLANK (if not used) pins should be tied high during this mode. Blank output is available.

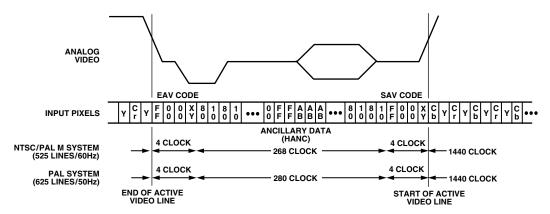


Figure 38. Timing Mode 0, Slave Mode

Mode 0 (CCIR-656): Master Option

(Timing Register 0 TR0 = X X X X X 0 0 1)

The ADV7194 generates H, V, and F signals required for the SAV (Start Active Video) and EAV (End Active Video) Time Codes in the CCIR656 standard. The H bit is output on the HSYNC pin, the V bit is output on the BLANK pin and the F bit is output on the VSYNC pin. Mode 0 is illustrated in Figure 39 (NTSC) and Figure 40 (PAL). The H, V, and F transitions relative to the video waveform are illustrated in Figure 41.

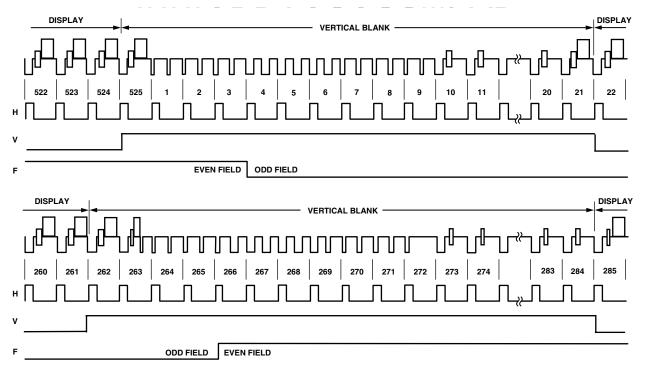


Figure 39. Timing Mode 0, NTSC Master Mode

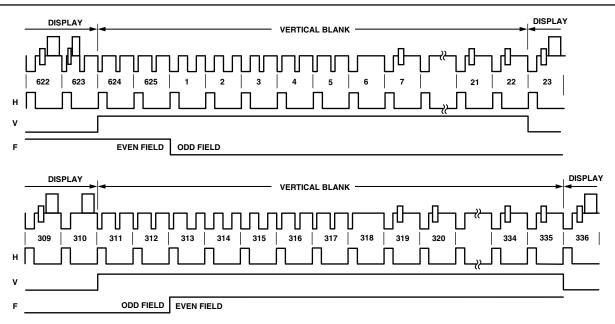


Figure 40. Timing Mode 0, PAL Master Mode

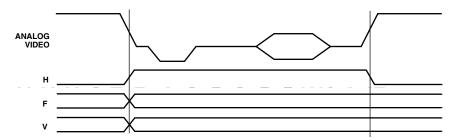


Figure 41. Timing Mode 0 Data Transitions, Master Mode

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Mode 1: Slave Option HSYNC, BLANK, FIELD

(Timing Register 0 TR0 = X X X X X 0 1 0)

In this mode the ADV7194 accepts Horizontal SYNC and Odd/Even FIELD signals. A transition of the FIELD input when HSYNC is low indicates a new frame, i.e., Vertical Retrace. The BLANK signal is optional. When the BLANK input is disabled the ADV7194 automatically blanks all normally blank lines as per CCIR-624. Mode 1 is illustrated in Figure 42 (NTSC) and Figure 43 (PAL).

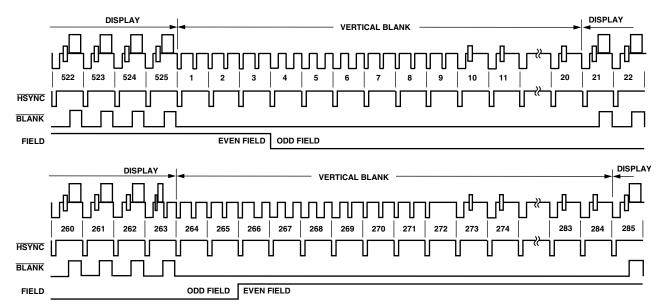


Figure 42. Timing Mode 1, NTSC

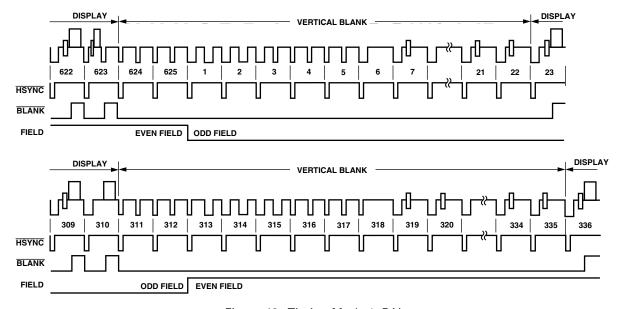


Figure 43. Timing Mode 1, PAL

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Mode 1: Master Option HSYNC, BLANK, FIELD

(Timing Register 0 TR0 = X X X X X 0 1 1)

In this mode the ADV7194 can generate Horizontal SYNC and Odd/Even FIELD signals. A transition of the FIELD input when HSYNC is low indicates a new frame, i.e., Vertical Retrace. The BLANK signal is optional. When the BLANK input is disabled the ADV7194 automatically blanks all normally blank lines as per CCIR-624. Pixel data is latched on the rising clock edge following the timing signal transitions. Mode 1 is illustrated in Figure 42 (NTSC) and Figure 43 (PAL). Figure 44 illustrates the HSYNC, BLANK and FIELD for an odd-or-even field transition relative to the pixel data.

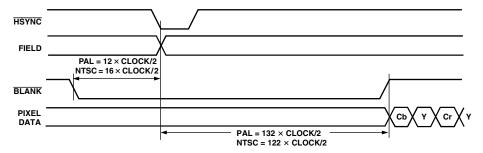


Figure 44. Timing Mode 1 Odd/Even Field Transitions Master/Slave

Mode 2: Slave Option HSYNC, VSYNC, BLANK

(Timing Register 0 TR0 = X X X X X 1 0 0)

In this mode the ADV7194 accepts Horizontal and Vertical SYNC signals. A coincident low transition of both HSYNC and VSYNC inputs indicates the start of an Odd Field. A VSYNC low transition when HSYNC is high indicates the start of an Even Field. The BLANK signal is optional. When the BLANK input is disabled, the ADV7194 automatically blanks all normally blank lines as per CCIR-624. Mode 2 is illustrated in Figure 45 (NTSC) and Figure 46 (PAL).

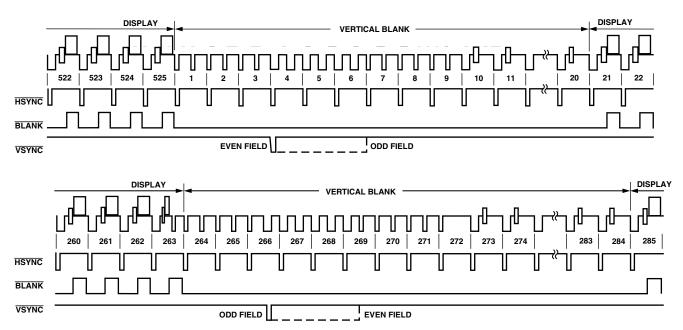


Figure 45. Timing Mode 2, NTSC

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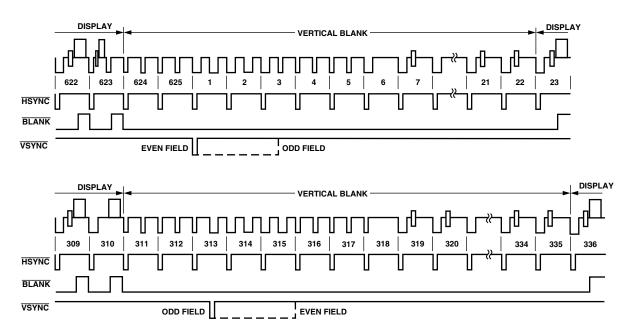


Figure 46. Timing Mode 2, PAL

Mode 2: Master Option HSYNC, VSYNC, BLANK

(Timing Register 0 TR0 = X X X X X 1 0 1)

In this mode the ADV7194 can generate Horizontal and Vertical SYNC signals. A coincident low transition of both \overline{HSYNC} and \overline{VSYNC} inputs indicates the start of an Odd Field. A \overline{VSYNC} low transition when \overline{HSYNC} is high indicates the start of an Even Field. The \overline{BLANK} signal is optional. When the \overline{BLANK} input is disabled, the ADV7194 automatically blanks all normally blank lines as per CCIR-624. Mode 2 is illustrated in Figure 45 (NTSC) and Figure 46 (PAL). Figure 47 illustrates the \overline{HSYNC} , \overline{BLANK} and \overline{VSYNC} for an even-to-odd field transition relative to the pixel data. Figure 48 illustrates the \overline{HSYNC} , \overline{BLANK} and \overline{VSYNC} for an odd-to-even field transition relative to the pixel data.

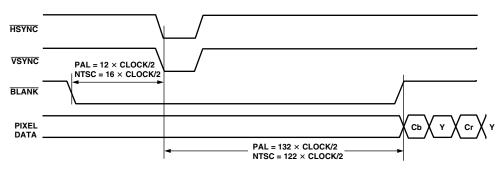


Figure 47. Timing Mode 2, Even-to-Odd Field Transition Master/Slave

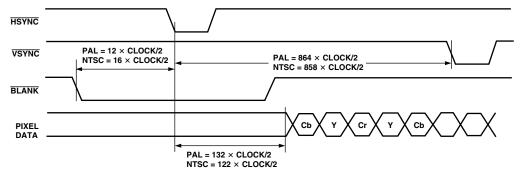


Figure 48. Timing Mode 2, Odd-to-Even Field Transition Master/Slave

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Mode 3: Master/Slave Option HSYNC, BLANK, FIELD (Timing Register 0 TR0 = X X X X X 1 1 0 or X X X X X 1 1 1)

In this mode the ADV7194 accepts or generates Horizontal SYNC and Odd/Even FIELD signals. A transition of the FIELD input when $\overline{\text{HSYNC}}$ is high indicates a new frame, i.e., Vertical Retrace. The $\overline{\text{BLANK}}$ signal is optional. When the $\overline{\text{BLANK}}$ input is disabled the ADV7194 automatically blanks all normally blank lines as per CCIR-624. Mode 3 is illustrated in Figure 49 (NTSC) and Figure 50 (PAL).

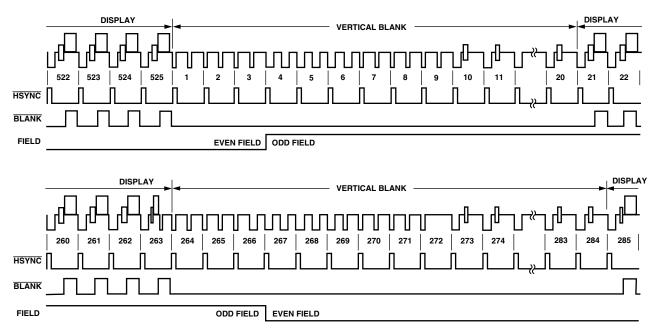


Figure 49. Timing Mode 3, NTSC

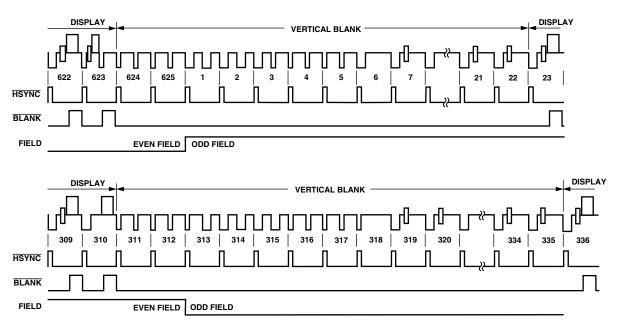


Figure 50. Timing Mode 3, PAL

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MPU PORT DESCRIPTION

The ADV7194 supports a 2-wire serial (I²C-compatible) microprocessor bus driving multiple peripherals. Two inputs Serial Data (SDA) and Serial Clock (SCL) carry information between any device connected to the bus. Each slave device is recognized by a unique address. The ADV7194 has four possible slave addresses for both read and write operations. These are unique addresses for each device and are illustrated in Figure 51 and Figure 53. The LSB sets either a read or write operation. Logic Level 1 corresponds to a read operation while Logic Level 0 corresponds to a write operation. A1 is set by setting the ALSB pin of the ADV7194 to Logic Level 0 or Logic Level 1. When ALSB is set to 0, there is greater input bandwidth on the I²C lines, which allows high speed data transfers on this bus. When ALSB is set to 1, there is reduced input bandwidth on the I²C lines, which means that pulses of less than 50 ns will not pass into the I²C internal controller. This mode is recommended for noisy systems.

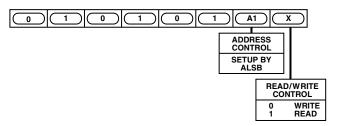


Figure 51. Slave Address

To control the various devices on the bus the following protocol must be followed. First the master initiates a data transfer by establishing a start condition, defined by a high to low transition on SDA while SCL remains high. This indicates that an address/data stream will follow. All peripherals respond to the start condition and shift the next eight bits (7-bit address + $R\overline{W}$ bit). The bits are transferred from MSB down to LSB. The peripheral that recognizes the transmitted address responds by pulling the data line low during the ninth clock pulse. This is known as an acknowledge bit. All other devices withdraw from the bus at this point and maintain an idle condition. The idle condition is where the device monitors the SDA and SCL lines waiting for the start condition and the correct transmitted address. The $R\overline{W}$ bit determines the direction of the data.

A Logic 0 on the LSB of the first byte means that the master will write information to the peripheral. A Logic 1 on the LSB of the first byte means that the master will read information from the peripheral.

The ADV7194 acts as a standard slave device on the bus. The data on the SDA pin is 8 bits long supporting the 7-bit addresses plus the $R\overline{W}$ bit. It interprets the first byte as the device address and the second byte as the starting subaddress. The subaddresses autoincrement allowing data to be written to or read from the starting subaddress. A data transfer is always terminated by a stop condition. The user can also access any unique subaddress register on a one by one basis without having to update all the registers. There is one exception. The Subcarrier Frequency Registers should be updated in sequence, starting with Subcarrier Frequency Register 0. The autoincrement function should be then used to increment and access Subcarrier Frequency Registers 1, 2, and 3. The Subcarrier Frequency Registers should not be accessed independently.

Stop and start conditions can be detected at any stage during the data transfer. If these conditions are asserted out of sequence with normal read and write operations, then these cause an immediate jump to the idle condition. During a given SCL high period the user should only issue one start condition, one stop condition or a single stop condition followed by a single start condition. If an invalid subaddress is issued by the user, the ADV7194 will not issue an acknowledge and will return to the idle condition. If in autoincrement mode, the user exceeds the highest subaddress then the following action will be taken:

- 1. In Read Mode, the highest subaddress register contents will continue to be output until the master device issues a no-acknowledge. This indicates the end of a read. A no-acknowledge condition is where the SDA line is not pulled low on the ninth pulse.
- 2. In Write Mode, the data for the invalid byte will be not be loaded into any subaddress register, a no-acknowledge will be issued by the ADV7194 and the part will return to the idle condition.



Figure 52. Bus Data Transfer

Figure 52 illustrates an example of data transfer for a read sequence and the start and stop conditions.

Figure 53 shows bus write and read sequences.

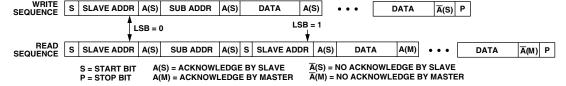


Figure 53. Write and Read Sequences

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REGISTER ACCESSES

The MPU can write to or read from all of the registers of the ADV7194 except the Subaddress Registers which are write only registers. The Subaddress Register determines which register the next read or write operation accesses. All communications with the part through the bus start with an access to the Subaddress Register. Then a read/write operation is performed from/to the target address which then increments to the next address until a stop command on the bus is performed.

REGISTER PROGRAMMING

The following section describes each register. All registers can be read from as well as written to.

Subaddress Register (SR7-SR0)

The Communications Register is an 8-bit write-only register. After the part has been accessed over the bus and a read/write operation is selected, the subaddress is set up. The Subaddress Register determines to/from which register the operation takes place.

Figure 54 shows the various operations under the control of the Subaddress Register 0 should always be written to SR7.

Register Select (SR6-SR0)

These bits are set up to point to the required starting address.

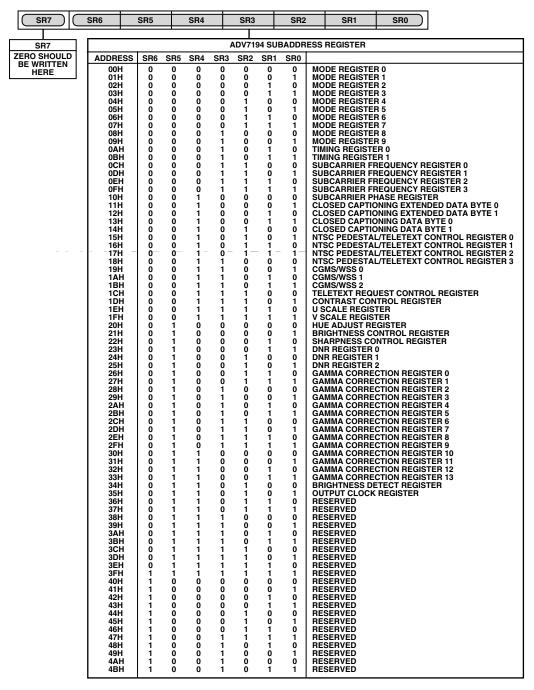


Figure 54. Subaddress Register for the ADV7194

MODE REGISTER 0 MR0 (MR07-MR00)

(Address (SR4-SR0) = 00H)

Figure 55 shows the various operations under the control of Mode Register 0.

MR0 BIT DESCRIPTION

Output Video Standard Selection (MR00-MR01)

These bits are used to setup the encoder mode. The ADV7194 can be set up to output NTSC, PAL (B, D, G, H, I), or PAL N standard video.

Luminance Filter Select (MR02-MR04)

These bits specify which luma filter is to be selected. The filter selection is made independent of whether PAL or NTSC is selected.

Chrominance Filter Select (MR05-MR07)

These bits select the chrominance filter. A low-pass filter can be selected with a choice of cutoff frequencies (0.65 MHz, 1.0 MHz, 1.3 MHz, 2 MHz, or 3 MHz) along with a choice of CIF or QCIF filters.

MODE REGISTER 1

MR1 (MR17-MR10)

(Address (SR4-SR0) = 01H)

Figure 56 shows the various operations under the control of Mode Register 1.

MR1 BIT DESCRIPTION

DAC Control (MR10-MR15)

Bits MR15–MR10 can be used to power down the DACs. This are used to reduce the power consumption of the ADV7194 or if any of the DACs are not required in the application.

4× Oversampling Control (MR16)

To enable 4× Oversampling this bit has to be set to 1. When enabled, the data is output at a frequency of 54 MHz.

Note that PLL Enable Control has to be enabled (MR61 = 0) in $4 \times$ Oversampling mode.

Reserved (MR17)

A Logical 0 must be written to this bit.

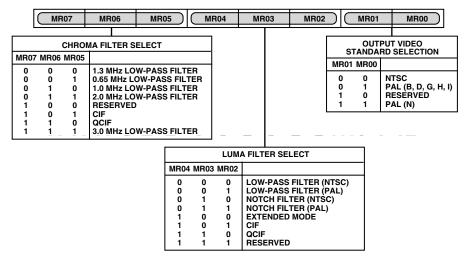


Figure 55. Mode Register 0, MR0

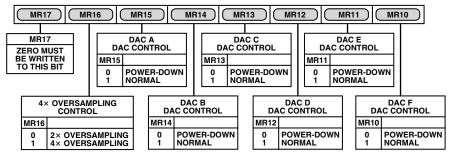


Figure 56. Mode Register 1, MR1

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MODE REGISTER 2

MR2 (MR27-MR20)

(Address (SR4-SR0) = 02H)

Mode Register 2 is an 8-bit-wide register.

Figure 57 shows the various operations under the control of Mode Register 2.

MR2 BIT DESCRIPTION

RGB/YUV Control (MR20)

This bit enables the output from the DACs to be set to YUV or RGB output video standard.

DAC Output Control (MR21)

This bit controls the output from DACs A, B, and C. When this bit is set to 1, Composite, Luma and Chroma Signals are output from DACs A, B and C (respectively). When this bit is set to 0, RGB or YUV may be output from these DACs.

SCART Enable Control (MR22)

This bit is used to switch the DAC outputs from SCART to a EUROSCART configuration. A complete table of all DAC output configurations is shown below.

Pedestal Control (MR23)

This bit specifies whether a pedestal is to be generated on the NTSC composite video signal. This bit is invalid when the device is configured in PAL mode.

Square Pixel Control (MR24)

This bit is used to setup square pixel mode. This is available in Slave Mode only. For NTSC, a 24.54 MHz clock must be supplied. For PAL, a 29.5 MHz clock must be supplied. Square pixel operation is not available in 4× Oversampling mode.

Standard I²C Control (MR25)

This bit controls the video standard used by the ADV7194. When this bit is set to 1 the video standard is as programmed in Mode Register 0 (Output Video Standard Selection). When it is set to 0, the ADV7194 is forced into the standard selected by the NTSC_PAL pin. When NTSC_PAL is low the standard is NTSC, when the NTSC_PAL pin is high, the standard is PAL.

Pixel Data Valid Control (MR26)

After resetting the device this bit has the value 0 and the pixel data input to the encoder is blanked such that a black screen is output from the DACs. The ADV7194 will be set to Master Mode timing. When this bit is set to 1 by the user (via the I²C), pixel data passes to the pins and the encoder reverts to the timing mode defined by Timing Mode Register 0.

Sleep Mode Control (MR27)

When this bit is set (1), Sleep Mode is enabled. With this mode enabled the ADV7194 current consumption is reduced to typically less than 0.1 mA. The I²C registers can be written to and read from when the ADV7194 is in Sleep Mode.

When the device is in Sleep Mode and 0 is written to MR27, the ADV7194 will come out of Sleep Mode and resume normal operation. Also, if a RESET is applied during Sleep Mode the ADV7194 will come out of Sleep Mode and resume normal operation.

For this to operate, Power up in Sleep Mode control has to be enabled (MR60 is set to a Logic 1), otherwise Sleep Mode is controlled by the PAL_NTSC and SCRESET/RTC/TR pins.

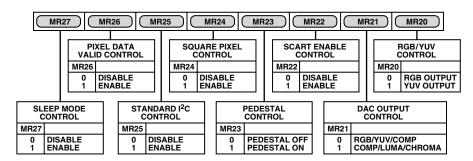


Figure 57. Mode Register 2, MR2

Table V. DAC Output Configuration

MR22	MR21	MR20	DAC A	DAC B	DAC C	DAC D	DAC E	DAC F
0	0	0	G (Y)	B (Pb)	R (Pr)	CVBS	LUMA	CHROMA
0	0	1	Y (Y)	U (Pb)	V (Pr)	CVBS	LUMA	CHROMA
0	1	0	CVBS	LUMA	CHROMA	G (Y)	B (Pb)	R (Pr)
0	1	1	CVBS	LUMA	CHROMA	Y (Y)	U (Pb)	V (Pr)
1	0	0	CVBS	B (Pb)	R (Pr)	G (Y)	LUMA	CHROMA
1	0	1	CVBS	U (Pb)	V (Pr)	Y (Y)	LUMA	CHROMA
1	1	0	CVBS	LUMA	CHROMA	G (Y)	B (Pb)	R (Pr)
1	1	1	CVBS	LUMA	CHROMA	Y (Y)	U (Pb)	V (Pr)

NOTE

In Progressive Scan Mode (MR80, 1) the DAC output configuration is stated in the brackets.

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MODE REGISTER 3 MR3 (MR37–MR30)

(Address (SR4-SR0) = 03H)

Mode Register 3 is an 8-bit-wide register. Figure 58 shows the various operations under the control of Mode Register 3.

MR3 BIT DESCRIPTION

Revision Code (MR30-MR31)

This bit is read only and indicates the revision of the device.

VBI Open (MR32)

This bit determines whether or not data in the Vertical Blanking Interval (VBI) is output to the analog outputs or blanked. Note that this condition is also valid in Timing Slave Mode 0. For further information see Vertical Blanking section.

Teletext Enable (MR33)

This bit must be set to 1 to enable teletext data insertion on the TTX pin. Note: TTX functionality is shared with $\overline{\text{VSO}}$ and CLAMP on Pin 62. CLAMP/ $\overline{\text{VSO}}$ Select (MR77) and TTX Input/CLAMP/ $\overline{\text{VSO}}$ Output (MR76) have to be set accordingly.

Teletext Bit Request Mode Control (MR34)

This bit enables switching of the teletext request signal from a continuous high signal (MR34 = 0) to a bitwise request signal (MR34 = 1).

Closed Captioning Field Control (MR35-MR36)

These bits control the fields that closed captioning data is displayed on, closed captioning information can be displayed on an odd field, even field or both fields.

Reserved (MR37)

A Logic 0 must be written to this bit.

MODE REGISTER 4 MR4 (MR47–MR40)

(Address (SR4-SR0) = 04H)

Mode Register 4 is an 8-bit-wide register. Figure 59 shows the various operations under the control of Mode Register 4.

MR4 BIT DESCRIPTION

VSYNC_3H Control (MR40)

When this bit is enabled (1) in Slave Mode, it is possible to drive the $\overline{\text{VSYNC}}$ input low for 2.5 lines in PAL mode and three lines in NTSC mode. When this bit is enabled in Master Mode the ADV7194 outputs an active low $\overline{\text{VSYNC}}$ signal for three lines in NTSC mode and 2.5 lines in PAL mode.

Genlock Control (MR41-MR42)

These bits control the Genlock feature and timing reset of the ADV7194 Setting MR41 and MR42 to Logic 0 disables the SCRESET/RTC/TR pin and allows the ADV7194 to operate in normal mode.

- 1. By setting MR41 to zero and MR42 to one, a timing reset is applied, resetting the horizontal and vertical counters. This has the effect of resetting the Field Count to Field 0.
 - If the SCRESET/RTC/TR pin is held high, the counters will remain reset. Once the pin is released the counters will commence counting again. For correct counter reset, the SCRESET/RTC/TR pin has to remain high for at least 37 ns (one clock cycle at 27 MHz).
- If MR41 is set to one and MR42 is set to zero, the SCRESET/ RTC/TR pin is configured as a subcarrier reset input and the subcarrier phase will reset to Field 0 whenever a low-tohigh transition is detected on the SCRESET/RTC/TR pin (SCH phase resets at the start of the next field).
- 3. If MR41 is set to one and MR42 is set to one, the SCRESET/RTC/TR pin is configured as a real time control input and the ADV7194 can be used to lock to an external video source working in RTC mode. See Figure 37.

Active Video Line Duration Control (MR43)

This bit switches between two active video line durations. A zero selects CCIR Rec. 601 (720 pixels PAL/NTSC) and a one selects ITU-R BT. 470 standard for active video duration (710 pixels NTSC, 702 pixels PAL).

Chrominance Control (MR44)

This bit enables the color information to be switched on and off the chroma, color component, composite video outputs.

Burst Control (MR45)

This bit enables the color burst to be switched on and off the chroma and composite video outputs.

Color Bar Control (MR46)

This bit can be used to generate and output an internal color bar test pattern. The color bar configuration is 100/7.5/75/7.5 for NTSC and 100/0/75/0 for PAL. It is important to note that when color bars are enabled the ADV7194 is configured in a Master Timing mode. The output pins \overline{VSYNC} , \overline{HSYNC} and \overline{BLANK} are three-state during color bar mode.

Interlaced Mode Control (MR47)

This bit is used to setup the output to interlaced or noninterlaced mode.

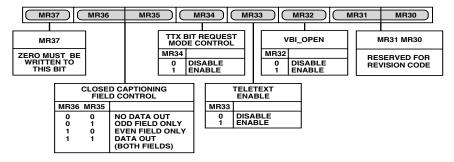


Figure 58. Mode Register 3, MR3

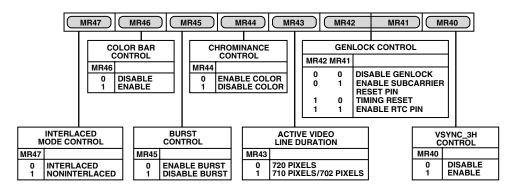


Figure 59. Mode Register 4, MR4

MODE REGISTER 5 MR5 (MR57-MR50)

(Address (SR4-SR0) = 05H)

Mode Register 5 is an 8-bit-wide register. Figure 60 shows the various operations under the control of Mode Register 5.

MR5 BIT DESCRIPTION

Y-Level Control (MR50)

This bit controls the component Y output level on the ADV7194. If this bit is set (0), the encoder outputs Betacam levels when configured in PAL or NTSC mode. If this bit is set (1), the encoder outputs SMPTE levels when configured in PAL or NTSC mode.

UV-Level Control (MR51-MR52)

These bits control the component U and V output levels on the ADV7194. It is possible to have UV levels with a peak-topeak amplitude of either 700 mV (MR52 + MR51 = 01) or 1000 mV (MR52 + MR51 = 10) in NTSC and PAL. It is also possible to have default values of 934 mV for NTSC and 700 mV for PAL (MR52 + MR51 = 00).

RGB Sync (MR53)

This bit is used to set up the RGB outputs with the sync information encoded on all RGB outputs.

Clamp Delay (MR54-MR55)

These bits control the delay or advance of the CLAMP signal in the front or back porch of the ADV7194. It is possible to delay or advance the pulse by zero, one, two, or three clock cycles.

Note: TTX functionality is shared with $\overline{\text{VSO}}$ and CLAMP on Pin 62. CLAMP/VSO Select (MR77) and TTX Input/CLAMP/VSO Output (MR76) have to be set accordingly.

Clamp Delay Direction (MR56)

This bit controls a positive or negative delay in the CLAMP signal. If this bit is set (1), the delay is negative. If it is set (0), the delay is positive.

Clamp Position (MR57)

This bit controls the position of the CLAMP signal. If this bit is set (1), the CLAMP signal is located in the back porch position. If this bit is set (0), the CLAMP signal is located in the front porch position.

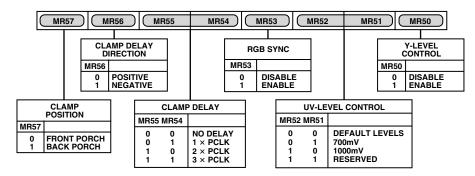


Figure 60. Mode Register 5, MR5

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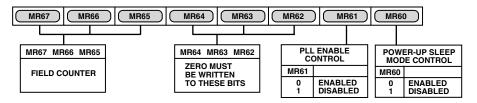


Figure 61. Mode Register 6, MR6

MODE REGISTER 6 MR6 (MR67-MR60) (ADDRESS (SR4-SR0) = 06H)

Mode Register 6 is an 8-bit-wide register. Figure 61 shows the various operations under the control of Mode Register 6.

MR6 BIT DESCRIPTION

Power-Up Sleep Mode Control (MR60)

After \overline{RESET} is applied this control is enabled (MR60 = 0) if both SCRESET/RTC/TR and NTSC_PAL pins are tied high. The ADV7194 will then power up in Sleep Mode to facilitate low power consumption before the I²C is initialized. When this control is disabled (MR60 = 1, via the I²C) Sleep Mode control passes to Sleep Mode Control, MR27.

PPL Enable Control (MR61)

The PLL control should be enabled (MR61 = 0) when $4\times$ Oversampling is enabled (MR16 = 1). It is also used to reset the PLL when this bit is toggled.

Reserved (MR62, MR63, MR64)

A Logic 0 must be written to these bits.

Field Counter (MR65, MR66, MR67)

These three bits are read-only bits. The field count can be read back over the I²C interface. In NTSC mode the field count goes from 0–3, in PAL Mode from 0–7.

MODE REGISTER 7 MR7 (MR77-MR70)

(Address (SR4-SR0) = 07H)

Mode Register 7 is an 8-bit-wide register. Figure 62 shows the various operations under the control of Mode Register 7.

MR7 BIT DESCRIPTION

Color Control Enable (MR70)

This bit is used to enable control of contrast and saturation of color. If this bit is set (1) color controls are enabled (Contrast Control, U-Scale, V-Scale Registers). If this bit is set (0), the color control features are disabled.

Luma Saturation Control (MR71)

When this bit is set (1), the luma signal will be clipped if it reaches a limit that corresponds to an input luma value of 255 (after scaling by the Contrast Control Register). This prevents the

chrominance component of the composite video signal being clipped if the amplitude of the luma is too high. When this bit is set (0), this control is disabled.

Hue Adjust Control (MR72)

This bit is used to enable hue adjustment on the composite and chroma output signals of the ADV7194. When this bit is set (1), the hue of the color is adjusted by the phase offset described in the Hue Adjust Control Register. When this bit is set (0), hue adjustment is disabled.

Brightness Enable Control (MR73)

This bit is used to enable brightness control on the ADV7194. The actual brightness level is programmed in the Brightness Control Register. This value or set-up level is added to the scaled Y data. When this bit is set (1), brightness control is enabled. When this bit is set (0), brightness control is disabled.

Sharpness Filter Enable (MR74)

This bit is used to enable the sharpness control of the luminance signal on the ADV7194 (Luma Filter Select has to be set to Extended, MR04–MR02 = 100). The various responses of the filter are determined by the Sharpness Control Register. When this bit is set 1, the luma response is altered by the amount described in the Sharpness Control Register. When this bit is set 0, the sharpness control is disabled. See Internal Filter Response section.

CSO_HSO Output Control (MR75)

This bit is used to determine whether \overline{HSO} or \overline{CSO} TTL output signal is output at the $\overline{CSO_HSO}$ pin. If this bit is set 1, then the \overline{CSO} TTL signal is output. If this bit is set 0, the \overline{HSO} TTL signal is output.

TTX Input/ CLAMP-VSO Output Control (MR76)

This bit controls whether Pin 62 is configured as an output or as an input pin. A 1 selects Pin 62 to be an output for CLAMP or VSO functionality. A 0 selects this pin as a TTX input pin.

CLAMP/VSO Select Control (MR77)

This bit is used to select the functionality of Pin 62. Setting this bit to 1 selects CLAMP as the output signal. A 0 selects $\overline{\text{VSO}}$ as the output signal. Since this pin is also shared with the TTX functionality, TTX Input/ CLAMP– $\overline{\text{VSO}}$ Output has to be set accordingly (MR76).

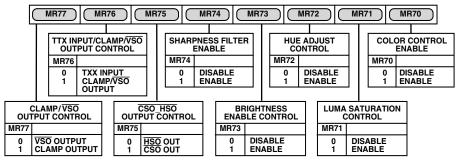


Figure 62. Mode Register 7, MR7

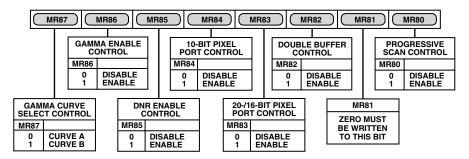


Figure 63. Mode Register 8, MR8

MODE REGISTER 8

MR8 (MR87-MR80)

(Address (SR4-SR0) = 08H)

Mode Register 8 is an 8-bit-wide register. Figure 63 shows the various operations under the control of Mode Register 8.

MR8 BIT DESCRIPTION

Progressive Scan Control (MR80)

This control enables the progressive scan inputs, Y0–Y9, Cr0–Cr9, Cb0–Cb9. To enable this control MR80 has to be set to 1. It is assumed that the incoming Y data contains all necessary sync information.

Note: Simultaneous progressive scan input and 16-bit pixel input is not possible.

10-Bit Pixel Port (MR84)

This bit selects 8-bit or 10-bit input format. In 8-bit mode, the LSB of the pixel data is input on Pin 3, in 10-bit mode, on Pin 1.

Double Buffer Control (MR82)

Double Buffering can be enabled or disabled on the Contrast Control Register, U Scale Register, V Scale Register, Hue Adjust Control, Closed Captioning Register, Brightness Control Register, Gamma Curve Select Bit. Double Buffering is not available in Mastering Timing mode.

20-, 16-Bit Pixel Port (MR83)

This bit controls whether the ADV7194 is operated in 16-bit mode (10-Bit Pixel Port disabled, MR84 = 0, MR83 = 1) or 20-bit mode (10-Bit Pixel Port enabled, MR84 = 1, MR83 = 1). The 16-bit mode, the first 8 bits are input on Pin Numbers 3 to 10, with LSB on Pin Number 3. The last 8 bits are input on Pin Numbers 13 to 20. Pin Numbers 11 and 12 are unused.

10-Bit Pixel Port (MR84)

This bit selects 8-bit or 10-bit format. In 8-bit mode, the LSB of the pixel data is input on Pin 3, in 10-bit mode on Pin 1.

DNR Enable Control (MR85)

To enable the DNR process this bit has to be set to 1. If this bit is set to 0, the DNR processing is bypassed. For further information on DNR controls see the DNR Bit Description section.

Gamma Enable Control (MR86)

To enable the programmable gamma correction this bit has to be set to enabled (MR86 = 1). For further information on Gamma Correction controls see the Gamma Correction Registers section.

Gamma Curve Select Control (MR87)

This bit selects which of the two programmable gamma curves is to be used. When setting MR87 to 0, the gamma correction curve selected is Curve A. Otherwise, Curve B is selected. Each curve

will have to be programmed by the user. For further information on Gamma Correction controls see DNR Bit Description and Gamma Correction sections.

MODE REGISTER 9

MR9 (MR97-MR90)

(Address (SR4-SR0) = 09H)

Mode Register 9 is an 8-bit-wide register. Figure 65 shows the various operations under the control of Mode Register 9.

MR9 BIT DESCRIPTION

Undershoot Limiter (MR90-MR91)

This control ensures that no luma video data will go below a programmable level. This prevents any synchronization problems due to luma signals going below the blanking level. Available limit levels are -1.5 IRE, -6 IRE, -11 IRE. Note that this facility is only available in 4× Oversampling mode (MR16 = 1). When the device is operated in 2× Oversampling mode (MR16 = 0), or RGB output without RGB sync is selected, the minimum luma level is set in Timing Register 0, TR06 (Min Luma Control).

Black Burst Y-DAC (MR92)

It is possible to output a Black Burst signal from the DAC which is selected to be the Luma DAC (MR22, MR21, MR20). When this control is set to enabled, MR92 is set to 1. This signal can be useful for locking two video sources together using professional video equipment. See also the Black Burst Output section.

Black Burst Luma-DAC (MR93)

It is possible to output a Black Burst signal from the DAC which is selected to be the Y-DAC (MR22, MR21, MR20). When this control is set to enabled, MR93 set to 1. This signal can be useful for locking two video sources together using professional video equipment. See also the Black Burst Output section.

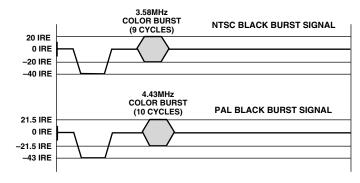


Figure 64. Black Burst Signals for PAL and NTSC Standards

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Figure 65. Mode Register 9, MR9

Chroma Delay Control (MR95-MR97)

The Chroma signal can be delayed by up to eight clock cycles at 27 MHz using MR94–95. For further information see also the Chroma/Luma Delay section.

TIMING REGISTER 0 (TR07-TR00)

(Address (SR4-SR0) = 0AH)

Figure 66 shows the various operations under the control of Timing Register 0. This register can be read from as well as written to.

TR0 BIT DESCRIPTION

Master/Slave Control (TR00)

This bit controls whether the ADV7194 is in master or slave mode.

Timing Mode Selection (TR01-TR02)

These bits control the timing mode of the ADV7194. These modes are described in more detail in the Timing and Control section of the data sheet.

BLANK Input Control (TR03)

This bit controls whether the \overline{BLANK} input is used to accept blank signals or whether blank signals are internally generated.

Note: When this input pin is tied high (to 5 V), the input is disabled regardless of the register setting. It, therefore, should be tied low (to Ground) to allow control over the I²C register.

Luma Delay (TR04-TR05)

The luma signal can be delayed by up to 222 ns (or six clock cycles at 27 MHz) using TR04–05. For further information see Chroma/Luma Delay section.

Min Luminance Value (TR06)

This bit is used to control the minimum luma output value by the ADV7194. When this bit is set to a Logic 1, the luma is limited to 7IRE below the blank level. When this bit is set to (0), the luma value can be as low as the sync bottom level.

Timing Register Reset (TR07)

Toggling TR07 from low to high and low again resets the internal timing counters. This bit should be toggled after power-up, reset or changing to a new timing mode.

TIMING REGISTER 1 (TR17-TR10)

(Address (SR4-SR0) = 0BH)

Timing Register 1 is an 8-bit-wide register.

Figure 67 shows the various operations under the control of Timing Register 1. This register can be read from as well written to. This register can be used to adjust the width and position of the master mode timing signals.

TR1 BIT DESCRIPTION

HSYNC Width (TR10-TR11)

These bits adjust the HSYNC pulsewidth.

 T_{PCLK} = one clock cycle at 27 MHz.

HSYNC to VSYNC Delay Control (TR13-TR12)

These bits adjust the position of the \overline{HSYNC} output relative to the VSYNC output.

 T_{PCLK} = one clock cycle at 27 MHz.

HSYNC to VSYNC Rising Edge Control (TR14-TR15)

When the ADV7194 is in Timing Mode 1, these bits adjust the position of the HSYNC output relative to the VSYNC output rising edge.

 T_{PCLK} = one clock cycle at 27 MHz.

VSYNC Width (TR14-TR15)

When the ADV7194 is configured in Timing Mode 2, these bits adjust the $\overline{\text{VSYNC}}$ pulsewidth.

 T_{PCLK} = one clock cycle at 27 MHz.

HSYNC to Pixel Data Adjust (TR16-TR17)

This enables the HSYNC to be adjusted with respect to the pixel data. This allows the Cr and Cb components to be swapped. This adjustment is available in both master and slave timing modes.

 T_{PCLK} = one clock cycle at 27 MHz.

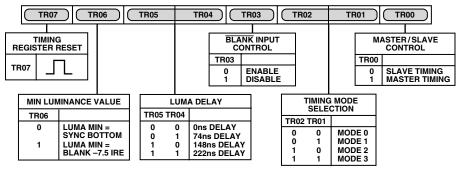


Figure 66. Timing Register 0

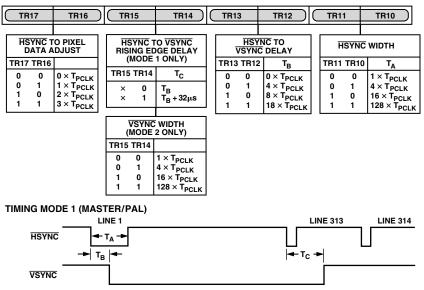


Figure 67. Timing Register 1

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SUBCARRIER FREQUENCY REGISTERS 3-0 (FSC31-FSC0) (Address (SR4-SR0) = 0CH-0FH)

These 8-bit-wide registers are used to set up the Subcarrier Frequency. The value of these registers are calculated by using the following equation:

$$Subcarrier\ Frequency\ Register = \frac{\left(2^{32}-1\right)\times f_{SCF}}{f_{CLK}}$$

Example: NTSC Mode, $f_{CLK} = 27$ MHz, $f_{SCF} = 3.5795454$ MHz

Subcarrier Frequency Value =
$$\frac{\left(2^{32} - 1\right) \times 3.5795454 \times 10^{6}}{27 \times 10^{6}}$$

Subcarrier Register Value = 21F07C16 Hex

Figure 68 shows how the frequency is set up by the four registers.

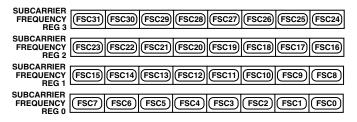


Figure 68. Subcarrier Frequency Registers

SUBCARRIER PHASE REGISTER (FPH7-FPH0) (Address (SR4-SR0) = 10H)

This 8-bit-wide register is used to set up the Subcarrier Phase. Each bit represents 1.41°. For normal operation this register is set to 00Hex.



Figure 69. Subcarrier Phase Register

CLOSED CAPTIONING EVEN FIELD DATA REGISTER 1-0 (CCD15-CCD00) (Address (SR4-SR0) = 11-12H)

These 8-bit-wide registers are used to set up the closed captioning extended data bytes on Even Fields. Figure 70 shows how the high and low bytes are set up in the registers.

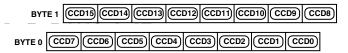


Figure 70. Closed Captioning Extended Data Register

CLOSED CAPTIONING ODD FIELD DATA REGISTER 1-0 (CCD15-CCD0)

(Subaddress (SR4-SR0) = 13-14H)

These 8-bit-wide registers are used to set up the closed captioning data bytes on Odd Fields. Figure 71 shows how the high and low bytes are set up in the registers.

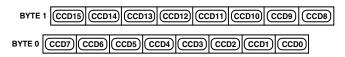


Figure 71. Closed Captioning Data Register

NTSC PEDESTAL/PAL TELETEXT CONTROL REGISTERS 3-0

(PCE15-0, PCO15-0)/(TXE15-0, TXO15-0) (Subaddress (SR4-SR0) = 15-18H)

These 8-bit-wide registers are used to enable the NTSC pedestal/PAL Teletext on a line by line basis in the vertical blanking interval for both odd and even fields. Figures 68 and 69 show the four control registers. A Logic 1 in any of the bits of these registers has the effect of turning the Pedestal OFF on the equivalent line when used in NTSC. A Logic 1 in any of the bits of these registers has the effect of turning Teletext ON on the equivalent line when used in PAL.

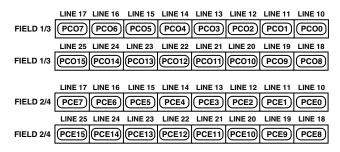


Figure 72. Pedestal Control Registers

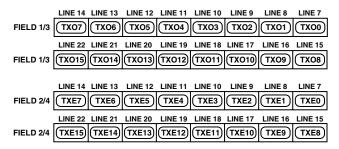


Figure 73. Teletext Control Registers

TELETEXT REQUEST CONTROL REGISTER TC07 (TC07-TC00)

(Address (SR4-SR0) = 1CH)

Teletext Control Register is an 8-bit-wide register. See Figure 74.

TTXREQ Falling Edge Control (TC00-TC03)

These bits control the position of the falling edge of TTXREQ. It can be programmed from zero clock cycles to a maximum of 15 clock cycles. This controls the active window for Teletext data. Increasing this value reduces the amount of Teletext bits below the default of 360. If Bits TC00–TC03 are 00Hex when Bits TC04–TC07 are changed then the falling edge of TTREQ will track that of the rising edge (i.e., the time between the falling and rising edge remains constant).

PCLK = clock cycle at 27 MHz.

TTXREQ Rising Edge Control (TC04-TC07)

These bits control the position of the rising edge of TTXREQ. It can be programmed from zero clock cycles to a maximum of 15 clock cycles.

PCLK = clock cycle at 27 MHz.

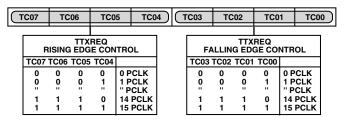


Figure 74. Teletext Control Register

CGMS_WSS REGISTER 0 C/W0 (C/W07-C/W00) (Address (SR4-SR0) = 19H)

CGMS_WSS register 0 is an 8-bit-wide register. Figure 71 shows the operations under control of this register.

C/W0 BIT DESCRIPTION

CGMS Data (C/W00-C/W03)

These four data bits are the final four bits of CGMS data output stream. Note it is CGMS data ONLY in these bit positions, i.e., WSS data does not share this location.

CGMS CRC Check Control (C/W04)

When this bit is enabled (1), the last six bits of the CGMS data, i.e., the CRC check sequence, is internally calculated by the ADV7194. If this bit is disabled (0), the CRC values in the register are output to the CGMS data stream.

CGMS Odd Field Control (C/W05)

When this bit is set (1), CGMS is enabled for odd fields. Note this is only valid in NTSC mode.

CGMS Even Field Control (C/W06)

When this bit is set (1), CGMS is enabled for even fields. Note this is only valid in NTSC mode.

WSS Control (C/W07)

When this bit is set (1), wide screen signalling is enabled. Note this is only valid in PAL mode.

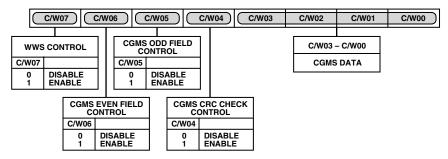


Figure 75. CGMS_WSS Register 0

CGMS_WSS REGISTER 1 C/W1 (C/W17-C/W10) (Address (SR4-SR0) = 1AH)

CGMS_WSS register 1 is an 8-bit-wide register. Figure 76 shows the operations under control of this register.

C/W1 BIT DESCRIPTION

CGMS/WSS Data (C/W10-C/W15)

These bit locations are shared by CGMS data and WSS data. In NTSC mode these bits are CGMS data. In PAL mode these bits are WSS data.

CGMS Data (C/W16-C/W17)

These bits are CGMS data bits only.

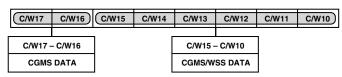


Figure 76. CGMS_WSS Register 1

CGMS WSS REGISTER 2

C/W1 (C/W27-C/W20)

(ADDRESS (SR4-SR0) = 1BH)

CGMS_WSS Register 2 is an 8-bit-wide register. Figure 77 shows the operations under control of this register.

C/W2 BIT DESCRIPTION

CGMS/WSS Data (C/W20-C/W27)

These bit locations are shared by CGMS data and WSS data. In NTSC mode these bits are CGMS data. In PAL mode these bits are WSS data.

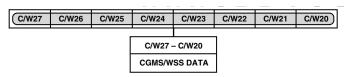


Figure 77. CGMS_WSS Register 2

CONTRAST CONTROL REGISTER (CC00-CC07) (Address (SR4-SR0) = 1DH)

The contrast control register is an 8-bit-wide register used to scale the Y output levels. Figure 78 shows the operation under control of this register.

Y Scale Value (CC00-CC07)

These eight bits represent the value required to scale the Y pixel data from 0.0 to 1.5 of its initial level. The value of these eight bits is calculated using the following equation:

Y Scale Value = Scale Factor \times 128

Example:

Scale Factor = 1.18

Y Scale Value = $1.18 \times 128 = 151.04$

Y Scale Value = 151 (rounded to the nearest integer)

Y Scale Value = 10010111_b

Y Scale Value = 97_h

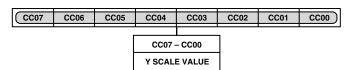


Figure 78. Contrast Control Register

COLOR CONTROL REGISTERS 1-2 (CC10-CC27) (Address (SR4-SR0) = 1EH-1FH)

The color control registers are 8-bit-wide registers used to scale the U and V output levels. Figure 79 shows the operations under control of these registers.

CC1 BIT DESCRIPTION

U Scale Value (CC10-CC17)

These eight bits represent the value required to scale the U level from 0.0 to 2.0 of its initial level. The value of these eight bits is calculated using the following equation:

U Scale Value = Scale Factor \times 128

Example:

Scale Factor = 1.18

U Scale Value = $1.18 \times 128 = 151.04$

U Scale Value = 151 (rounded to the nearest integer)

U Scale Value = 10010111_b

U Scale Value = 97_h

CC2 BIT DESCRIPTION

V Scale Value (CC20-CC27)

These eight bits represent the value required to scale the V pixel data from 0.0 to 2.0 of its initial level. The value of these eight bits is calculated using the following equation:

V Scale Value = Scale Factor \times 128

Example:

Scale Factor = 1.18

V Scale Value = $1.18 \times 128 = 151.04$

V Scale Value = 151 (rounded to the nearest integer)

V Scale Value = 10010111_b

V Scale Value = 97_h

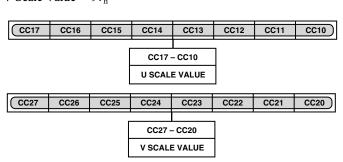


Figure 79. Color Control Register

HUE ADJUST CONTROL REGISTER (HCR) (Address (SR5-SR0) = 20H)

The hue control register is an 8-bit-wide register used to adjust the hue on the composite and chroma outputs. Figure 80 shows the operation under control of this register.

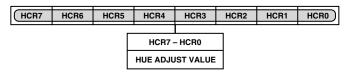


Figure 80. Hue Adjust Control Register

HCR BIT DESCRIPTION

Hue Adjust Value (HCR0-HCR7)

These eight bits represent the value required to vary the hue of the video data, i.e., the variance in phase of the subcarrier during active video with respect to the phase of the subcarrier during the colorburst. The ADV7194 provides a range of $\pm 22.5^{\circ}$ increments of 0.17578125°. For normal operation (zero adjustment) this register is set to 80Hex. FFHex and 00Hex represent the upper and lower limit (respectively) of adjustment attainable.

Hue Adjust [°] = 0.17578125° × (HC R_d – 128); for positive Hue Adjust Value

Example:

To adjust the hue by $+4^{\circ}$ write 97_h to the Hue Adjust Control Register:

$$(4/0.17578125) + 128 = 151_d^* = 97_h$$

To adjust the hue by (-4°) write 69_h to the Hue Adjust-Control – Register:

$$(-4/0.17578125) + 128 = 105_d^* = 69_h$$

BRIGHTNESS CONTROL REGISTERS (BCR) (Address (SR5-SR0) = 21H)

The brightness control register is an 8-bit-wide register which allows brightness control. Figure 81 shows the operation under control of this register.

BCR BIT DESCRIPTION

Brightness Value (BCR0-BCR6)

Seven bits of this 8-bit-wide register are used to control the brightness level. The brightness is controlled by adding a programmable setup level onto the scaled Y data. This brightness level can be a positive or negative value.

The programmable brightness levels in NTSC without pedestal and PAL are max 15 IRE and min -7.5 IRE, in NTSC with pedestal max 22.5 IRE and min 0 IRE.

Table VI. Brightness Control Register Value

Setup Level in NTSC with Pedestal	Setup Level in NTSC No Pedestal	Setup Level in PAL	Brightness Control Register Value	
22.5 IRE	15 IRE	15 IRE	$1E_h \\ 0F_h \\ 00_h \\ 71_h$	
15 IRE	7.5 IRE	7.5 IRE		
7.5 IRE	0 IRE	0 IRE		
0 IRE	–7.5 IRE	-7.5 IRE		

NOTE

Values in the range from $3F_{\text{h}}$ to 44_{h} might result in an invalid output signal.

EXAMPLE

1. Standard: NTSC with Pedestal. To add +20 IRE brightness level, write 28_H into the Brightness Control Register:

[Brightness Control Register Value]_h = [IRE Value \times 2.015631]_h = [20 \times 2.015631]_h = [40.31262]_h = 28_h

2. Standard: PAL. To add -7 IRE brightness level write 72h into the Brightness Control Register:

$$[|IRE\ Value| \times 2.015631] = [7 \times 2.015631] = [14.109417] = 0001110_b$$

 $[0001110]\ into\ two's\ complement = 1110010_b = 72_b$

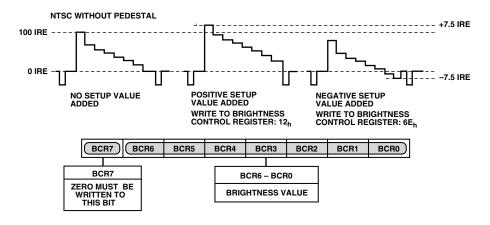


Figure 81. Brightness Control Register

^{*}Rounded to the nearest integer.

SHARPNESS RESPONSE REGISTER (PR) (Address (SR5-SR0) = 22H)

The sharpness response register is an 8-bit-wide register. The four MSBs are set to 0. The four LSBs are written to in order to select a desired filter response. Figure 82 shows the operation under control of this register.

PR BIT DESCRIPTION

Sharpness Response Select Value (PR3-PR0)

These four bits are used to select the desired luma filter response. The option of twelve responses is given supporting a gain boost/ attenuation in the range –4 dB to +4 dB. The value 12 (1100) written to these four bits corresponds to a boost of +4 dB while the value 0 (0000) corresponds to –4 dB. For normal operation these four bits are set to 6 (0110). Note: Luma Filter Select has to be set to Extended Mode and Sharpness Filter Control has to be enabled for settings in the Sharpness Response Register to take effect (MR02–04 = 100; MR74 = 1).

Reserved (PR4-PR7)

A Logic 0 must be written to these bits.

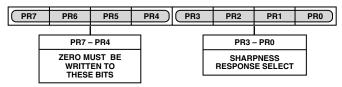


Figure 82. Sharpness Response Register

DNR REGISTERS 2-0 (DNR 2-DNR 0)

(Address (SR5-SR0) = 23H-25H)

The Digital Noise Reduction Registers are three 8-bit-wide register. They are used to control the DNR processing. See also the Functional Description section.

Coring Gain Border (DNR00-DNR03)

These four bits are assigned to the gain factor applied to border areas.

In DNR Mode the range of gain values is 0–1, in increments of 1/8. This factor is applied to the DNR filter output which lies below the set threshold range. The result is then subtracted from the original signal.

In DNR Sharpness Mode the range of gain values is 0–0.5, in increments of 1/16. This factor is applied to the DNR filter output which lies above the threshold range.

The result is added to the original signal.

Coring Gain Data (DNR04-DNR07)

These four bits are assigned to the gain factor applied to the luma data inside the MPEG pixel block.

In DNR Mode the range of gain values is 0–1, in increments of 1/8. This factor is applied to the DNR filter output which lies below the set threshold range. The result is then subtracted from the original signal.

In DNR Sharpness Mode the range of gain values is 0–0.5, in increments of 1/16. This factor is applied to the DNR filter output which lies above the threshold range. The result is added to the original signal.

Figures 79 and 80 show the various operations under the control of DNR Register 0.

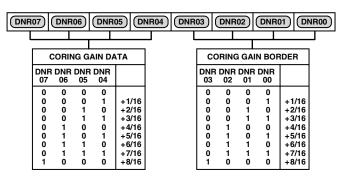


Figure 83. DNR Register 0 in Sharpness Mode

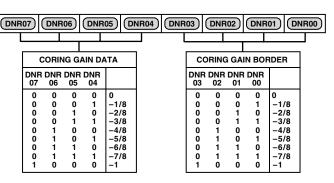


Figure 84. DNR Register 0 in DNR Mode

DNR1 BIT DESCRIPTION

DNR Threshold (DNR10-DNR15)

These six bits are used to define the threshold value in the range of 0 to 63. The range is an absolute value.

Border Area (DNR16)

In setting DNR16 to a Logic 1 the block transition area can be defined to consist of four pixels. If this bit is set to a Logic 0 the border transition area consists of two pixels, where one pixel refers to two clock cycles at 27 MHz.

Block Size Control (DNR17)

This bit is used to select the size of the data blocks to be processed (see Figure 85). Setting the block size control function to a Logic 1 defines a 16×16 pixel data block, a Logic 0 defines an 8×8 pixel data block, where one pixel refers to two clock cycles at 27 MHz.

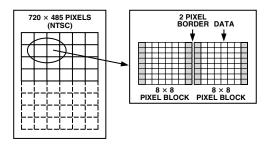


Figure 85. MPEG Block Diagram

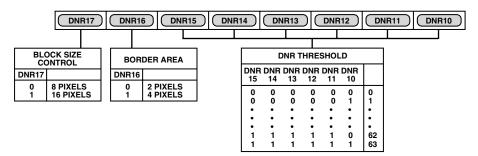


Figure 86. DNR Register 1

DNR2 BIT DESCRIPTION DNR Input Select (DNR20-DNR22)

Three bits are assigned to select the filter which is applied to the incoming Y data. The signal which lies in the passband of the selected filter is the signal which will be DNR processed. Figure 87 shows the filter responses selectable with this control.

DNR Mode Control (DNR23)

This bit controls the DNR mode selected. A Logic 0 selects DNR mode, a Logic 1 selects DNR Sharpness mode.

DNR works on the principle of defining low amplitude, high-frequency signals as probable noise and subtracting this noise from the original signal.

In DNR mode, it is possible to subtract a fraction of the signal which lies below the set threshold, assumed to be noise, from the original signal. The threshold is set in DNR Register 1.

When DNR Sharpness mode is enabled it is_possible_to add a_fraction of the signal which lies above the set threshold to the original signal, since this data is assumed to be valid data and not noise. The overall effect being that the signal will be boosted (similar to using Extended SSAF Filter).

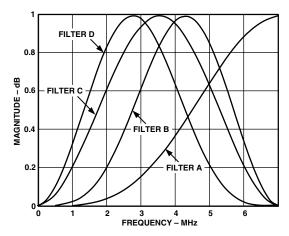
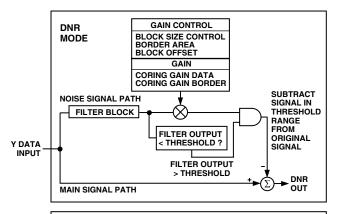


Figure 87. Filter Response of Filters Selectable



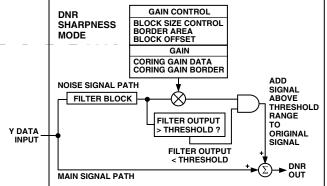


Figure 88. Block Diagram for DNR Mode and DNR Sharpness Mode

Block Offset (DNR24-DNR27)

Four bits are assigned to this control which allows a shift of the data block of 15 pixels maximum. Consider the coring gain positions fixed. The block offset shifts the data in steps of one pixel such that the border coring gain factors can be applied at the same position regardless of variations in input timing of the data.

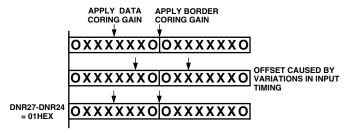


Figure 89.

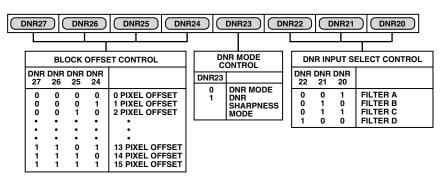


Figure 90. DNR Register 2

GAMMA CORRECTION REGISTERS 0-13 (GAMMA CORRECTION 0-13)

(Address (SR5-SR0) = 26H-32H)

The Gamma Correction Registers are fourteen 8-bit-wide registers. They are used to program the gamma correction Curves A and B.

Generally gamma correction is applied to compensate for the nonlinear relationship between signal input and brightness level output (as perceived on the CRT). It can also be applied wherever nonlinear processing is used.

Gamma correction uses the function:

$$Signal_{OUT} = (Signal_{IN})^{\gamma}$$

where

$$\gamma = gamma power factor$$

Gamma correction is performed on the luma data only. The user has the choice to use two different curves, Curve A or Curve B. At any one time only one of these curves can be used.

The response of the curve is programmed at seven predefined locations. In changing the values at these locations the gamma curve can be modified. Between these points linear interpolation is used to generate intermediate values. Considering the curve to have a total length of 256 points, the seven locations are at: 32, 64, 96, 128, 160, 192, and 224.

Location 0, 16, 240 and 255 are fixed and can not be changed.

For the length of 16 to 240 the gamma correction curve has to be calculated as below:

$$y = x^{\gamma}$$

where

y = gamma corrected output

x = linear input signal

 γ = gamma power factor

To program the gamma correction registers, the seven values for y have to be calculated using the following formula:

$$y_n = [x_{(n-16)}/(240-16)]^{\gamma} \times (240-16) + 16$$

where

 $x_{(n-16)}$ = Value for x along x-axis at points n = 32, 64, 96, 128, 160, 192 or 224

 y_n = Value for y along the y-axis, which has to be written into the gamma correction register

Example:

$$y_{32} = [(16/224)^{0.5} \times 224] + 16 = 76*$$
 $y_{64} = [(48/224)^{0.5} \times 224] + 16 = 120*$
 $y_{96} = [(80/224)^{0.5} \times 224] + 16 = 150*$
 $y_{128} = [(112/224)^{0.5} \times 224] + 16 = 174*$

*Rounded to the nearest integer.

The above will result in a gamma curve shown below, assuming a ramp signal as an input.

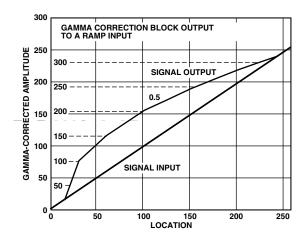


Figure 91. Signal Input (Ramp) and Signal Output for Gamma 0.5

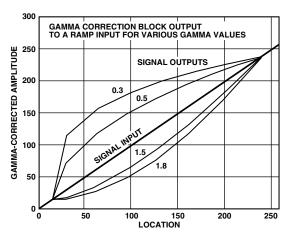


Figure 92. Signal Input (Ramp) and Selectable Gamma Output Curves

The gamma curves shown above are examples only, any user defined curve is acceptable in the range of 16–240.

BRIGHTNESS DETECT REGISTER

(Address (SR5-SR0) = 34H)

The Brightness Detect Register is an 8-bit-wide register used only to read back data in order to monitor the brightness/darkness of the incoming video data on a field-by-field basis. The brightness information is read from the I²C and based on this information, the color controls or the gamma correction controls may be adjusted.

The luma data is monitored in the active video area only. The average brightness I^2C register is updated on the falling edge of every \overline{VSYNC} signal.

OUTPUT CLOCK REGISTER (OCR9-0)

(Address (SR4-SR0) = 35H)

The Output Clock Register is an 8-bit-wide register. Figure 93 shows the various operations under the control of this register.

OCR BIT DESCRIPTION

Reserved (OCR00)

A Logic 0 must be written to this bit.

CLKOUT Pin Control (OCR01)

This bit enables the CLKOUT pin when set to 1 and, therefore, outputs a 54 MHz clock generated by the internal PLL. The PLL and $4\times$ Oversampling have to be enabled for this control to take effect, (MR61 = 0; MR16 = 1).

Reserved (OCR02-OCR03)

A Logic 0 must be written to these bits.

Reserved (OCR04-OCR06)

A Logic 1 must be written to these bits.

Reserved (OCR07)

A Logic 0 must be written to this bit.

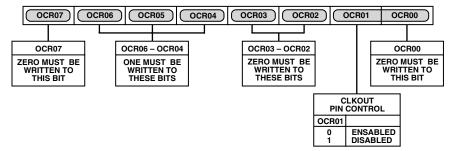


Figure 93. Mode Register 10 (MR10)

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APPENDIX 1

BOARD DESIGN AND LAYOUT CONSIDERATIONS

The ADV7194 is a highly integrated circuit containing both precision analog and high-speed digital circuitry. It has been designed to minimize interference effects on the integrity of the analog circuitry by the high-speed digital circuitry. It is imperative that these same design and layout techniques be applied to the system level design such that high-speed, accurate performance is achieved. The Recommended Analog Circuit Layout shows the analog interface between the device and monitor.

The layout should be optimized for lowest noise on the ADV7194 power and ground lines by shielding the digital inputs and providing good decoupling. The lead length between groups of V_{AA} , AGND, V_{DD} , and DGND pins should be minimized so as to minimize inductive ringing.

Ground Planes

The ground plane should encompass all ADV7194 ground pins, voltage reference circuitry, power supply bypass circuitry for the ADV7194, the analog output traces, and all the digital signal traces leading up to the ADV7194. This should be as substantial as possible to maximize heat spreading and power dissipation on the board.

Power Planes

The ADV7194 and any associated analog circuitry should have its own power plane, referred to as the analog power plane (V_{AA}). This power plane should be connected to the regular PCB power plane (V_{CC}) at a single point through a ferrite bead. This bead should be located within three inches of the ADV7194.

The metallization gap separating device power plane and board power plane should be as narrow as possible to minimize the obstruction to the flow of heat from the device into the general board.

The PCB power plane should provide power to all digital logic on the PC board, and the analog power plane should provide power to all ADV7194 power pins and voltage reference circuitry.

Plane-to-plane noise coupling can be reduced by ensuring that portions of the regular PCB power and ground planes do not overlay portions of the analog power plane, unless they can be arranged such that the plane-to-plane noise is common-mode.

Supply Decoupling

For optimum performance, bypass capacitors should be installed using the shortest leads possible, consistent with reliable operation, to reduce the lead inductance. Best performance is obtained with 0.1 μF ceramic capacitor decoupling. Each group of V_{AA} pins on the ADV7194 must have at least one 0.1 μF decoupling capacitor to AGND. The same applies to groups of V_{DD} and DGND. These capacitors should be placed as close as possible to the device.

It is important to note that while the ADV7194 contains circuitry to reject power supply noise, this rejection decreases with frequency. If a high frequency switching power supply is used, the designer should pay close attention to reducing power supply noise and consider using a three-terminal voltage regulator for supplying power to the analog power plane.

Digital Signal Interconnect

The digital inputs to the ADV7194 should be isolated as much as possible from the analog outputs and other analog circuitry. Also, these input signals should not overlay the analog power plane.

Due to the high clock rates involved, long clock lines to the ADV7194 should be avoided to reduce noise pickup.

Any active termination resistors for the digital inputs should be connected to the regular PCB power plane (V_{CC}), and not the analog power plane.

Analog Signal Interconnect

The ADV7194 should be located as close as possible to the output connectors to minimize noise pickup and reflections due to impedance mismatch.

The video output signals should overlay the ground plane, and not the analog power plane, to maximize the high frequency power supply rejection.

Digital inputs, especially pixel data inputs and clocking signals should never overlay any of the analog signal circuitry and should be kept as far away as possible.

For best performance, the outputs should each have a 300 Ω load resistor connected to AGND. These resistors should be placed as close as possible to the ADV7194 so as to minimize reflections.

The ADV7194 should have no inputs left floating. Any inputs that are not required should be tied to ground.

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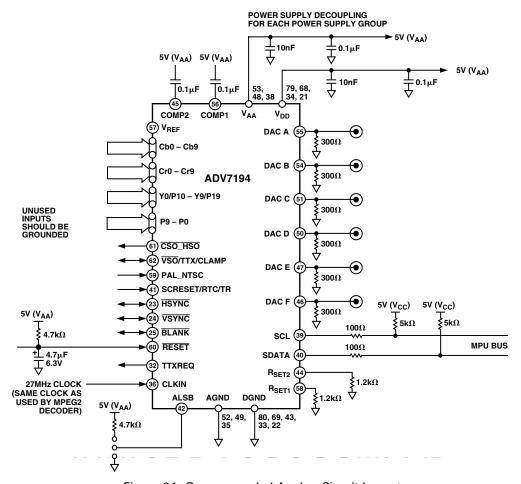


Figure 94. Recommended Analog Circuit Layout

APPENDIX 2 CLOSED CAPTIONING

The ADV7194 supports closed captioning conforming to the standard television synchronizing waveform for color transmission. Closed captioning is transmitted during the blanked active line time of Line 21 of the odd fields and Line 284 of even fields.

Closed captioning consists of a seven-cycle sinusoidal burst that is frequency and phase locked to the caption data. After the clock run-in signal, the blanking level is held for two data bits and is followed by a Logic Level 1 start bit. Sixteen bits of data follow the start bit. These consist of two eight-bit bytes, seven data bits, and one odd parity bit. The data for these bytes is stored in Closed Captioning Data Registers 0 and 1.

The ADV7194 also supports the extended closed captioning operation which is active during even fields and is encoded on Scan Line 284. The data for this operation is stored in Closed Captioning Extended Data Registers 0 and 1.

All clock run-in signals and timing to support Closed Captioning on Lines 21 and 284 are generated automatically by the ADV7194 All pixels inputs are ignored during Lines 21 and 284 if closed captioning is enabled.

FCC Code of Federal Regulations (CFR) 47 Section 15.119 and EIA608 describe the closed captioning information for Lines 21 and 284.

The ADV7194 uses a single buffering method. This means that the closed captioning buffer is only one byte deep, therefore, there will be no frame delay in outputting the closed captioning data unlike other two byte deep buffering systems. The data must be loaded one line before (Line 20 or Line 283) it is outputted on Line 21 and Line 284. A typical implementation of this method is to use \$\overline{VSYNC}\$ to interrupt a microprocessor, which in turn will load the new data (two bytes) every field. If no new data is required for transmission, 0s must be inserted in both data registers, this is called NULLING. It is also important to load control codes all of which are double bytes on Line 21 or a TV will not recognize them. If there is a message like Hello World which has an odd number of characters, it is important to pad it out to even in order to get end of caption 2-byte control code to land in the same field.

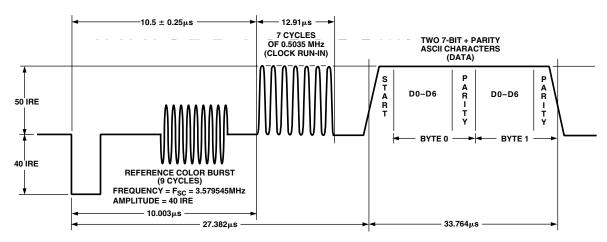


Figure 95. Closed Captioning Waveform (NTSC)

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COPY GENERATION MANAGEMENT SYSTEM (CGMS)

The ADV7194 supports Copy Generation Management System (CGMS) conforming to the standard. CGMS data is transmitted on Line 20 of the odd fields and Line 283 of even fields. Bits C/W05 and C/W06 control whether or not CGMS data is put out on ODD and EVEN fields. CGMS data can only be transmitted when the ADV7194 is configured in NTSC mode. The CGMS data is 20 bits long, the function of each of these bits is as shown below. The CGMS data is preceded by a reference pulse of the same amplitude and duration as a CGMS bit, see Figure 96. These bits are put out from the configuration registers in the following order: C/W00 = C16, C/W01 = C17, C/W02 =C18, C/W03 = C19, C/W10 = C8, C/W11 = C9, C/W12 =C10, C/W13 = C11, C/W14 = C12, C/W15 = C13, C/W16 =C14, C/W17 = C15, C/W20 = C0, C/W21 = C1, C/W22 = C2, C/W23 = C3, C/W24 = C4, C/W25 = C5, C/W26 = C6, C/W27= C7. If the bit C/W04 is set to a Logic 1, the last six bits C19-C14 which comprise the 6-bit CRC check sequence are calculated automatically on the ADV7194 based on the lower 14 bits (C0-C13) of the data in the data registers and output with the remaining 14 bits to form the complete 20 bits of the CGMS data. The calculation of the CRC sequence is based on the polynomial $X^6 + X + 1$ with a preset value of 111111. If C/W04 is set to a Logic 0 then all 20 bits (C0-C19) are output directly from the CGMS registers (no CRC calculated, must be calculated by the user).

Function of CGMS Bits

```
Word 0 – 6 Bits
Word 1 - 4 Bits
Word 2 – 6 Bits
CRC - 6 Bits CRC Polynomial = X^6 + X + 1 (Preset to
                                             111111)
WORD 0
                                                 0
                                   1
B1
                Aspect Ratio
                                   16:9
                                                 4:3
                Display Format
B2
                                  Letterbox
                                                 Normal
B3
                Undefined
WORD 0
B4, B5, B6
                Identification Information About Video and
                Other Signals (e.g., Audio)
WORD 1
B7, B8, B9,
                Identification Signal Incidental to Word 0
B10
WORD 2
B11, B12,
                Identification Signal and Information
B13, B14
                Incidental to Word 0
```

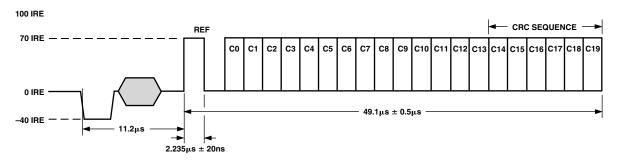


Figure 96. CGMS Waveform Diagram

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WIDE SCREEN SIGNALING

 $\mathbf{R}A$

The ADV7194 supports Wide Screen Signalling (WSS) conforming to the standard. WSS data is transmitted on Line 23. WSS data can only be transmitted when the ADV7194 is configured in PAL mode. The WSS data is 14 bits long, the function of each of these bits is as shown below. The WSS data is preceded by a run-in sequence and a Start Code, see Figure 97. The bits are output from the configuration registers in the following order: C/W20 = W0, C/W21 = W1, C/W22 = W2, C/W23 = W3, C/W24 = W4, C/W25 = W5, C/W26 = W6, C/W27 = W7, C/W10 = W8, C/W11 = W9, C/W12 = W10, C/W13 = W11, C/W14 = W12, C/W15 = W13. If the bit C/W07 is set to a Logic 1, it enables the WSS data to be transmitted on Line 23. The latter portion of Line 23 (42.5 µs from the falling edge of HSYNC) is available for the insertion of video.

Function of CGMS Bits

Bit 0-Bit 2

Bit 3			Is Odd Parity Check of Bit 0-Bit 2				
				Aspect	Format	Position	
В0,	B1,	B2,	B3	Ratio	Format	Position	
0	0	0	1	4:3	Full Format	Nonapplicable	
1	0	0	0	14:9	Letterbox	Center	
0	1	0	0	14:9	Letterbox	Top	
1	1	0	1	16:9	Letterbox	Center	
0	0	1	0	16:9	Letterbox	Top	
1	0	1	1	>16:9	Letterbox	Center	
0	1	1	1	14:9	Full Format	Center	
1	1	1	0	16:9	Nonapplicable	Nonapplicable	

Aspect Ratio/Format/Position

В4	
0	Camera Mode
1	Film Mode
B5	
0	Standard Coding
1	Motion Adaptive Color Plus
B6	
0	No Helper
1	Modulated Helper
B7	RESERVED
B9	B10
0	0 No Open Subtitles
1	0 Subtitles in Active Image Area
0	1 Subtitles Out of Active Image Area
1	1 RESERVED
B11	
0	No Surround Sound Information
1	Surround Sound Mode
B12	RESERVED
B13	RESERVED

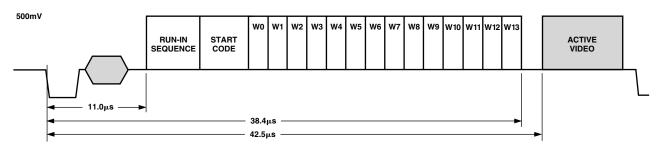


Figure 97. WSS Waveform Diagram

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TELETEXT INSERTION

Time, t_{PD} , is the time needed by the ADV7194 to interpolate input data on TTX and insert it onto the CVBS or Y outputs, such that it appears $T_{SYNTTXOUT} = 10.2 \,\mu s$ after the leading edge of the horizontal signal. Time TTX_{DEL} is the pipeline delay time by the source that is gated by the TTXREQ signal in order to deliver TTX data.

With the programmability that is offered with TTXREQ signal on the Rising/Falling edges, the TTX data is always inserted at the correct position of 10.2 µs after the leading edge of Horizontal Sync pulse, thus this enables a source interface with variable pipeline delays.

The width of the TTXREQ signal must always be maintained such that it allows the insertion of 360 (in order to comply with the Teletext Standard PAL-WST) teletext bits at a text data rate of 6.9375 Mbits/s, this is achieved by setting TC03–TC00 to 0. The insertion window is not open if the Teletext Enable bit (MR33) is set to 0.

Teletext Protocol

The relationship between the TTX bit clock (6.9375 MHz) and the system CLOCK (27 MHz) for 50 Hz is given as follows:

$$(27 MHz/4) = 6.75 MHz$$

 $(6.9375 \times 10^6/6.75 \times 10^6) = 1.027777$

Thus 37 TTX bits correspond to 144 clocks (27 MHz), each bit has a width of almost four clock cycles. The ADV7194 uses an internal sequencer and variable phase interpolation filter to minimize the phase jitter and thus generate a bandlimited signal which can be output on the CVBS and Y outputs.

At the TTX input the bit duration scheme repeats after every 37 TTX bits or 144 clock cycles. The protocol requires that TTX Bits 10, 19, 28, 37 are carried by three clock cycles, all other bits by four clock cycles. After 37 TTX bits, the next bits with three clock cycles are Bits 47, 56, 65, and 74. This scheme holds for all following cycles of 37 TTX bits, until all 360 TTX bits are completed. All teletext lines are implemented in the same way. Individual control of teletext lines are controlled by Teletext Setup Registers.

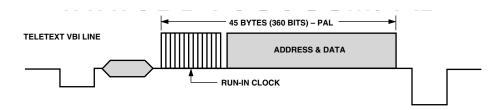
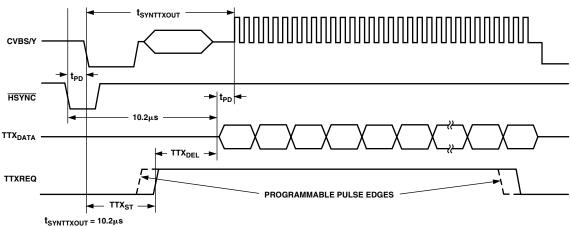


Figure 98. Teletext VBI Line



 $t_{SYNTTXOUT}$ = 10.2 μ s t_{PD} = PIPELINE DELAY THROUGH ADV7194 TTX_{DEL} = TTXREQ TO TTX (PROGRAMMABLE RANGE = 4 BITS [0–15 CLOCK CYCLES])

Figure 99. Teletext Functionality Diagram

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OPTIONAL OUTPUT FILTER

If an output filter is required for the CVBS, Y, UV, Chroma and RGB outputs of the ADV7194, the following filter in Figure 100 can be used in 2× Oversampling Mode. In 4× Oversampling Mode the filter in Figure 102 is recommended. The plot of the filter characteristics are shown in Figures 101 and 103. An output

filter is not required if the outputs of the ADV7194 are connected to most analog monitors or TVs, however, if the output signals are applied to a system where sampling is used (e.g., Digital TVs) then a filter is required to prevent aliasing.

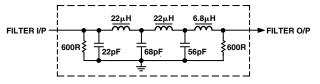


Figure 100. Output Filter for 2x Oversampling Mode

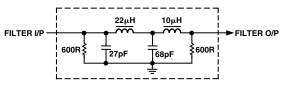


Figure 101. Output Filter for 4x Oversampling Mode

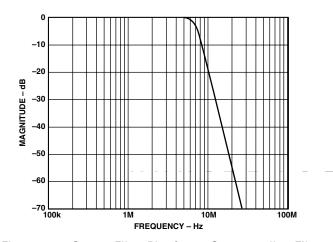


Figure 102. Output Filter Plot for 2x Oversampling Filter

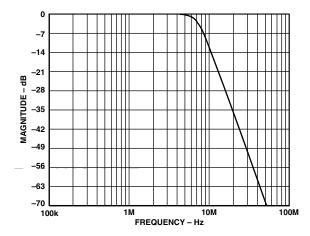


Figure 103. Output Filter Plot for 4× Oversampling Filter

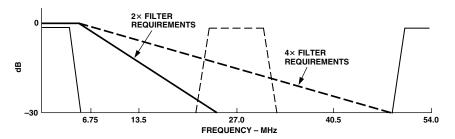


Figure 104. Output Filter Requirements in 4x Oversampling Mode

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DAC BUFFERING

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External buffering is needed on the ADV7194 DAC outputs. The configuration in Figure 105 is recommended.

When calculating absolute output full-scale current and voltage use the following equations:

$$V_{OUT} = I_{OUT} \times R_{LOAD}$$

$$I_{OUT} = (V_{REF} \times K)/R_{SET}$$

$$K = 4.2146 \ constant, \ V_{REF} = 1.235 \ V$$

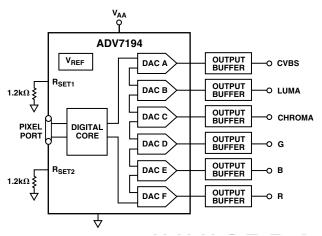


Figure 105. Output DAC Buffering Configuration

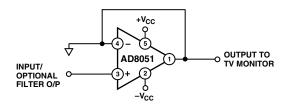


Figure 106. Recommended DAC Output Buffer Using an Op Amp

RECOMMENDED REGISTER VALUES

The ADV7194 registers can be set depending on the user standard required. The following examples give the various register formats for several video standards.

NTSC ($F_{SC} = 3.5795454 \text{ MHz}$)

PAL B, D, G, H, I ($F_{SC} = 4.43361875 \text{ MHz}$)

Address		Data	Address		Data
00Hex	Mode Register 0	10Hex	00Hex	Mode Register 0	Data 11Hex
01Hex	Mode Register 1	3FHex	00Hex 01Hex	Mode Register 0 Mode Register 1	3FHex
02Hex	Mode Register 2	62Hex	01Hex 02Hex		62Hex
03Hex	Mode Register 3	00Hex	02Hex 03Hex	Mode Register 2	02Hex 00Hex
04Hex	Mode Register 4	00Hex	04Hex	Mode Register 3	00Hex
05Hex	Mode Register 5	00Hex		Mode Register 4	
06Hex	Mode Register 6	00Hex	05Hex	Mode Register 5	00Hex
07Hex	Mode Register 7	00Hex	06Hex	Mode Register 6	00Hex
08Hex	Mode Register 8	04Hex	07Hex	Mode Register 7	00Hex
09Hex	Mode Register 9	00Hex	08Hex	Mode Register 8	04Hex
0AHex	Timing Register 0	08Hex	09Hex	Mode Register 9	00Hex
0BHex	Timing Register 0 Timing Register 1	00Hex	0AHex	Timing Register 0	08Hex
0CHex	Subcarrier Frequency Register 0	16Hex	0BHex	Timing Register 1	00Hex
0DHex	Subcarrier Frequency Register 1	7CHex	0CHex	Subcarrier Frequency Register 0	CBHex
0EHex	Subcarrier Frequency Register 2	F0Hex	0DHex	Subcarrier Frequency Register 1	8AHex
0EHex 0FHex		21Hex	0EHex	Subcarrier Frequency Register 2	09Hex
10Hex	Subcarrier Frequency Register 3	00Hex	0FHex	Subcarrier Frequency Register 3	2AHex
	Subcarrier Phase Register		10Hex	Subcarrier Phase Register	00Hex
11Hex	Closed Captioning Ext Register 0	-00Hex —	⁻ 11Hex	Closed Captioning Ext Register 0	00Hex
12Hex	Closed Captioning Ext Register 1	00Hex	12Hex	Closed Captioning Ext Register 1	00Hex
13Hex	Closed Captioning Register 0	00Hex	13Hex	Closed Captioning Register 0	00Hex
14Hex	Closed Captioning Register 1	00Hex	14Hex	Closed Captioning Register 1	00Hex
15Hex	Pedestal Control Register 0	00Hex	15Hex	Pedestal Control Register 0	00Hex
16Hex	Pedestal Control Register 1	00Hex	16Hex	Pedestal Control Register 1	00Hex
17Hex	Pedestal Control Register 2	00Hex	17Hex	Pedestal Control Register 2	00Hex
18Hex	Pedestal Control Register 3	00Hex	18Hex	Pedestal Control Register 3	00Hex
19Hex	CGMS_WSS Reg 0	00Hex	19Hex	CGMS_WSS Reg 0	00Hex
1AHex	CGMS_WSS Reg 1	00Hex	1AHex	CGMS_WSS Reg 1	00Hex
1BHex	CGMS_WSS Reg 2	00Hex	1BHex	CGMS_WSS Reg 2	00Hex
1CHex	Teletext Control Register	00Hex	1CHex	Teletext Control Register	00Hex
1DHex	Contrast Control Register	00Hex	1DHex	Contrast Control Register	00Hex
1EHex	Color Control Register 1	00Hex	1EHex	Color Control Register 1	00Hex
1FHex	Color Control Register 2	00Hex	1FHex	Color Control Register 2	00Hex
20Hex	Hue Control Register	00Hex	20Hex	Hue Control Register	00Hex
21Hex	Brightness Control Register	00Hex	21Hex	Brightness Control Register	00Hex
22Hex	Sharpness Response Register	00Hex	22Hex	Sharpness Response Register	00Hex
23Hex	DNR 0	44Hex	23Hex	DNR 0	44Hex
24Hex	DNR 1	20Hex	24Hex	DNR 1	20Hex
25Hex	DNR 2	00Hex	25Hex	DNR 2	00Hex
35Hex	Output Clock Register	70Hex	35Hex	Output Clock Register	70Hex
	<u>-</u>		JJIICA	Output Glock Register	IUIICA

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PAL N ($F_{SC} = 4.43361875 \text{ MHz}$)

PAL 60 (F_{SC} = 4.43361875 MHz)

Address		Data	Address		Data
00Hex	Mode Register 0	13Hex	00Hex	Mode Register 0	12Hex
01Hex	Mode Register 1	3FHex	01Hex	Mode Register 1	3FHex
02Hex	Mode Register 2	62Hex	02Hex	Mode Register 2	62Hex
03Hex	Mode Register 3	00Hex	03Hex	Mode Register 3	00Hex
04Hex	Mode Register 4	00Hex	04Hex	Mode Register 4	00Hex
05Hex	Mode Register 5	00Hex	05Hex	Mode Register 5	00Hex
06Hex	Mode Register 6	00Hex	06Hex	Mode Register 6	00Hex
07Hex	Mode Register 7	00Hex	07Hex	Mode Register 7	00Hex
08Hex	Mode Register 8	04Hex	08Hex	Mode Register 8	04Hex
09Hex	Mode Register 9	00Hex	09Hex	Mode Register 9	00Hex
0AHex	Timing Register 0	08Hex	0AHex	Timing Register 0	08Hex
0BHex	Timing Register 1	00Hex	0BHex	Timing Register 1	00Hex
0CHex	Subcarrier Frequency Register 0	CBHex	0CHex	Subcarrier Frequency Register 0	CBHex
0DHex	Subcarrier Frequency Register 1	8AHex	0DHex	Subcarrier Frequency Register 1	8AHex
0EHex	Subcarrier Frequency Register 2	09Hex	0EHex	Subcarrier Frequency Register 2	09Hex
0FHex	Subcarrier Frequency Register 3	2AHex	0FHex	Subcarrier Frequency Register 3	2AHex
10Hex	Subcarrier Phase Register	00Hex	10Hex	Subcarrier Phase Register	00Hex
11Hex	Closed Captioning Ext Register 0	00Hex	11Hex	Closed Captioning Ext Register 0	00Hex
12Hex	Closed Captioning Ext Register 1	00Hex	12Hex	Closed Captioning Ext Register 1	00Hex
13Hex	Closed Captioning Register 0	00Hex	13Hex	Closed Captioning Register 0	00Hex
4Hex	Closed Captioning Register 1	00Hex	14Hex	Closed Captioning Register 1	00Hex
15Hex	Pedestal Control Register 0	00Hex	15Hex	Pedestal Control Register 0	00Hex
16Hex	Pedestal Control Register 1	00Hex	16Hex	Pedestal Control Register 1	00Hex
17Hex	Pedestal Control Register 2	00Hex	17Hex	Pedestal Control Register 2	00Hex
18Hex	Pedestal Control Register 3	00Hex	18Hex	Pedestal Control Register 3	00Hex
19Hex	CGMS_WSS Reg 0	00Hex	19Hex	CGMS_WSS Reg 0	00Hex
1AHex	CGMS_WSS Reg 1	00Hex	1AHex	CGMS_WSS Reg 1	00Hex
1BHex	CGMS_WSS Reg 2	00Hex	1BHex	CGMS_WSS Reg 2	00Hex
1CHex	Teletext Control Register	00Hex	1CHex	Teletext Control Register	00Hex
DHex	Contrast Control Register	00Hex	1DHex	Contrast Control Register	00Hex
1EHex	Color Control Register 1	00Hex	1EHex	Color Control Register 1	00Hex
1FHex	Color Control Register 2	00Hex	1FHex	Color Control Register 2	00Hex
20Hex	Hue Control Register	00Hex	20Hex	Hue Control Register	00Hex
21Hex	Brightness Control Register	00Hex	21Hex	Brightness Control Register	00Hex
22Hex	Sharpness Response Register	00Hex	22Hex	Sharpness Response Register	00Hex
23Hex	DNR 0	44Hex	23Hex	DNR 0	44Hex
24Hex	DNR 1	20Hex	24Hex	DNR 1	20Hex
25Hex	DNR 2	00Hex	25Hex	DNR 2	00Hex
35Hex	Output Clock Register	70Hex	35Hex	Output Clock Register	70Hex

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POWER-ON RESET REGISTER VALUES

POWER-ON RESET REG VALUES (PAL_NTSC = 0, NTSC Selected)

POWER-ON RESET REG VALUES (PAL_NTSC = 1, PAL Selected)

	(TIL_TITOG = 0, TITOG Selected)			(TIL_IVIOG = 1, TILL Science)	
Address 00Hex	Mada Dagistan 0	Data 00Hex	Address 00Hex	Mada Pagistan 0	Data 00Hex
	Mode Register 0			Mode Register 0	
01Hex	Mode Register 1	07Hex	01Hex	Mode Register 1	07Hex
02Hex	Mode Register 2	08Hex	02Hex	Mode Register 2	08Hex
03Hex	Mode Register 3	00Hex	03Hex	Mode Register 3	00Hex
04Hex	Mode Register 4	00Hex	04Hex	Mode Register 4	00Hex
05Hex	Mode Register 5	00Hex	05Hex	Mode Register 5	00Hex
06Hex	Mode Register 6	00Hex	06Hex	Mode Register 6	00Hex
07Hex	Mode Register 7	00Hex	07Hex	Mode Register 7	00Hex
08Hex	Mode Register 8	00Hex	08Hex 09Hex	Mode Register 8	00Hex
09Hex	Mode Register 9	00Hex		Mode Register 9	00Hex
0AHex	Timing Register 0	08Hex	0AHex	Timing Register 0	08Hex
0BHex	Timing Register 1	00Hex	0BHex	Timing Register 1	00Hex
0CHex	Subcarrier Frequency Register 0	16Hex	0CHex	Subcarrier Frequency Register 0	CBHex
0DHex	Subcarrier Frequency Register 1	7CHex	0DHex	Subcarrier Frequency Register 1	8AHex
0EHex	Subcarrier Frequency Register 2	F0Hex	0EHex	Subcarrier Frequency Register 2	09Hex
0FHex	Subcarrier Frequency Register 3	21Hex	0FHex	Subcarrier Frequency Register 3	2AHex
10Hex	Subcarrier Phase Register	00Hex	10Hex	Subcarrier Phase Register	00Hex
11Hex	Closed Captioning Ext Register 0	00Hex	11Hex	Closed Captioning Ext Register 0	00Hex
12Hex	Closed Captioning Ext Register 1	00Hex	12Hex	Closed Captioning Ext Register 1	00Hex
13Hex	Closed Captioning Register 0	00Hex	13Hex	Closed Captioning Register 0	00Hex
14Hex	Closed Captioning Register 1	00Hex	14Hex	Closed Captioning Register 1	00Hex
15Hex	Pedestal Control Register 0	00Hex	15Hex	Pedestal Control Register 0	00Hex
16Hex	Pedestal Control Register 1	00Hex	16Hex	Pedestal Control Register 1	00Hex
17Hex	Pedestal Control Register 2	00Hex	17Hex	Pedestal Control Register 2	00Hex
18Hex	Pedestal Control Register 3	00Hex	18Hex	Pedestal Control Register 3	00Hex
19Hex	CGMS_WSS Reg 0	00Hex	19Hex	CGMS_WSS Reg 0	00Hex
1AHex	CGMS_WSS Reg 1	00Hex	1AHex	CGMS_WSS Reg 1	00Hex
1BHex	CGMS_WSS Reg 2	00Hex	1BHex	CGMS_WSS Reg 2	00Hex
1CHex	Teletext Control Register	00Hex	1CHex	Teletext Control Register	00Hex
1DHex	Contrast Control Register	00Hex	1DHex	Contrast Control Register	00Hex
1EHex	Color Control Register 1	00Hex	1EHex	Color Control Register 1	00Hex
1FHex	Color Control Register 2	00Hex	1FHex	Color Control Register 2	00Hex
20Hex	Hue Control Register	00Hex	20Hex	Hue Control Register	00Hex
21Hex	Brightness Control Register	00Hex	21Hex	Brightness Control Register	00Hex
22Hex	Sharpness Response Register	00Hex	22Hex	Sharpness Response Register	00Hex
23Hex	DNR 0	00Hex	23Hex	DNR 0	00Hex
24Hex	DNR 1	00Hex	24Hex	DNR 1	00Hex
25Hex	DNR 2	00Hex	25Hex	DNR 2	00Hex
26Hex	Gamma 0	xxHex	26Hex	Gamma 0	xxHex
27Hex	Gamma 1	xxHex	27Hex	Gamma 1	xxHex
28Hex	Gamma 2	xxHex	28Hex	Gamma 2	xxHex
29Hex	Gamma 3	xxHex	29Hex	Gamma 3	xxHex
2AHex	Gamma 4	xxHex	2AHex	Gamma 4	xxHex
2BHex	Gamma 5	xxHex	2BHex	Gamma 5	xxHex
2CHex	Gamma 6	xxHex	2CHex	Gamma 6	xxHex
2DHex	Gamma 7	xxHex	2DHex	Gamma 7	xxHex
2EHex	Gamma 8	xxHex	2EHex	Gamma 8	xxHex
2FHex	Gamma 9	xxHex	2FHex	Gamma 9	xxHex
30Hex	Gamma 10	xxHex	30Hex	Gamma 10	xxHex
31Hex	Gamma 11	xxHex	31Hex	Gamma 11	xxHex
32Hex	Gamma 12	xxHex	32Hex	Gamma 12	xxHex
33Hex	Gamma 13	xxHex	33Hex	Gamma 13	xxHex
34Hex	Brightness Detect Register	xxHex	34Hex	Brightness Detect Register	xxHex
35Hex	Output Clock Register	72Hex	35Hex	Output Clock Register	72Hex

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APPENDIX 9 NTSC WAVEFORMS (WITH PEDESTAL)

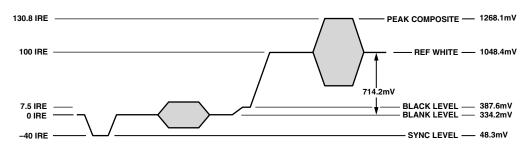


Figure 107. NTSC Composite Video Levels

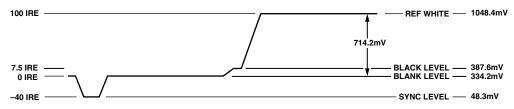


Figure 108. NTSC Luma Video Levels

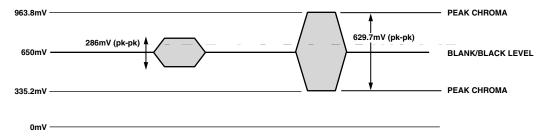


Figure 109. NTSC Chroma Video Levels

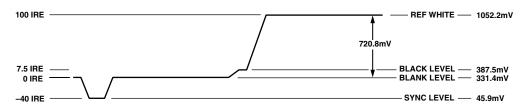


Figure 110. NTSC RGB Video Levels

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NTSC WAVEFORMS (WITHOUT PEDESTAL)

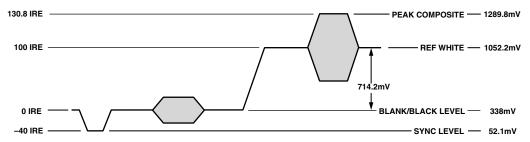


Figure 111. NTSC Composite Video Levels

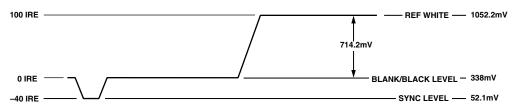


Figure 112. NTSC Luma Video Levels

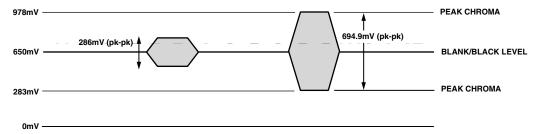


Figure 113. NTSC Chroma Video Levels

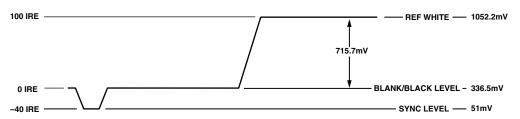


Figure 114. NTSC RGB Video Levels

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PAL WAVEFORMS

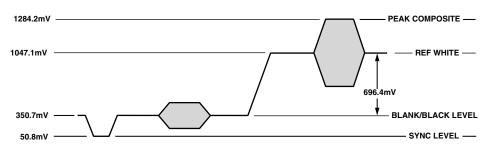


Figure 115. PAL Composite Video Levels

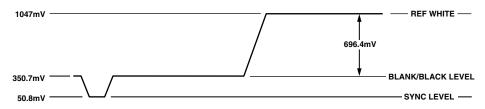


Figure 116. PAL Luma Video Levels

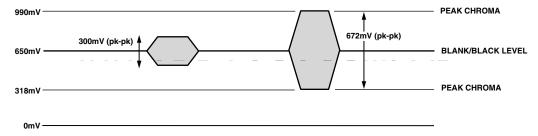


Figure 117. PAL Chroma Video Levels

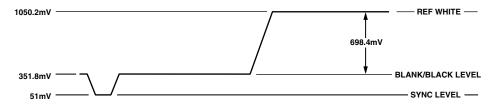


Figure 118. PAL RGB Video Levels

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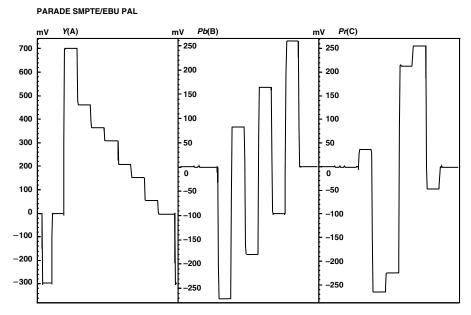


Figure 119. PAL YUV Parade Plot

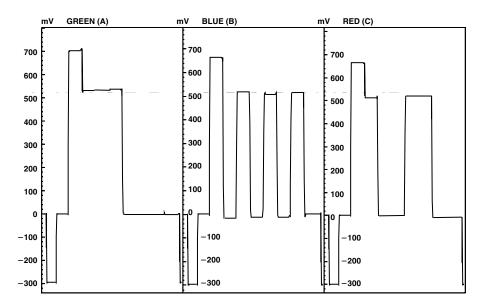


Figure 120. PAL RGB Waveforms

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UV WAVEFORMS

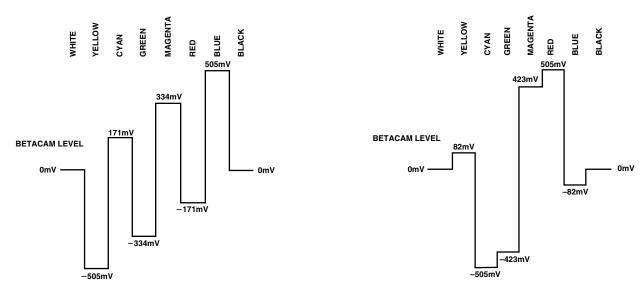


Figure 121. NTSC 100% Color Bars No Pedestal U Levels

Figure 124. NTSC 100% Color Bars No Pedestal V Levels

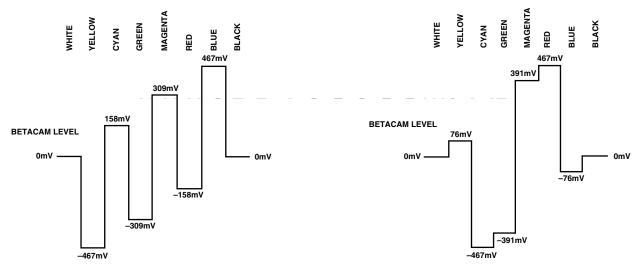


Figure 122. NTSC 100% Color Bars with Pedestal U Levels

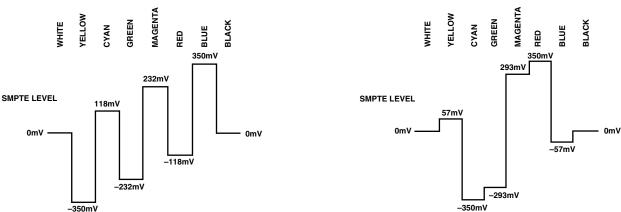


Figure 123. PAL 100% Color Bars U Levels

Figure 126. PAL 100% Color Bars V Levels

Figure 125. NTSC 100% Color Bars with Pedestal V

OUTPUT WAVEFORMS

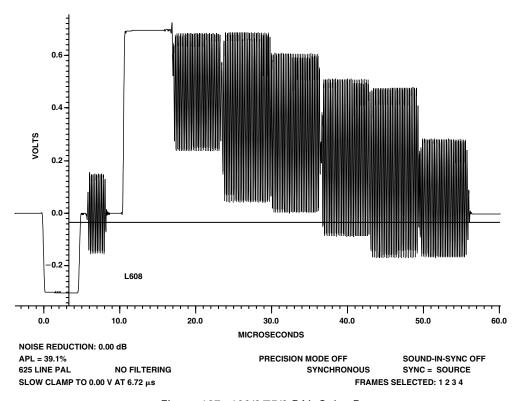


Figure 127. 100/0/75/0 PAL Color Bars

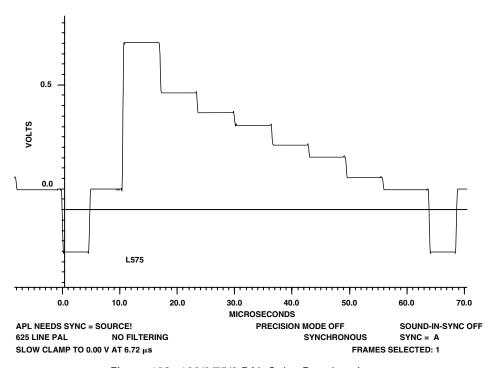


Figure 128. 100/0/75/0 PAL Color Bars Luminance

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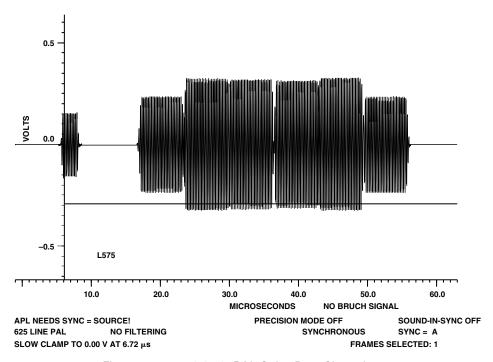


Figure 129. 100/0/75/0 PAL Color Bars Chrominance

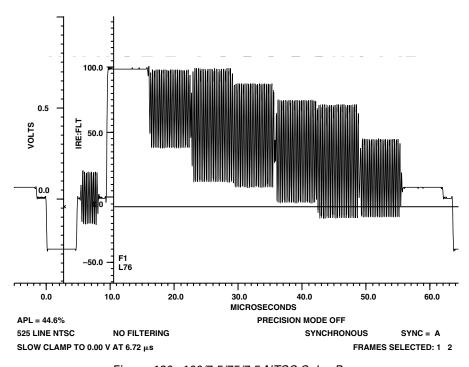


Figure 130. 100/7.5/75/7.5 NTSC Color Bars

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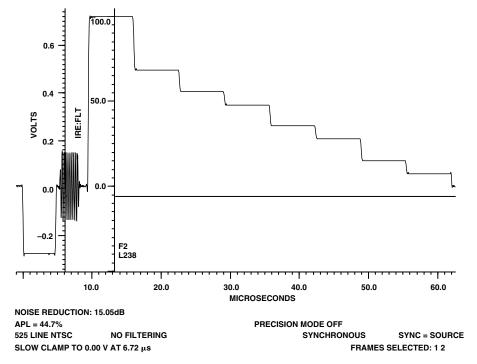


Figure 131. 100/7.5/75/7.5 NTSC Color Bars Luminance

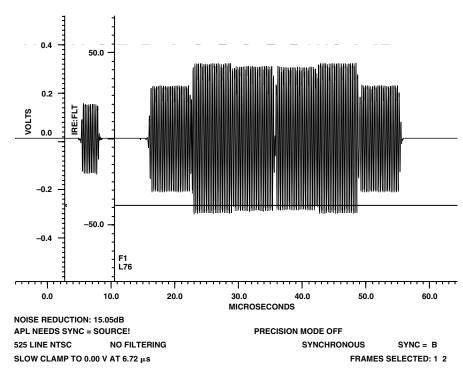


Figure 132. 100/7.5/75/7.5 NTSC Color Bars Chrominance

REV. A -63-

VIDEO MEASUREMENT PLOTS

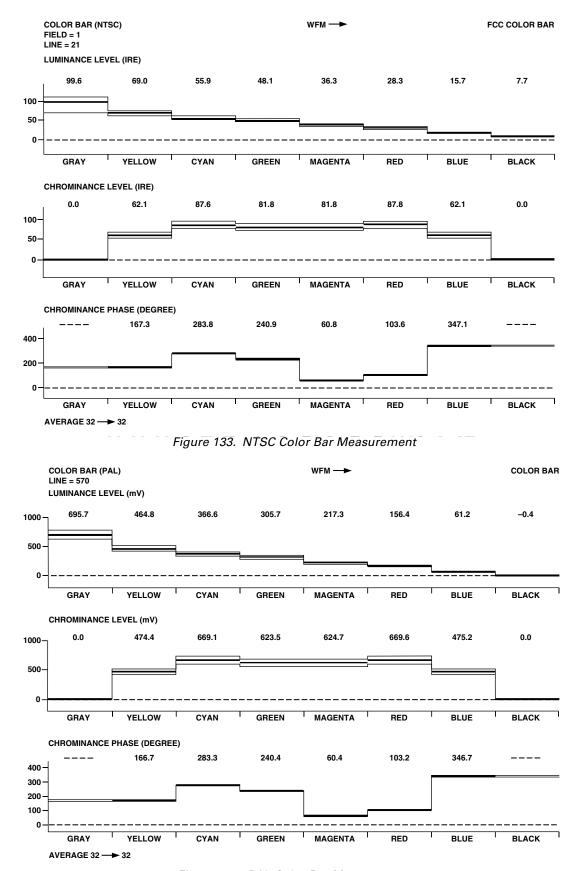


Figure 134. PAL Color Bar Measurement

0.32

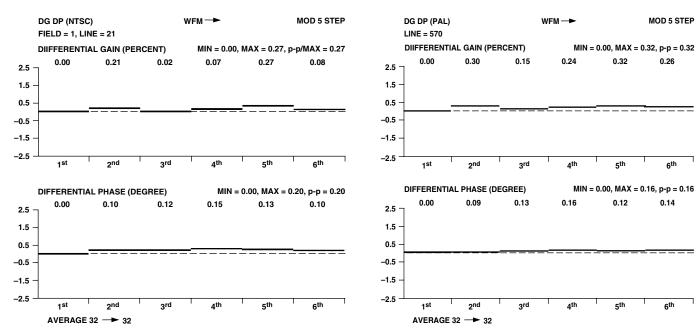
5th

0.12

MOD 5 STEP

0.26

6th







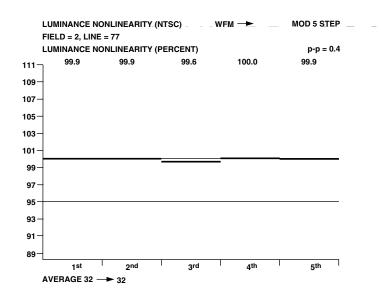


Figure 136. NTSC Luminance Nonlinearity

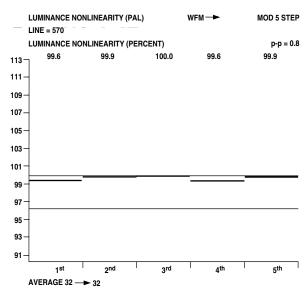


Figure 138. PAL Luminance Nonlinearity

REV. A -65-

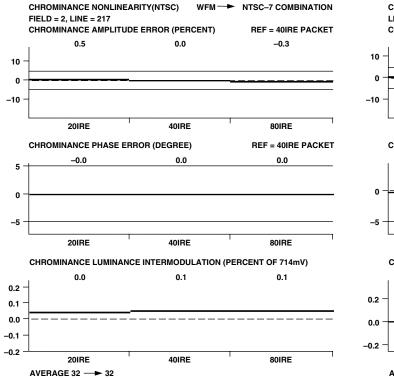


Figure 139. NTSC Chrominance Nonlinearity

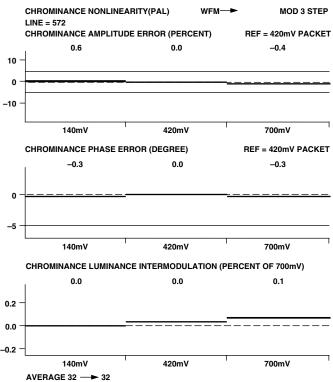
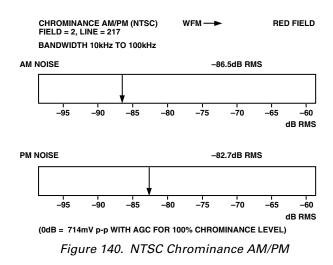


Figure 141. PAL Chrominance Nonlinearity



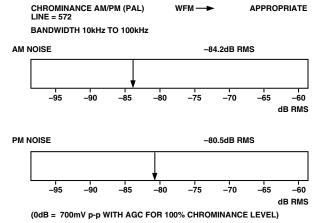


Figure 142. PAL Chrominance AM/PM

REV. A

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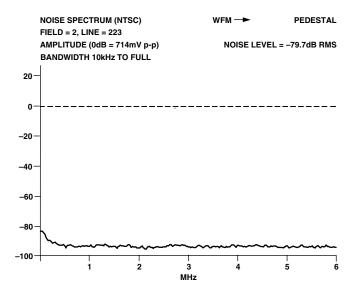


Figure 143. NTSC Noise Spectrum: Pedestal

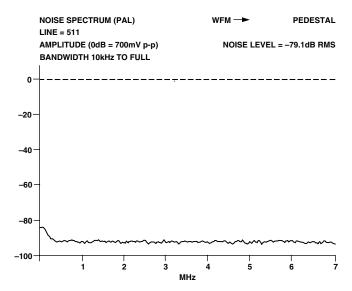


Figure 145. PAL Noise Spectrum: Pedestal

WFM →

RAMP

NOISE SPECTRUM (PAL)

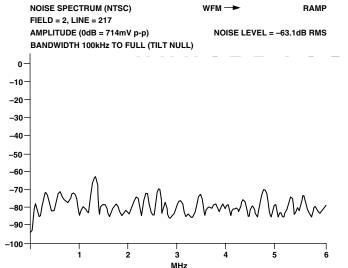


Figure 144. NTSC Noise Spectrum: Ramp

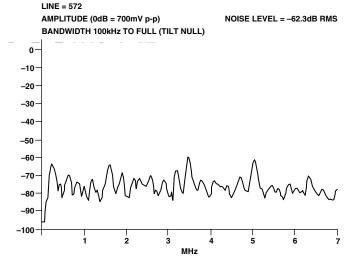
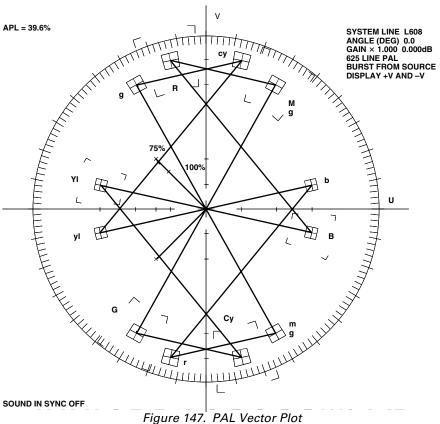


Figure 146. PAL Noise Spectrum: Ramp

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APPENDIX 10 VECTOR PLOTS



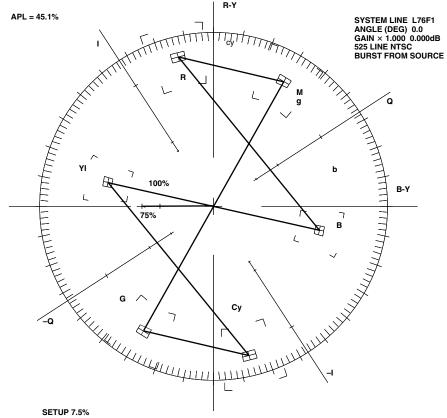
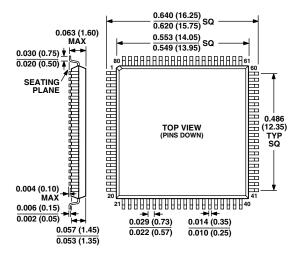


Figure 148. NTSC Vector Plot

OUTLINE DIMENSIONS

Dimensions shown in inches and (mm).

80-Lead LQFP (ST-80)



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